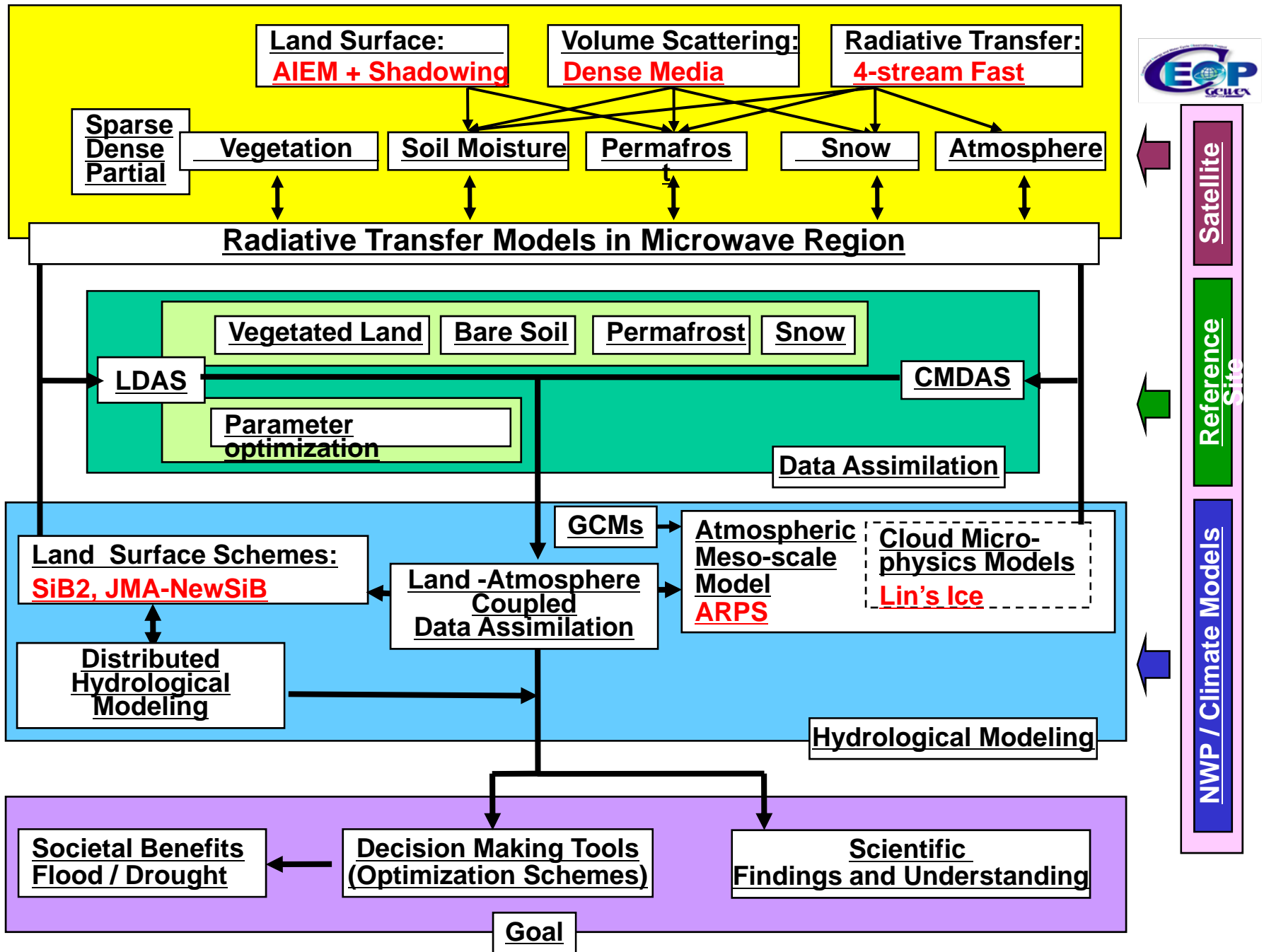


Development of LDAS Coupled with Atmospheric Models by CEOP

Souhail Boussetta (now at ECMWF) and Toshio Koike (U. Tokyo)

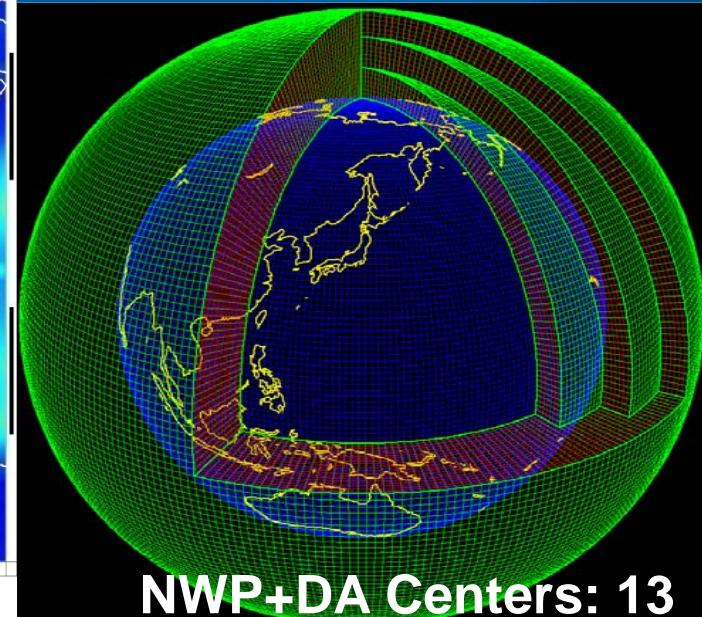
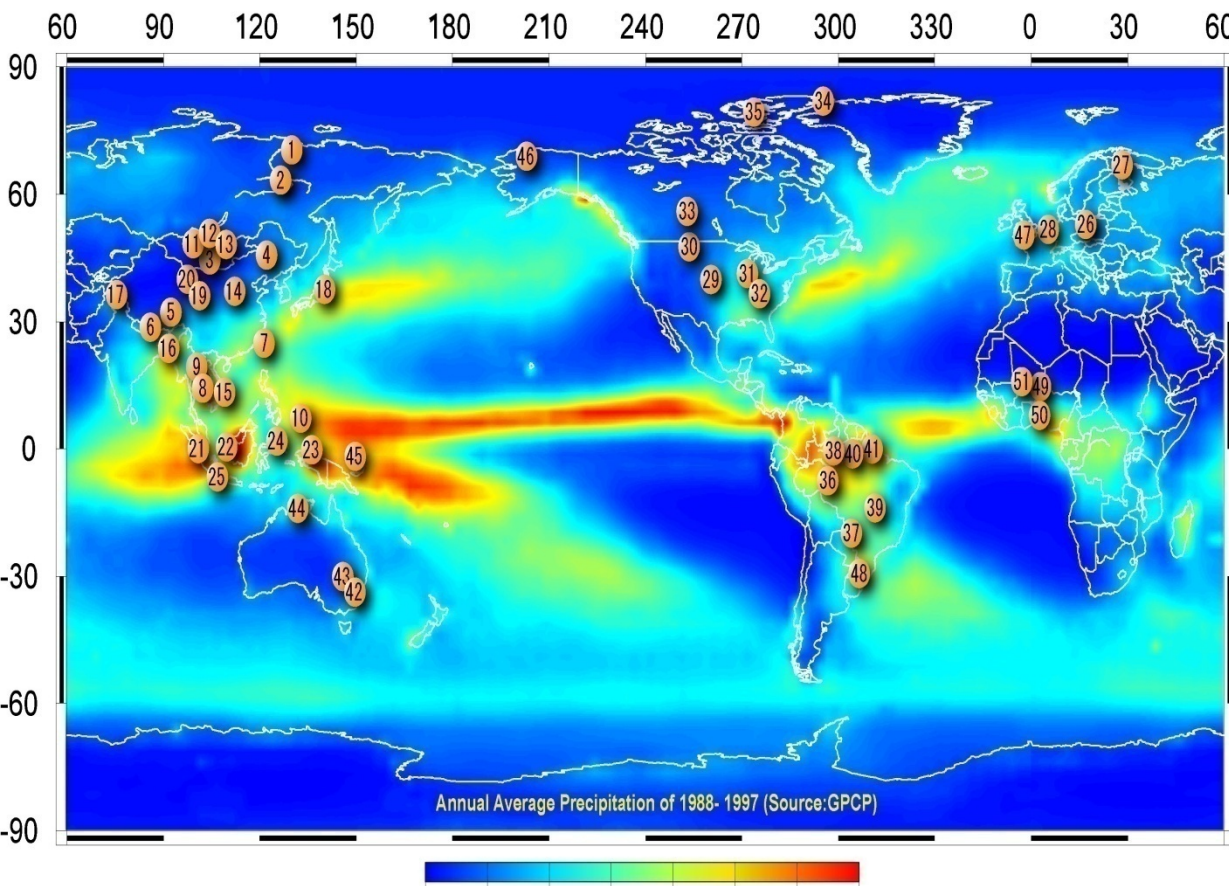
Acknowledgement to

Tobias Graf , Xin Li, Kun Yang, Lu Hui,
Mahadevan Pathmathevan, David Kuria,
Tetsu Ohta, Dawen Yang, Cyrus raza Mirza,
Hiroyuki Tsutsui, Oliver Saveedra, Wang Lei
Katsunori Tamagawa, Hideyuki Fuji



Coordinated Energy and Water Cycle Observations Project

Convergence of Observations A Prototype of the Global Water Cycle Observation System of Systems



Satellite Observation

Brightness Temperature, TB
10GHz (V, H) and 36GHz (V)

Latitude, Longitude, Observation date

Quality
Check
yes

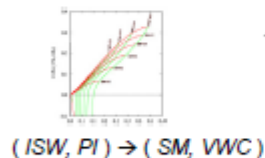
Index of Soil Wetness(Koike,1996)

$$ISW = \frac{T_{B36H} - T_{B10H}}{\frac{1}{2}(T_{B36H} + T_{B10H})}$$

Polarization Index(Shimonetta,1998)

$$PI = \frac{T_{B10V} - T_{B10H}}{\frac{1}{2}(T_{B10V} + T_{B10H})}$$

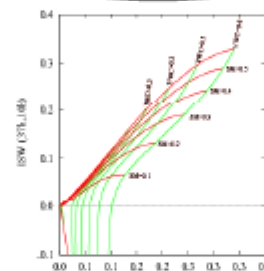
Selected LUT



Soil Moisture
Vegetation Water Content

Main Routine

Look-up Table Dataset,
LUT (f_c)



LUT(f_c)

LUT(f_c)

$f_c = 1 \dots 100\%$

$f_c (lat, lon, date)$

Global dataset of
fractional vegetation cover,
 $f_c (lat, lon, date)$

Data source:

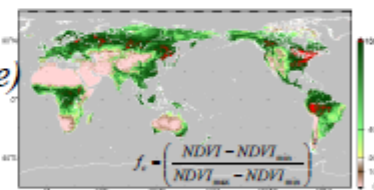
Terra/Aqua Modis 16days, 1km ISIN

Period: Jun 2002 – May 2008

Sampling point: 0.05x0.05 grid

Resolution: approx. 33x33 km

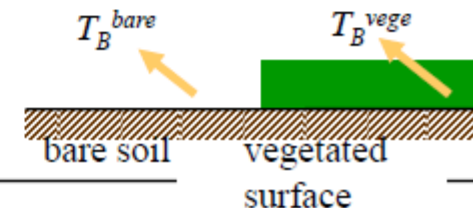
f_c -model: Carlson and replay, 1997

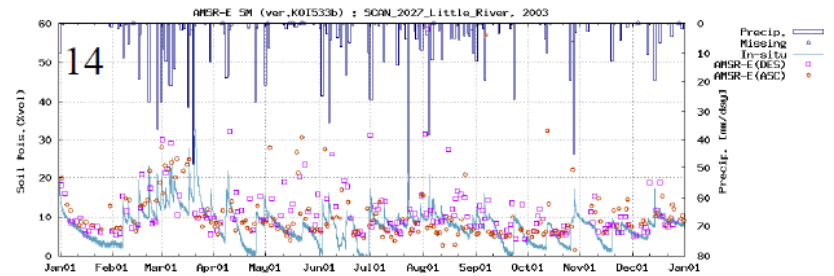
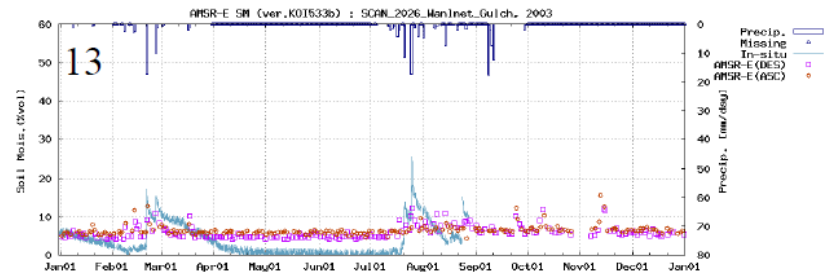
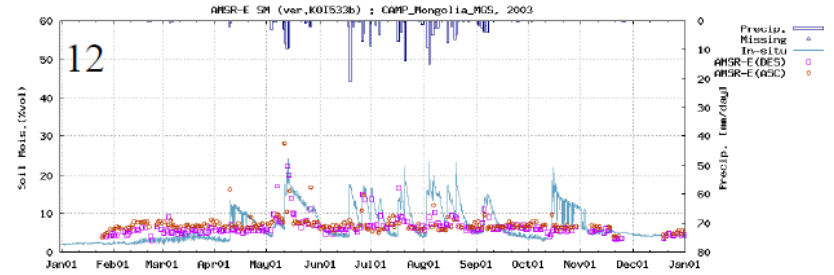
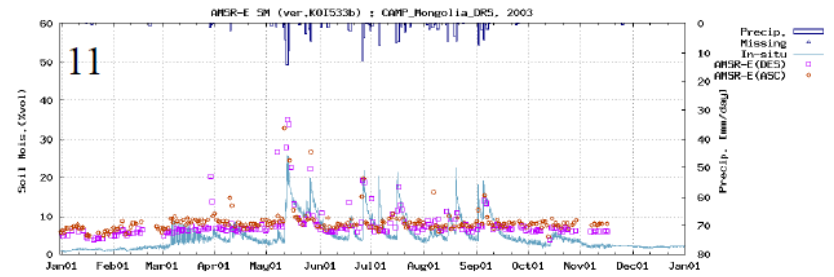
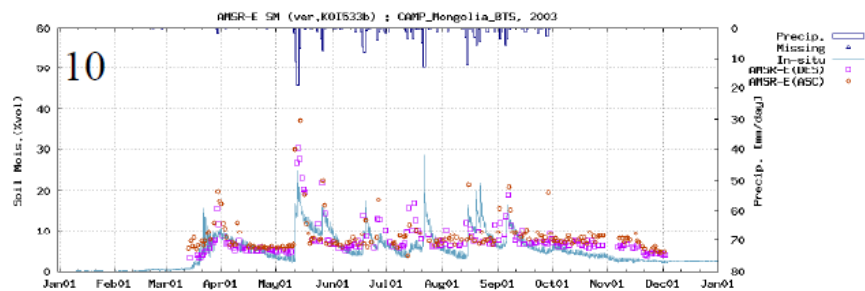
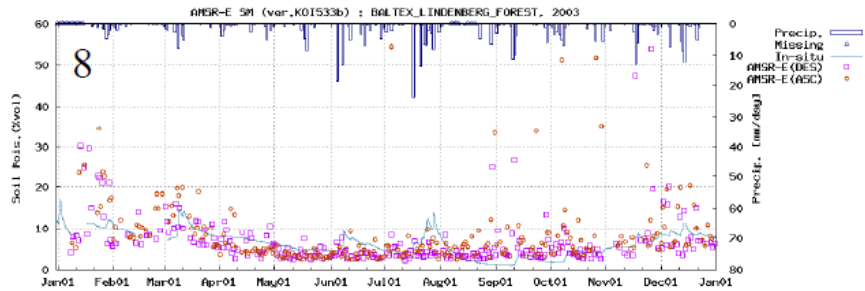
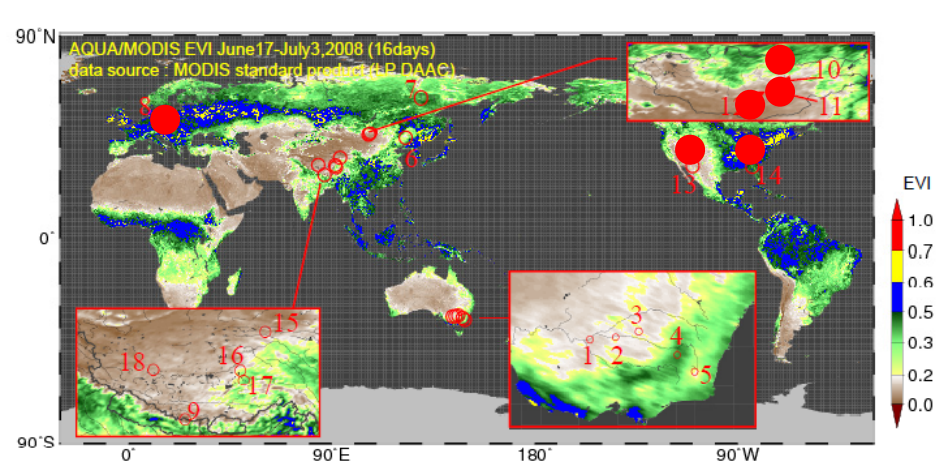


Ancillary Data Base

Radiative Transfer Model

$$T_B = (1-f_c)T_B^{bare} + f_c T_B^{vege}$$



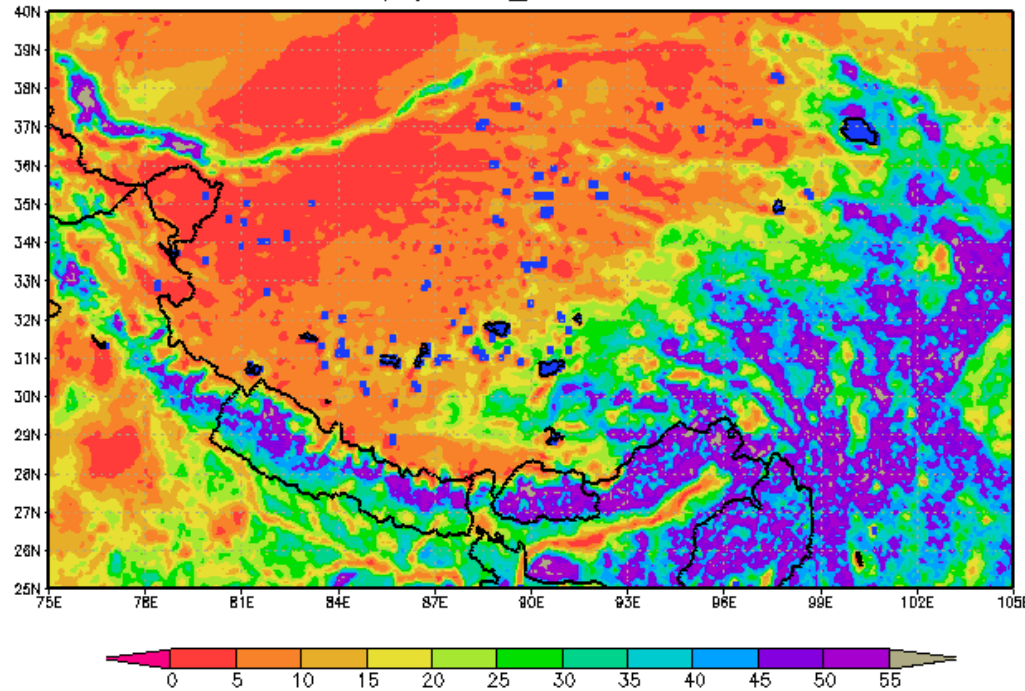


(Lu et al. 2007 and
Tamagawa et al. 2008)

Seasonal Variation of the Soil Moisture

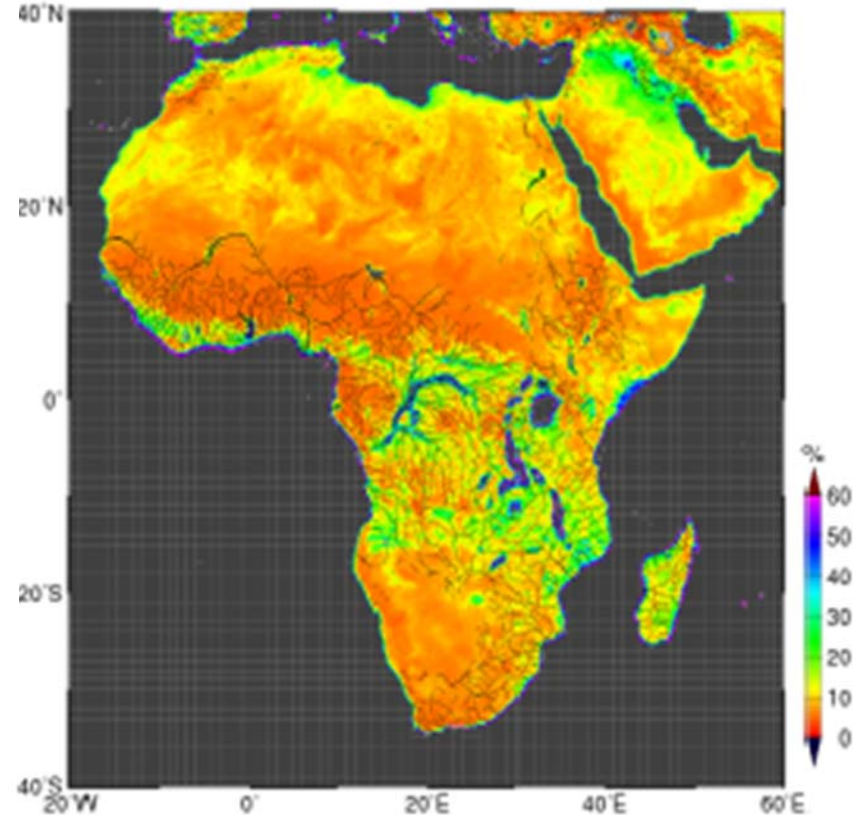
Tibetan Plateau Africa

6G Mv(%) tibet_D 2003SEP-last



SM(AMSR-E)

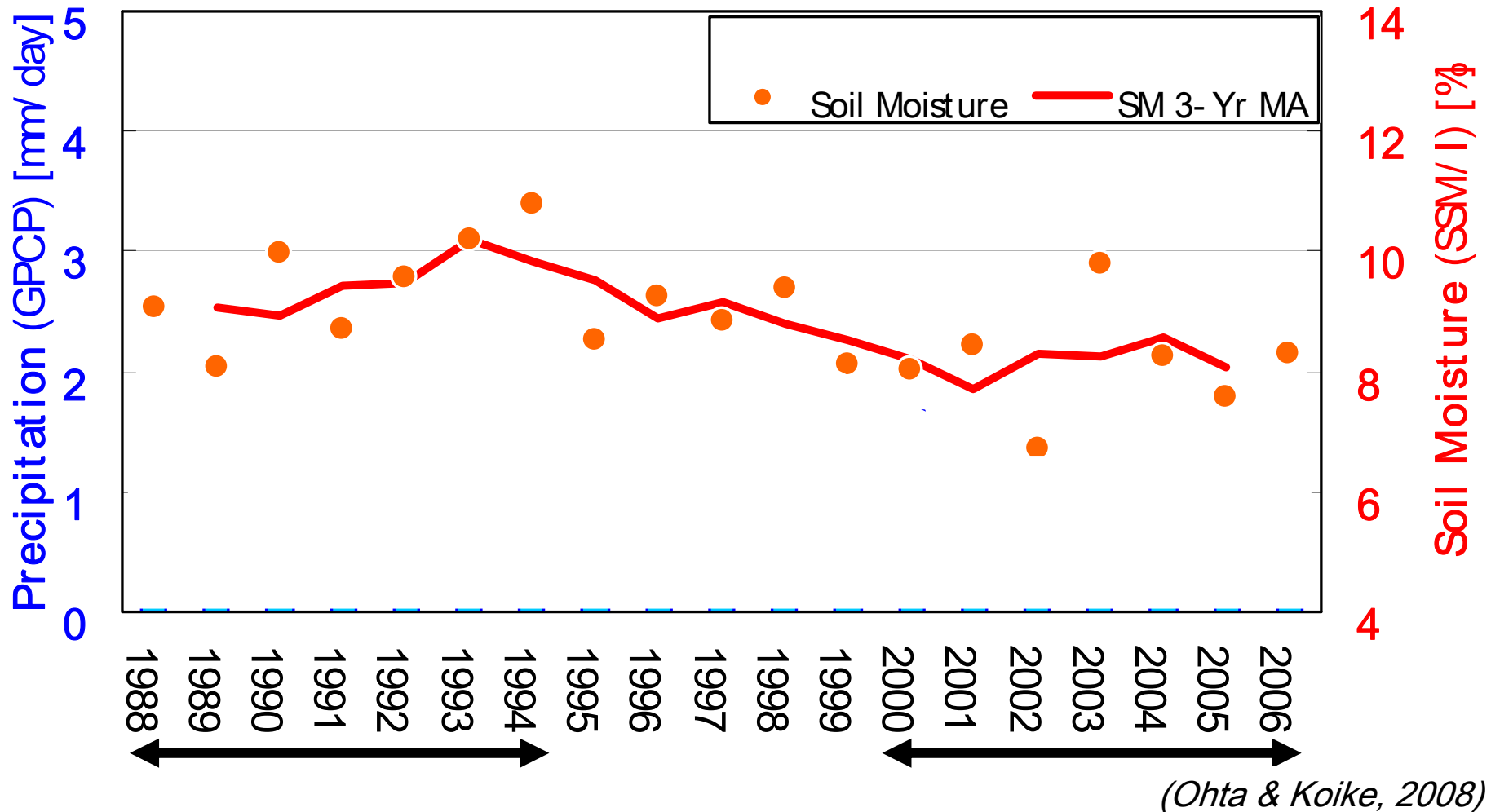
AQUA/AMSR-E SM Dec., 2003 DES (Monthly)



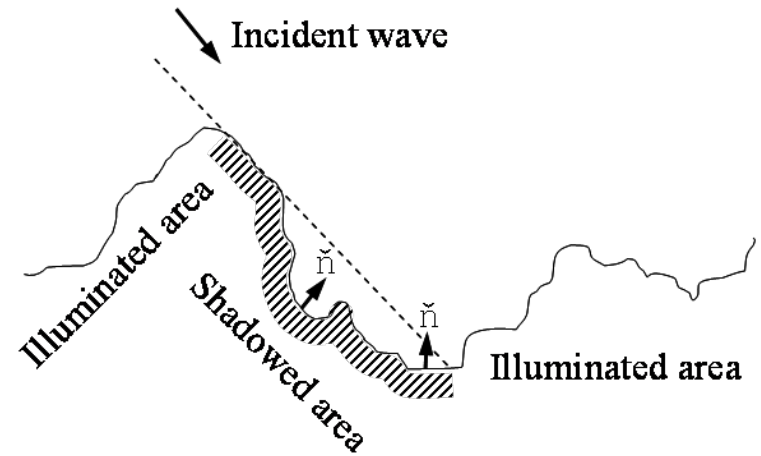
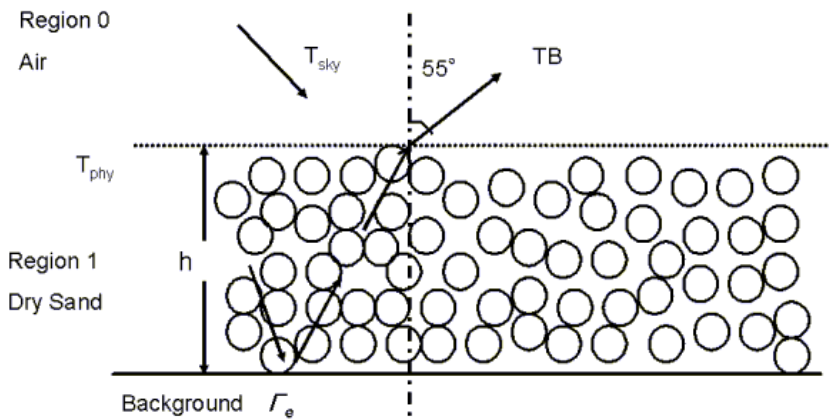
CEOP Reference Site in Mongolia

Long Term Application of 2.5 x 2.5 Degrees Area including Validation Sites (JJA Average)

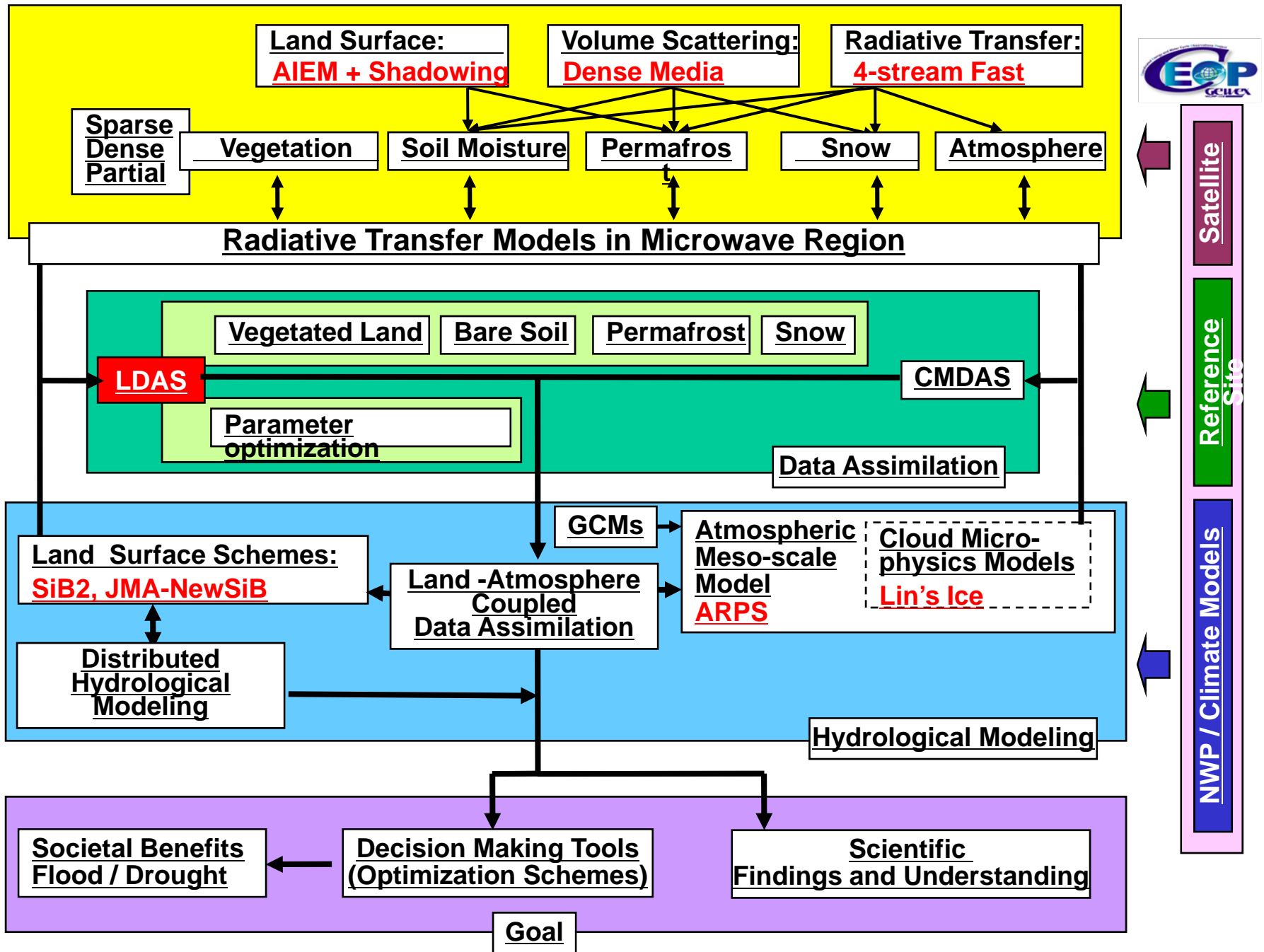
(Satellite data application to climate change)

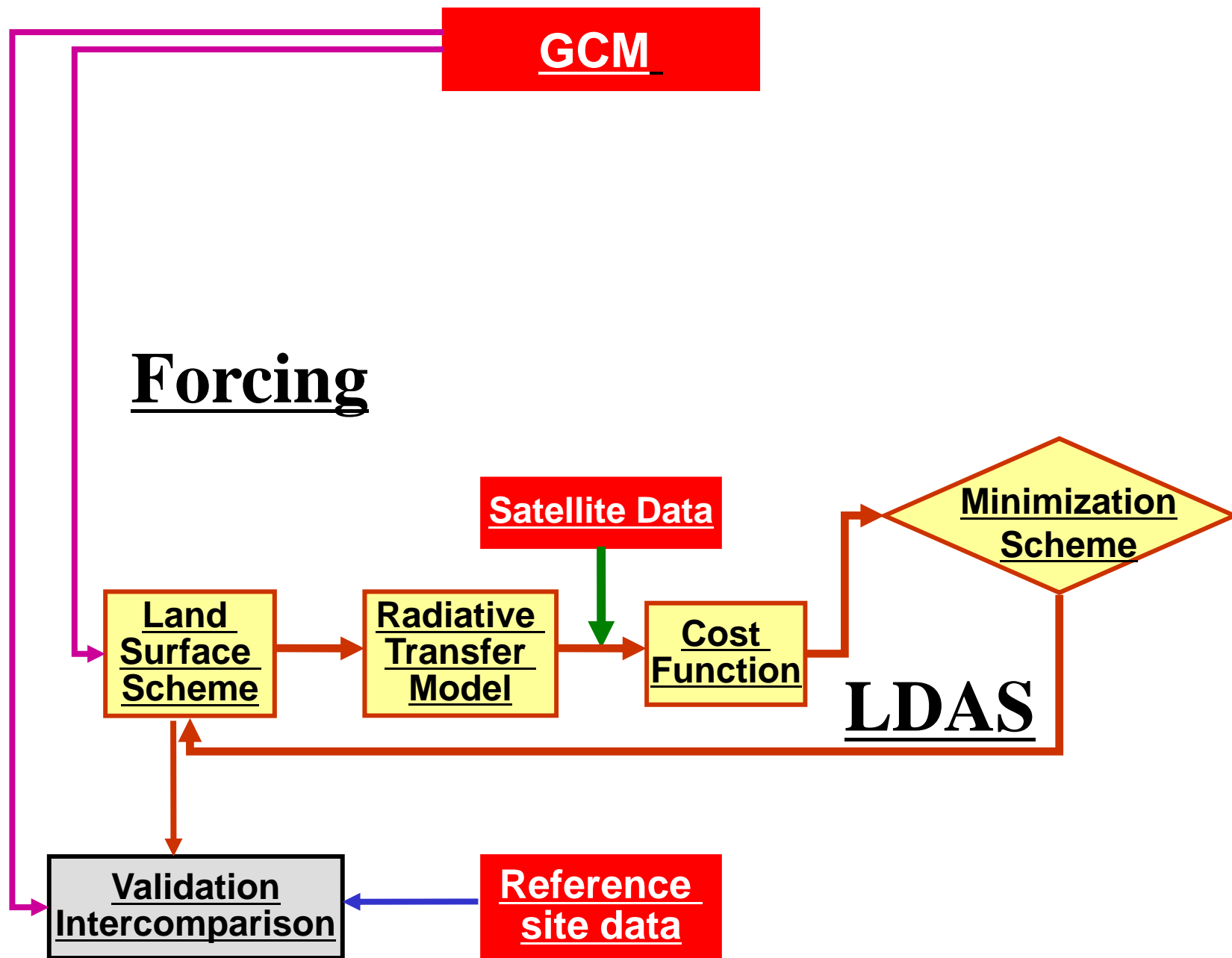


GBHM Experiments



(Kurita et al. 2007)



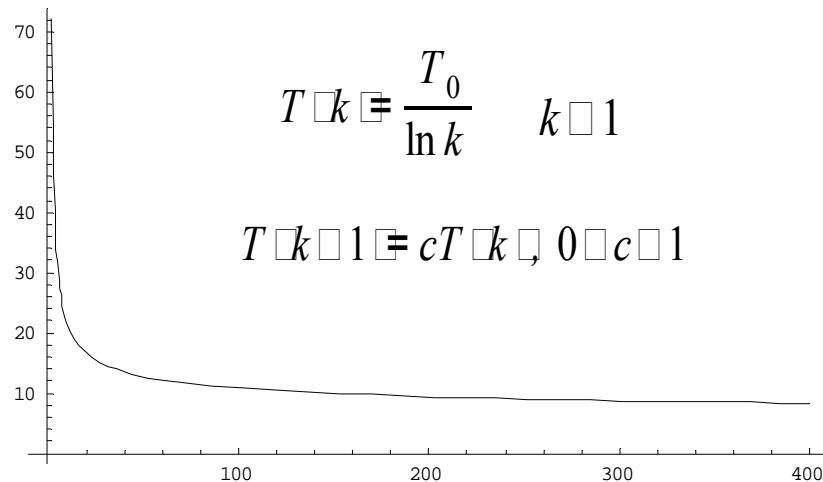


SA method (Boltzmann Annealing)

- Boltzmann distribution

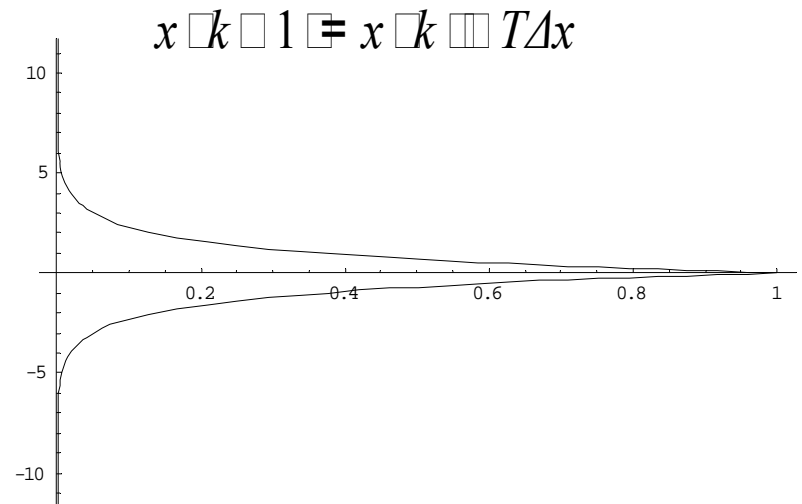
$$g(x) = \frac{1}{\sqrt{2\pi T}} \exp[-x^2 / (2T)]$$

- Annealing schedule

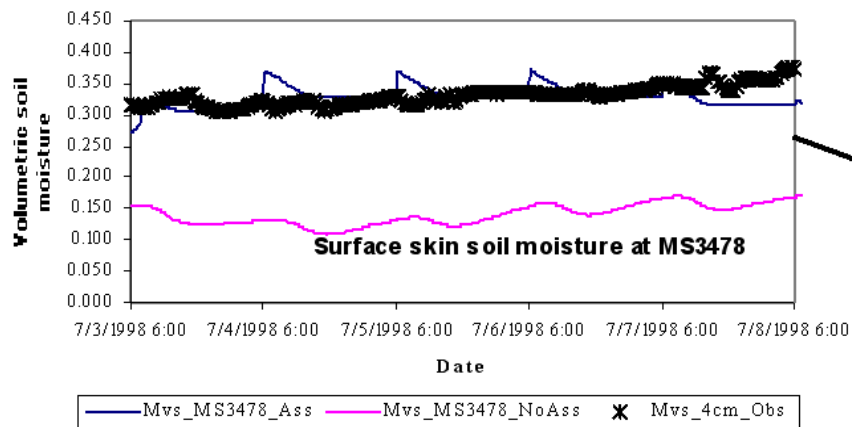


- Generating function of random change

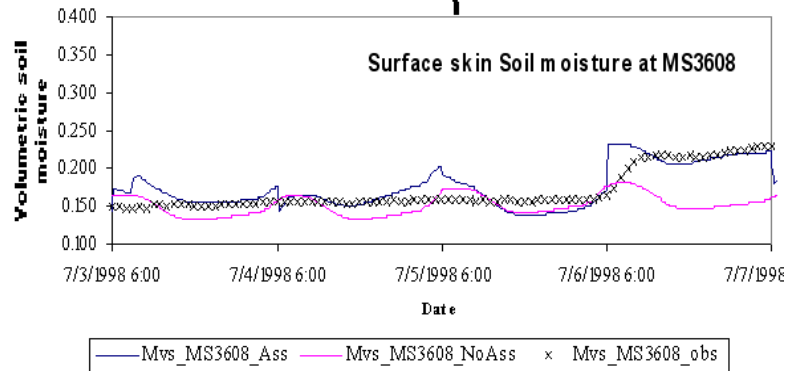
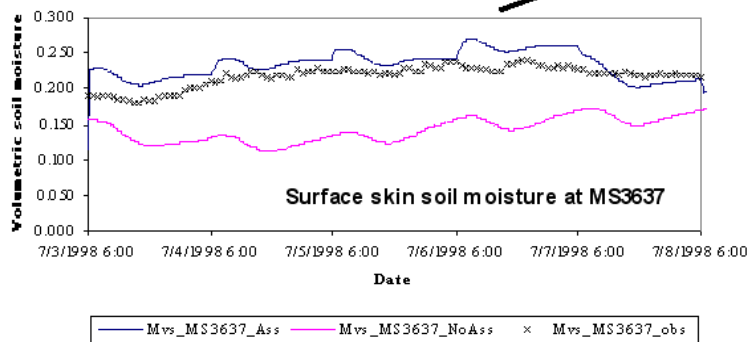
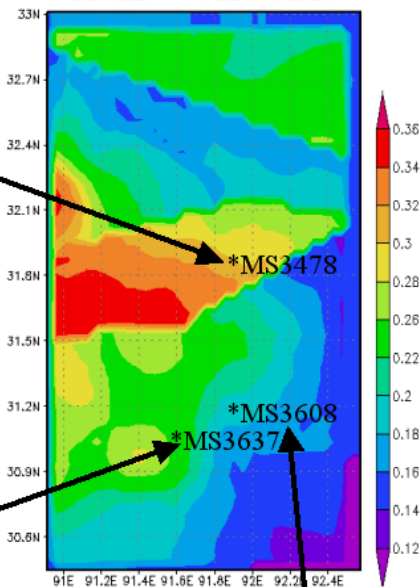
$$\Delta x = \text{sign}\{U[-1,1]\} \times \ln U[0,1], \quad \Delta x \in [-\infty, \infty]$$



soil moisture

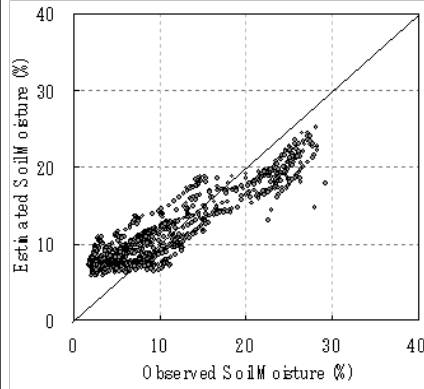
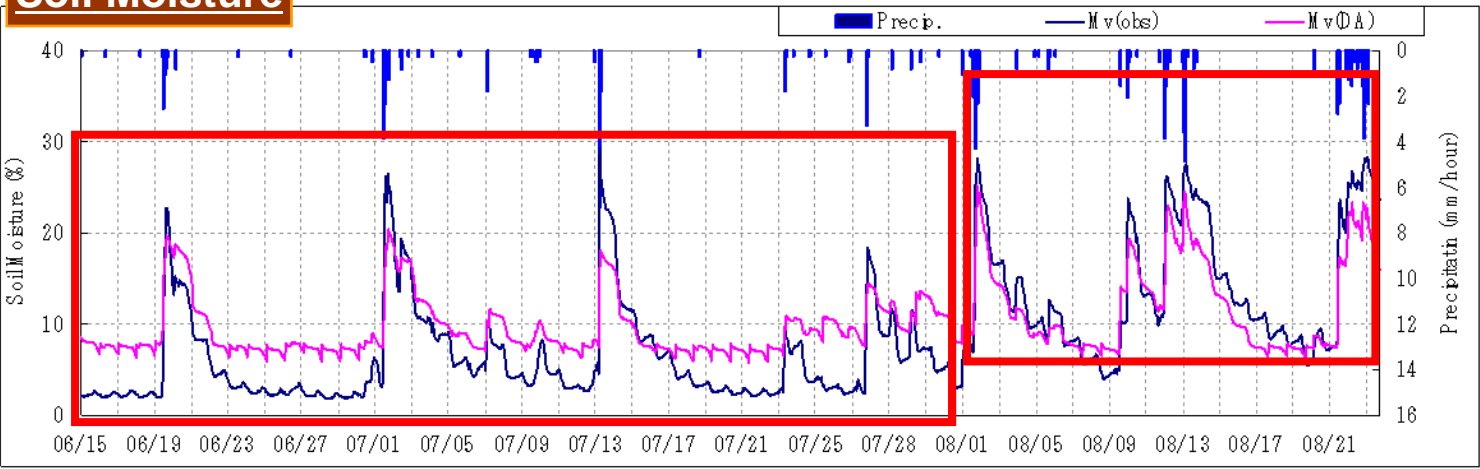


Average Surface soil Moisture [m³/m³] at 12LT - Assimilation

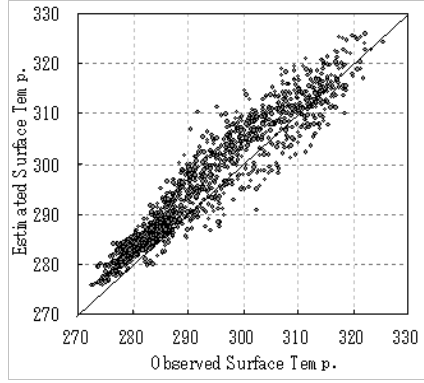
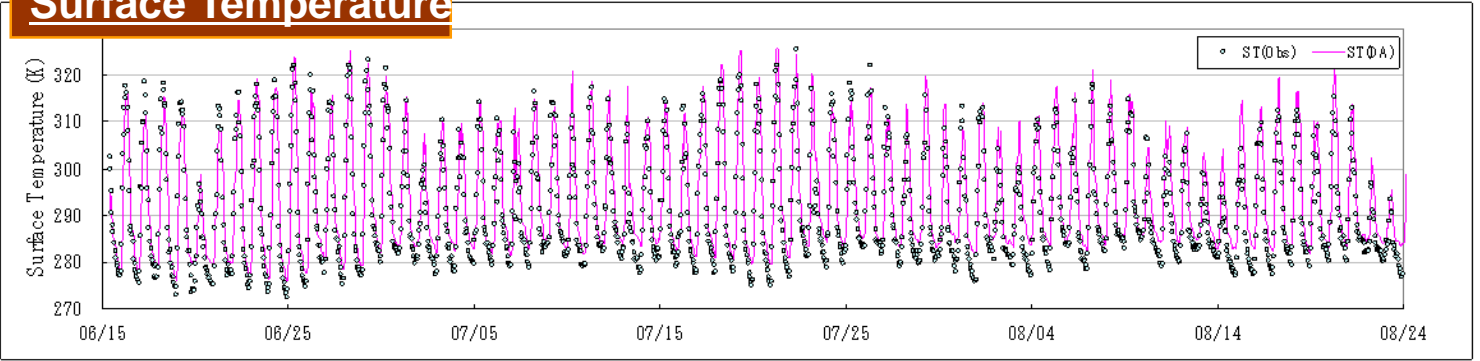


(Boussetta et al. 2005)

Soil Moisture



Surface Temperature



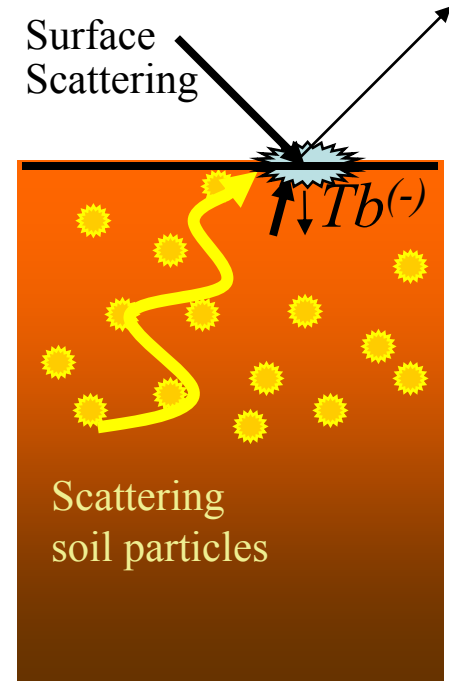
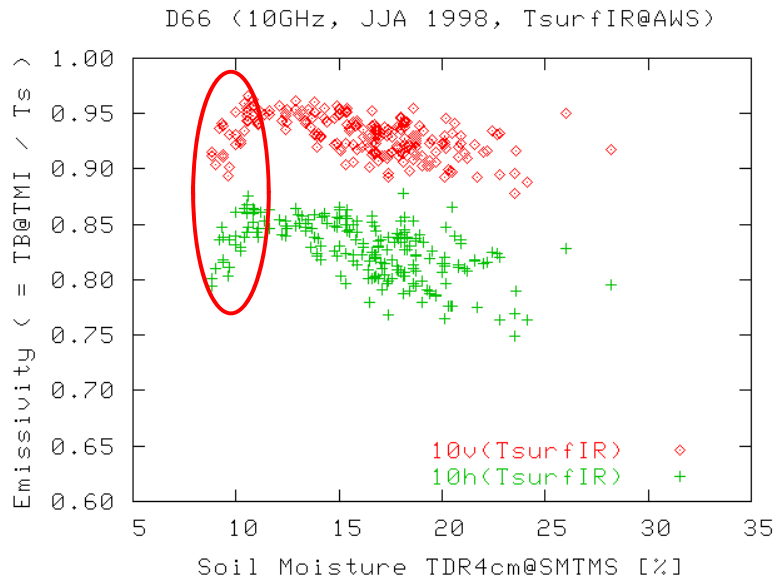
LDASUT

Good agreement under wet condition

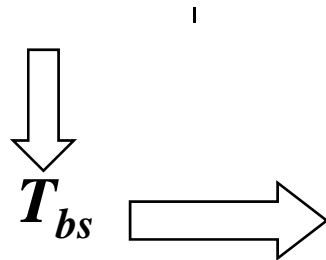
Gap under dry condition

(Yang et al. 2007)

Radiative Transfer Model for dry soil

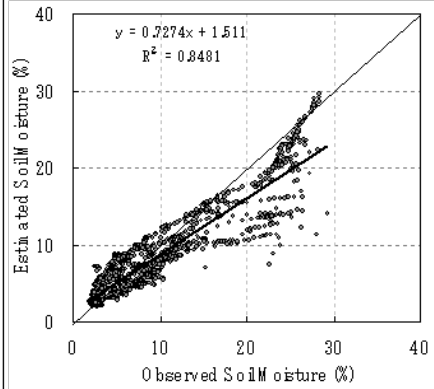
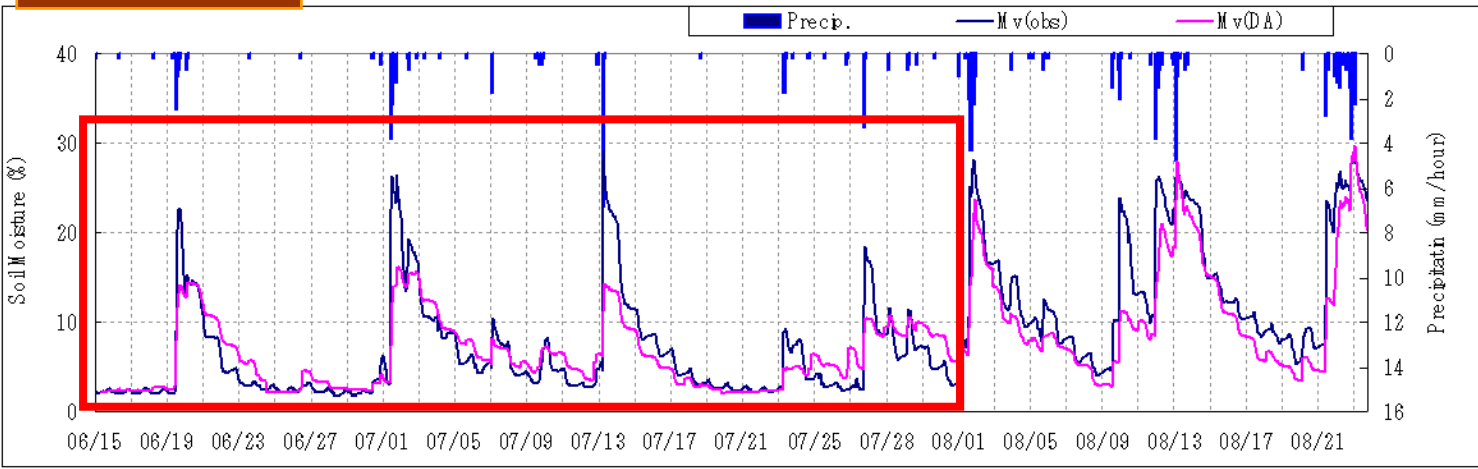


radiative transfer model which can represent the *scattering effect of soil particles*

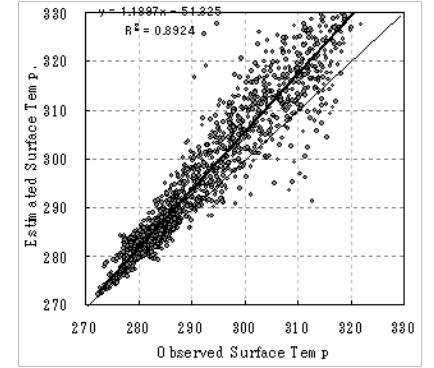
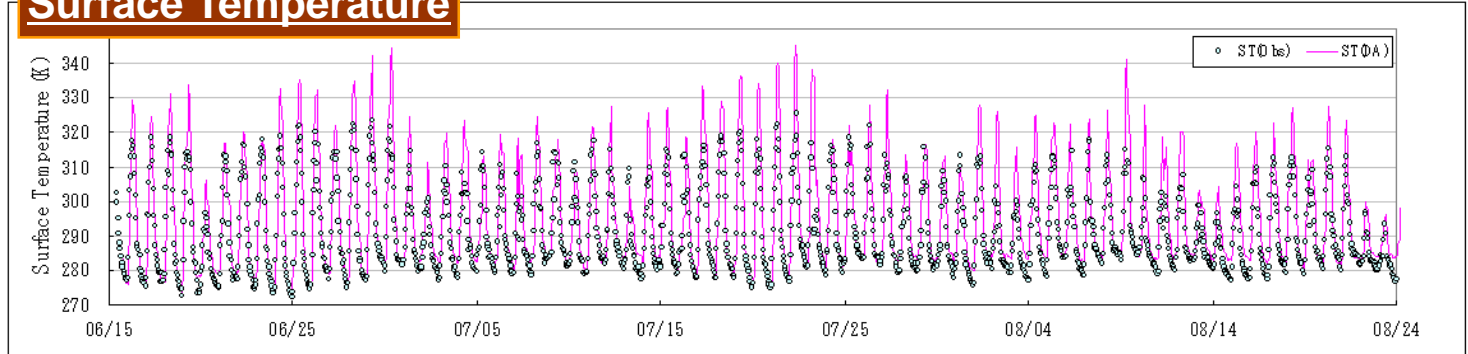


$$T_b = (1 - f)(1 - \Gamma)T_{bs} + f((1 - \Gamma)T_{bs}e^{-\tau_c} + (1 - w_c)(1 - e^{-\tau_c})T_c + (1 - w_c)(1 - e^{-\tau_c})T_c\Gamma e^{-\tau_c})$$

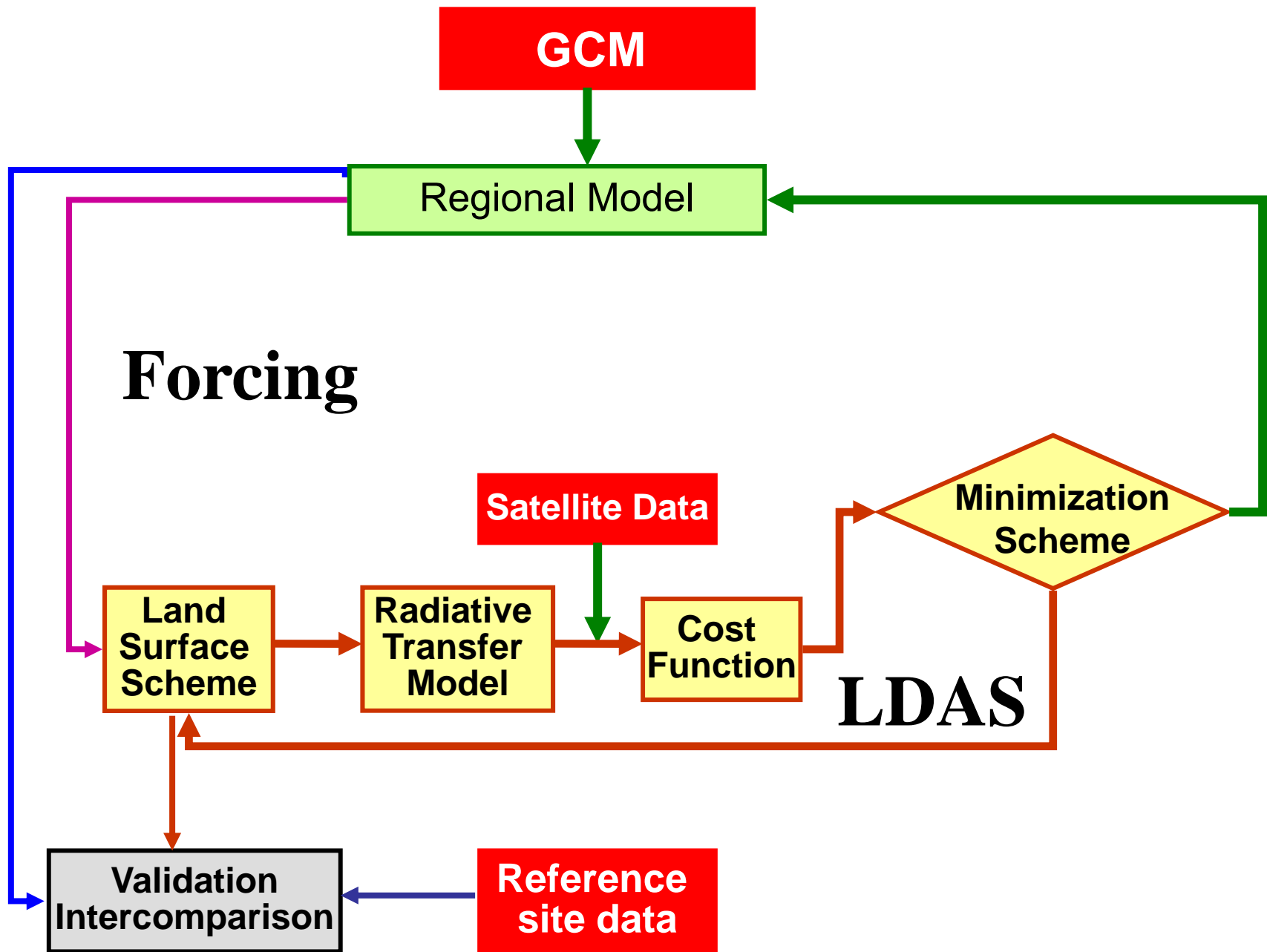
Soil moisture



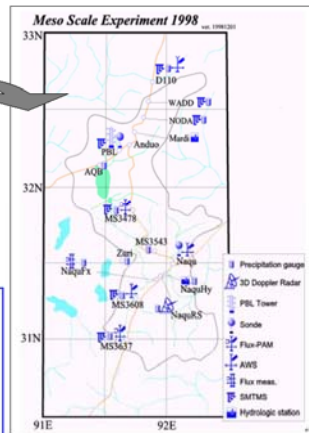
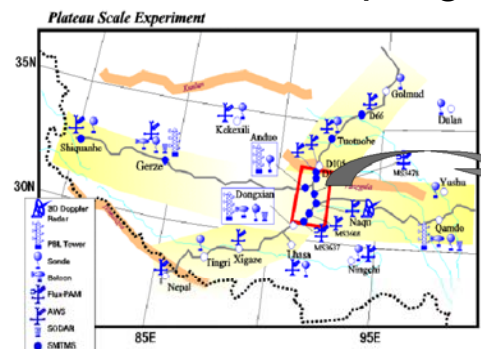
Surface Temperature



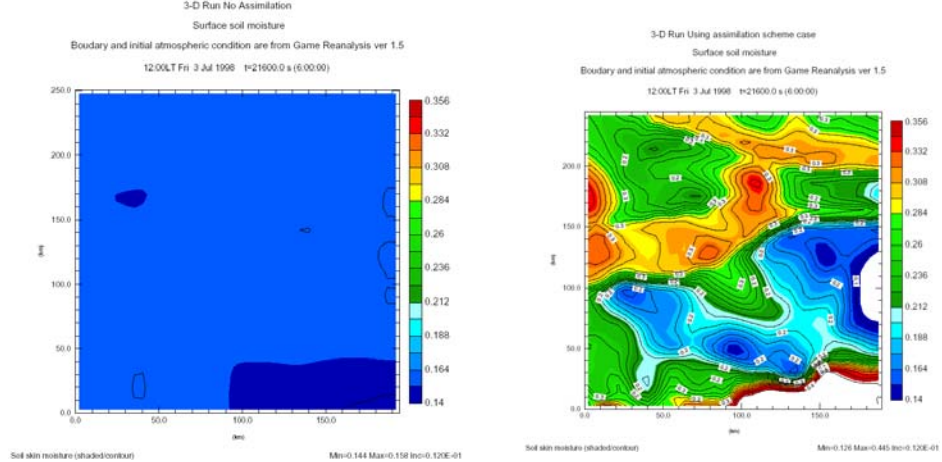
LDASUT with DMRT (dense media radiative transfer model)



Coupling Atmospheric Model with Land Data Assimilation System

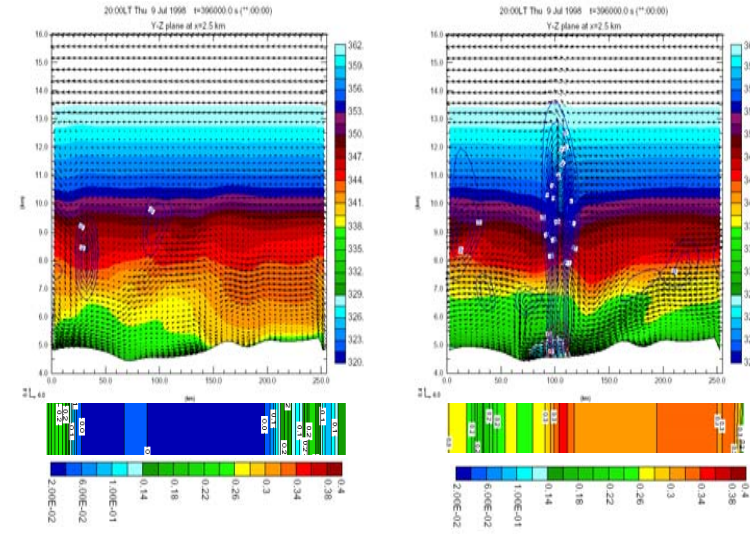


Surface Soil moisture Distribution

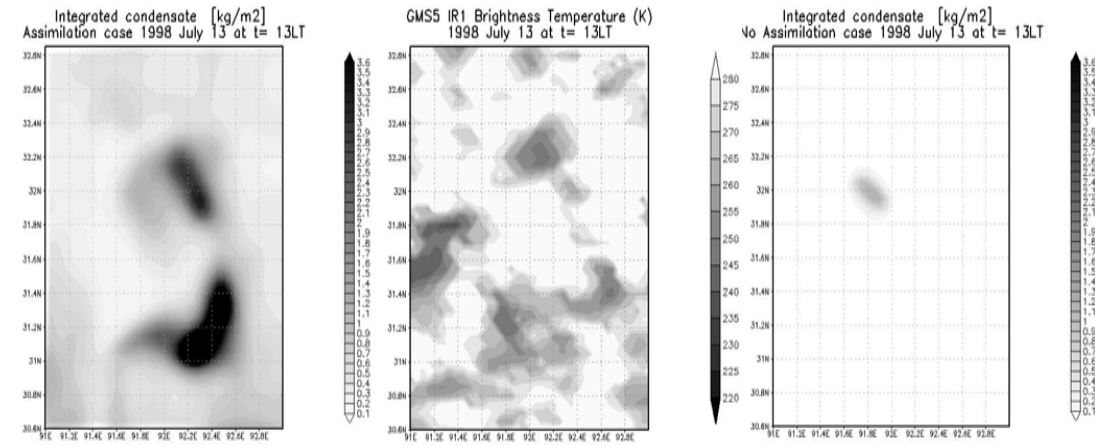


Spatial Resolution = $0.05^\circ \times 0.05^\circ$ (1800 Grids)
 Assimilation Window = 1Day
 Initial Conditions = GAME Reanalysis Ver1.5
 Simulation Period = July 3rd 1998~8th
 Satellite Data = TMI (10.35GHz & 19.65GHz)

Convection



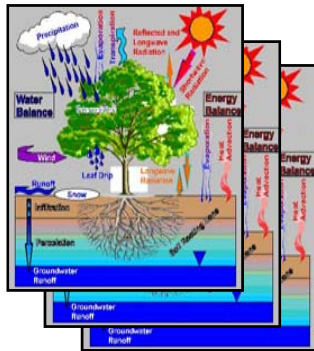
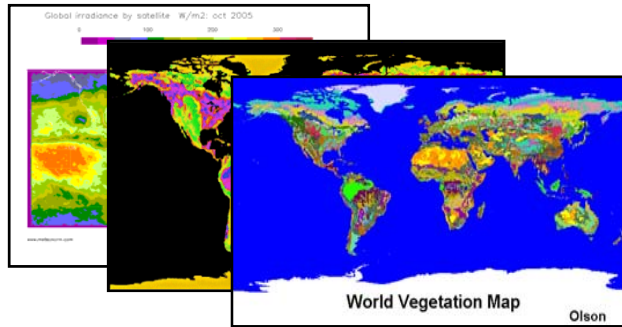
Cloudiness



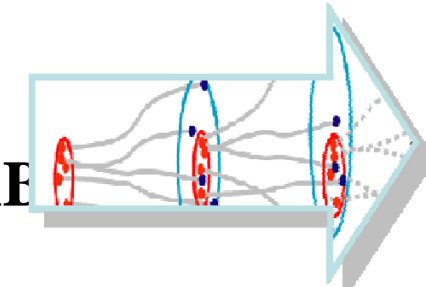
Spatial distribution of the integrated condensate : no-assimilation case (right), assimilation case (left), compared with the spatial distribution of the GMS5 IR1 infrared brightness temperature (middle)

(Boussetta et al. 2007)

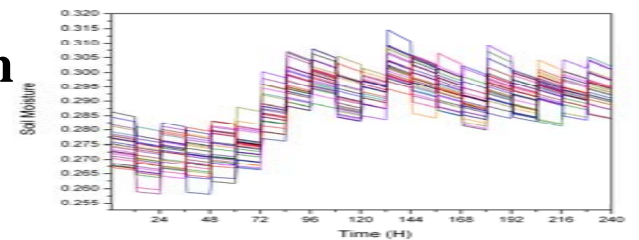
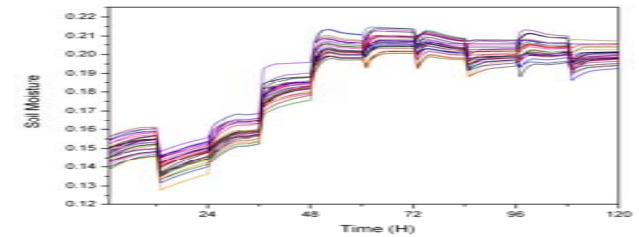
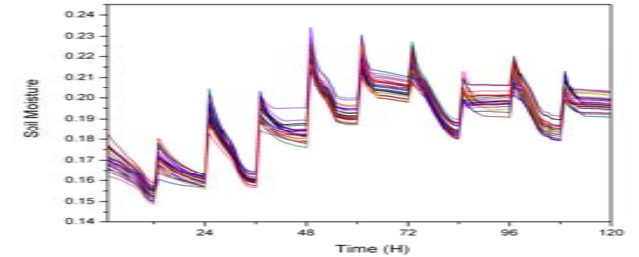
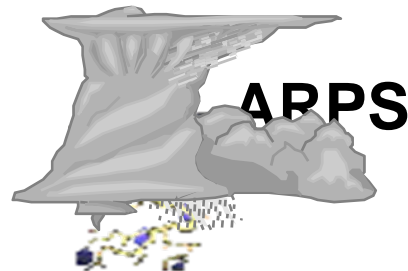
Ensemble Prediction



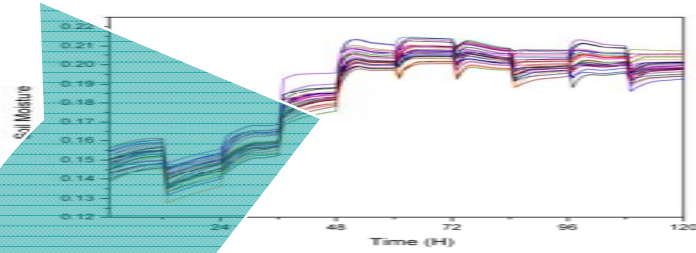
JMASiE



Ensemble prediction

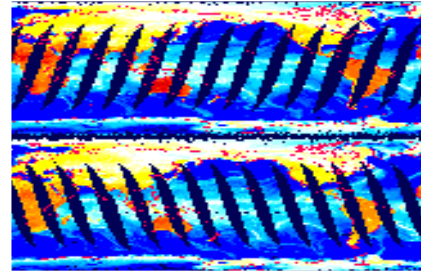
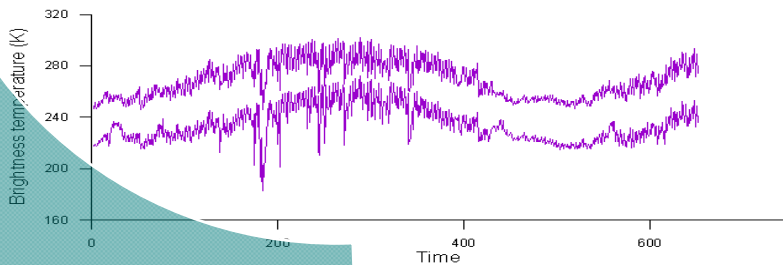
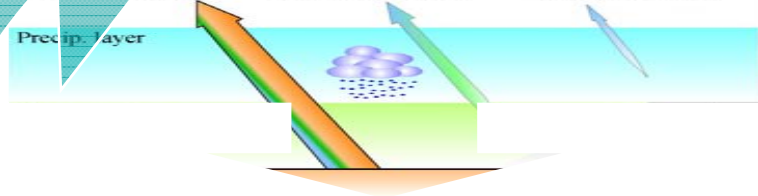


Ensemble filtering



The Radiative Transfer Equation

$$T_b = T_{br} e^{-\tau} e^{\tau_s} + (1-\omega_v) (1-e^{-\tau}) T_c e^{\tau_s} + \sum (1-\omega_r) (1-e^{-\tau}) T_r$$



AMSR-E

+

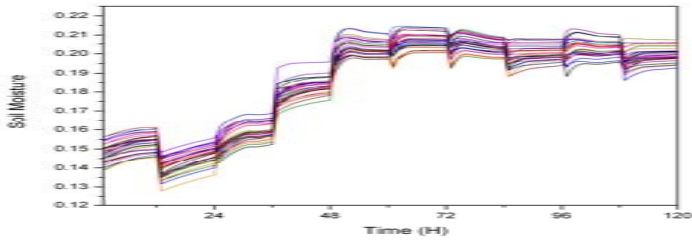


**Kalman
gain**

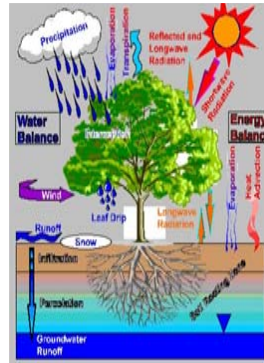
×

**Innovation
vector**

Atmospheric Prediction



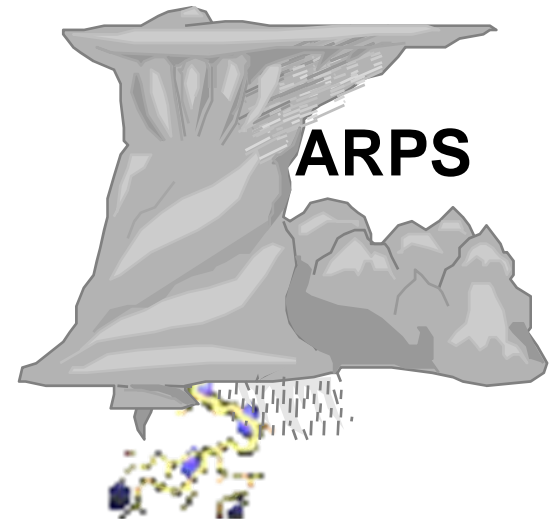
State



fluxes

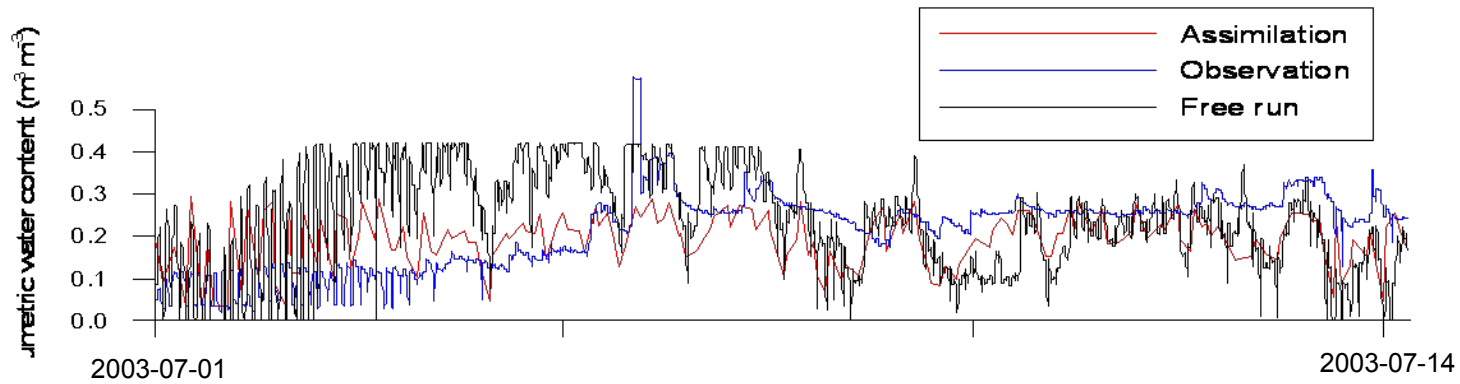


JMASiB

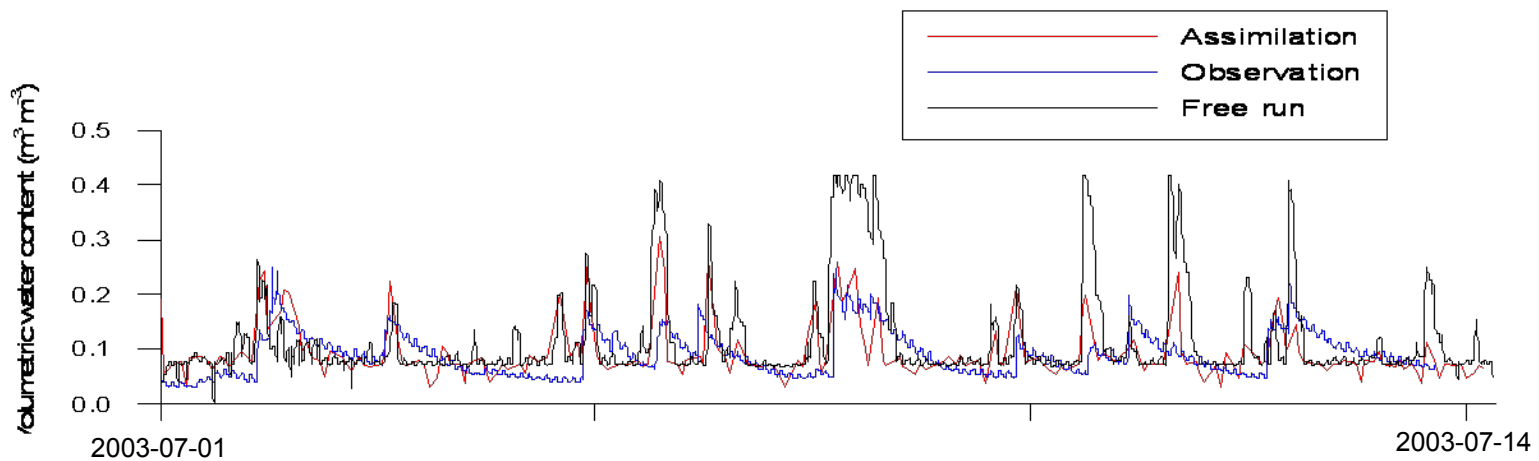


(Boussetta et al. 2007)

Surface soil moisture(Tibet)



Surface Soil moisture (Mongolia)



(Li et al. 2007)

EnKF vs 4DVAR

- Variational methods
 - Multiple minima
 - Hard to compute error statistics
 - Do not allow for sequential processing of measurement
- Ensemble methods
 - Provide estimate with error statistics
 - Allow for sequential processing of measurement
 - Advantage with nonlinear dynamics

(Evensen G. The parameter estimation problem revisited. Bergen, Norway: Hydro Research Centre, 2005)

EnKF vs 4DVAR (cont)

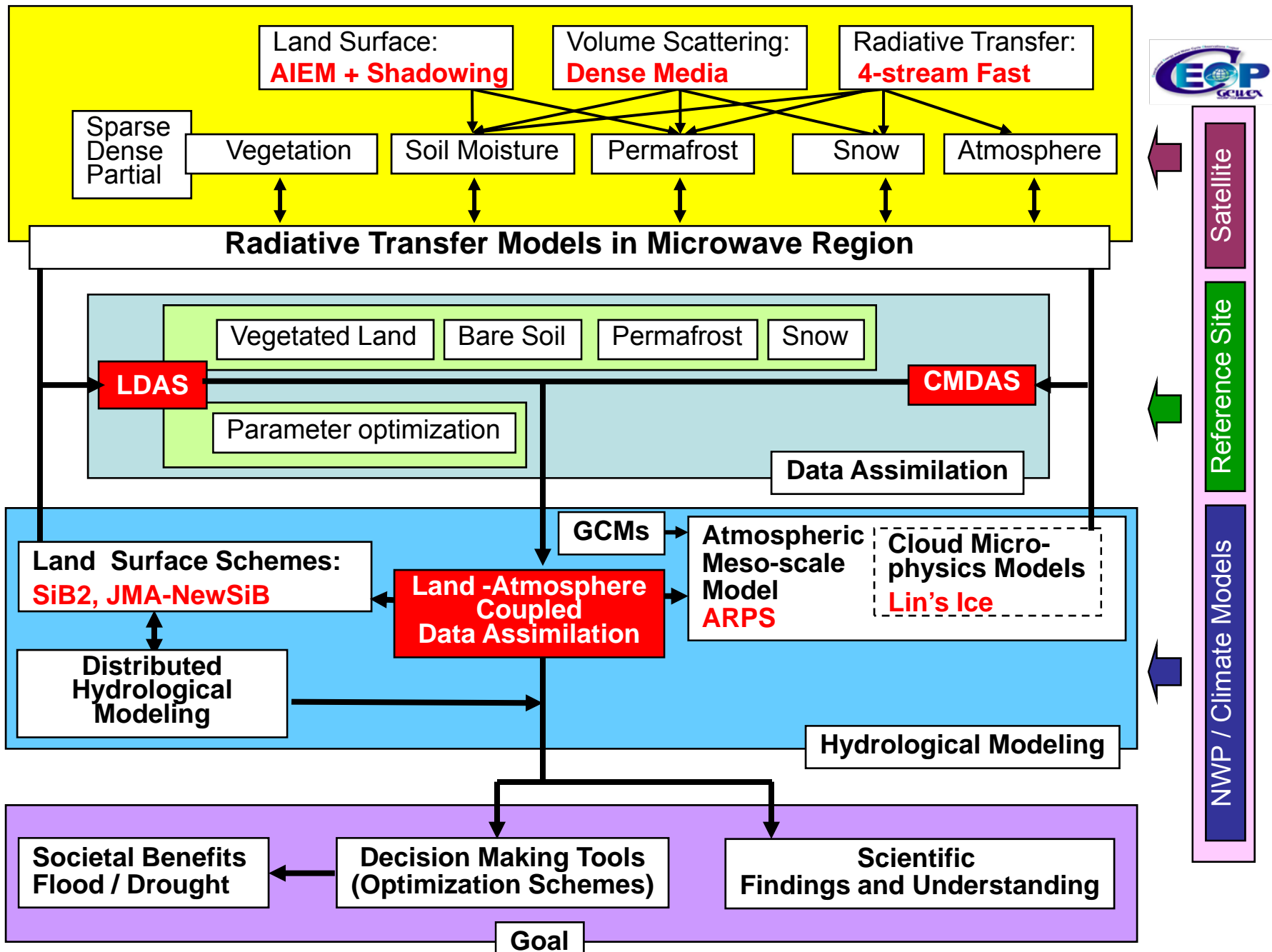
	4DVAR	EnKF
Flow dependent background errors	Yes, within each cycle, but errors are not propagated between cycles	Yes.
Nonlinear observation operators	Yes, with non-quadratic cost function	Yes, but results will be treated as Gaussian

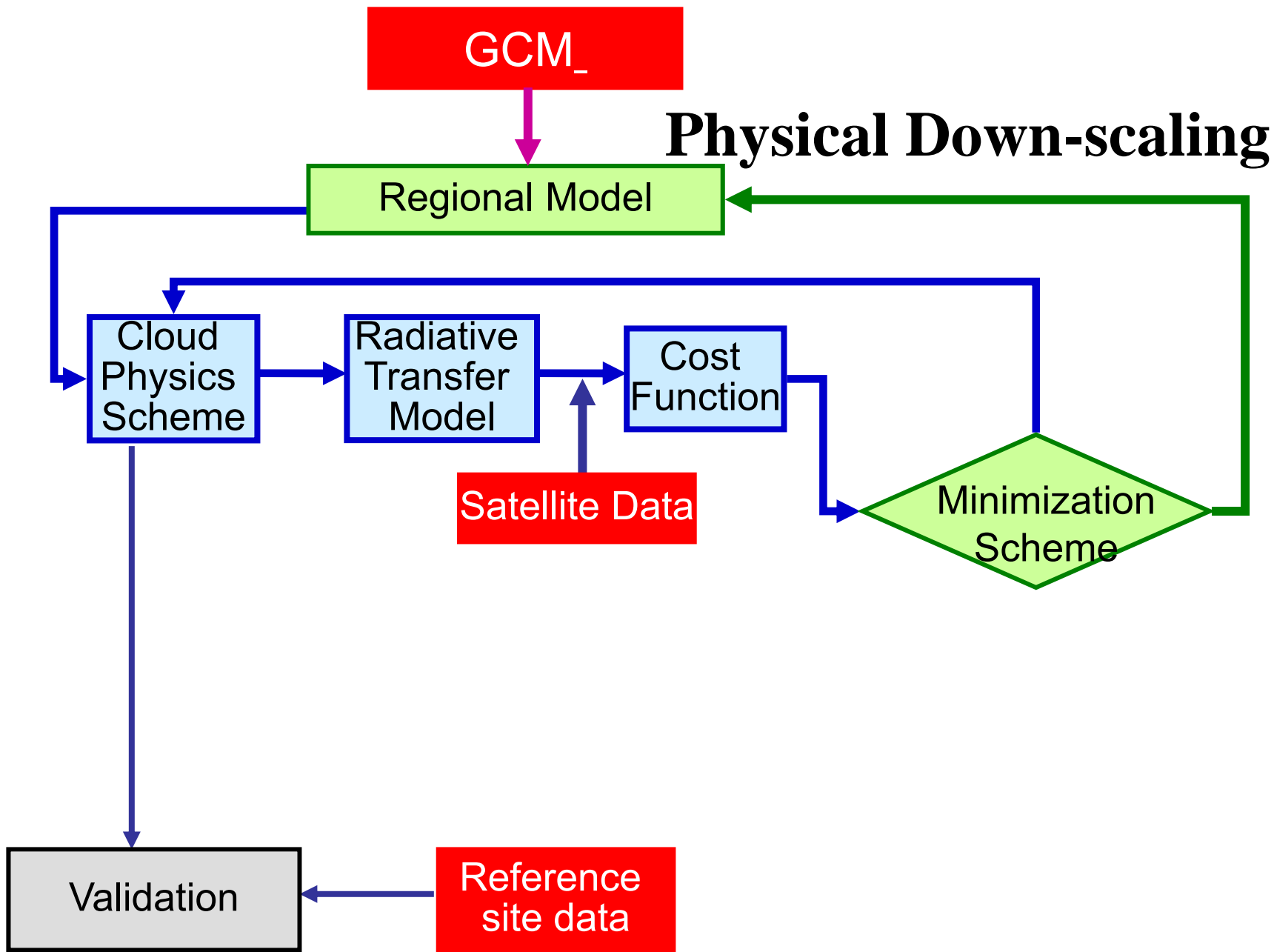
$$J(\delta \underline{\mathbf{x}}) = \frac{1}{2} (\delta \underline{\mathbf{x}} - \delta \underline{\mathbf{x}}^b)^T \mathbf{B}_{(\underline{\mathbf{x}})}^{f,1} (\delta \underline{\mathbf{x}} - \delta \underline{\mathbf{x}}^b) + \frac{1}{2} (\underline{\mathbf{y}} - \underline{\mathbf{y}}^o)^T \mathbf{R}^{-1} (\underline{\mathbf{y}} - \underline{\mathbf{y}}^o)$$

EnKF vs 4DVAR (cont)

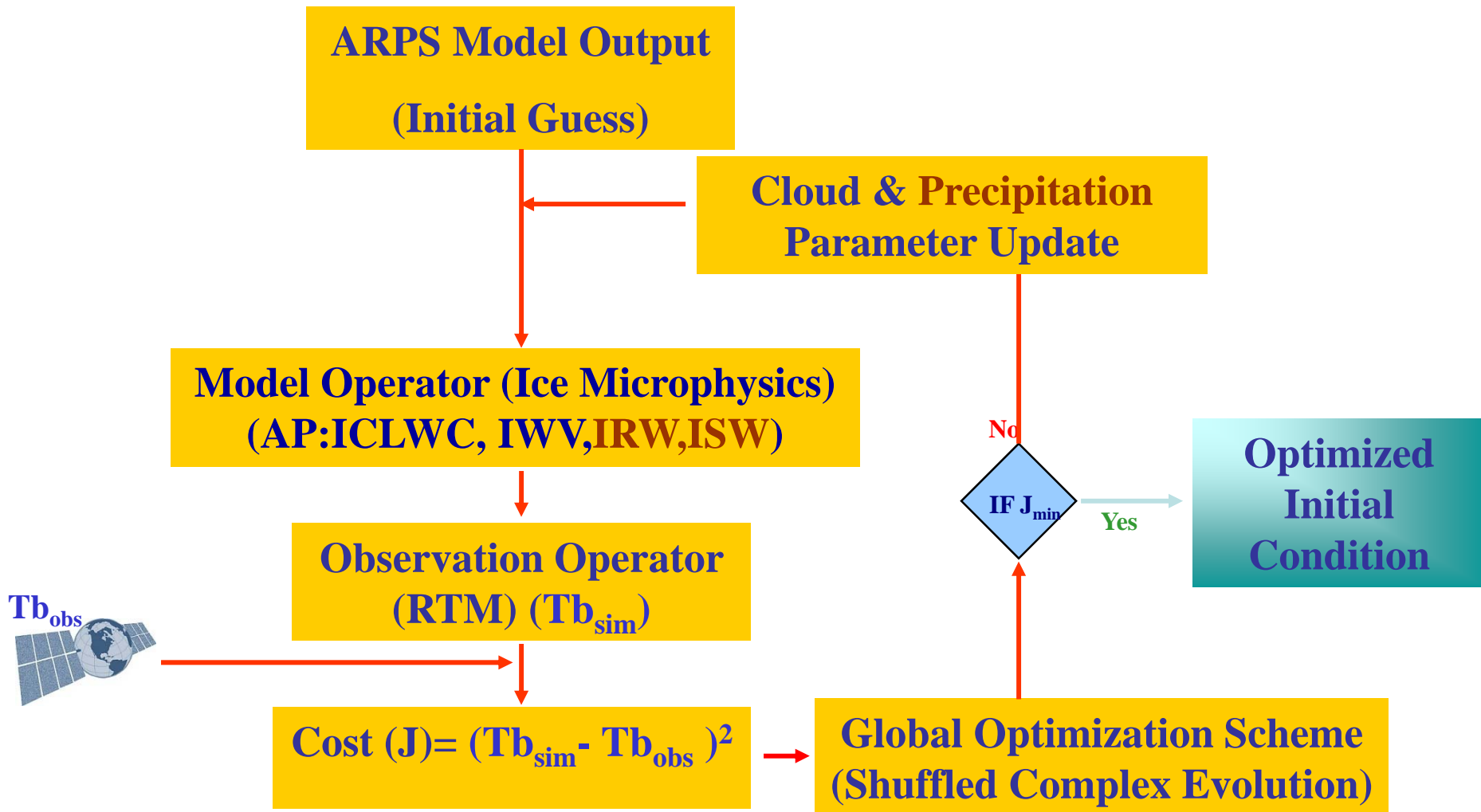
	4DVAR	EnKF
Forecast model	Uses a TLM or PF model that must be specially designed. Model switches are problematic.	Uses full nonlinear forecast model which describes the evolution of atmospheric states.
Lateral boundary conditions	Set boundary increments to zero, or treat as control variables	May require a global ensemble
Balance	Balance imposed as part of assimilation	Localization removes some balance

(Dance S, Roulstone I, Lorenc A. A review of the theoretical potential, & limitations of the Ensemble Kalman Filter and 4D-Var. NERC Centres for Atmospheric Science, 2003)

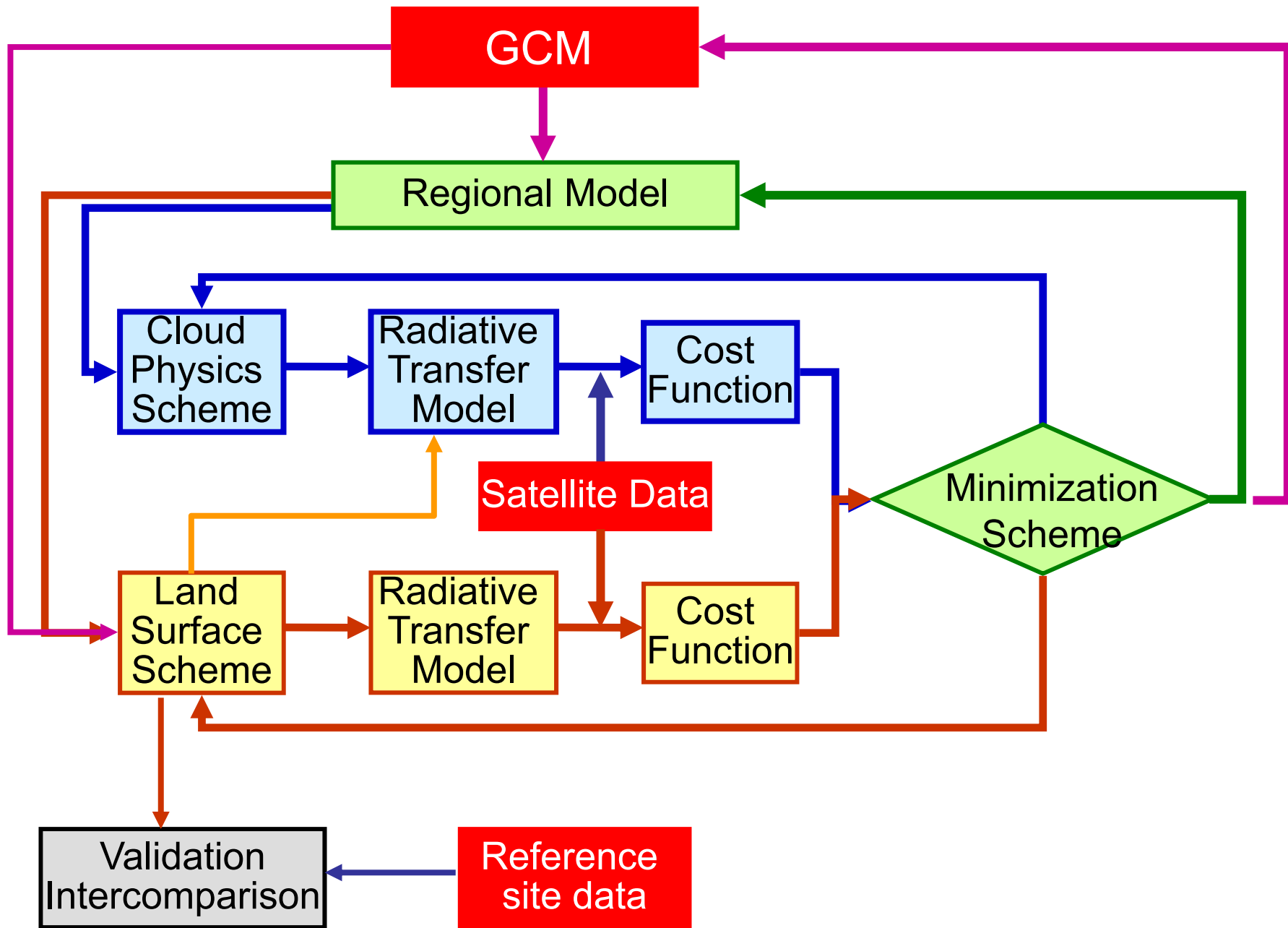


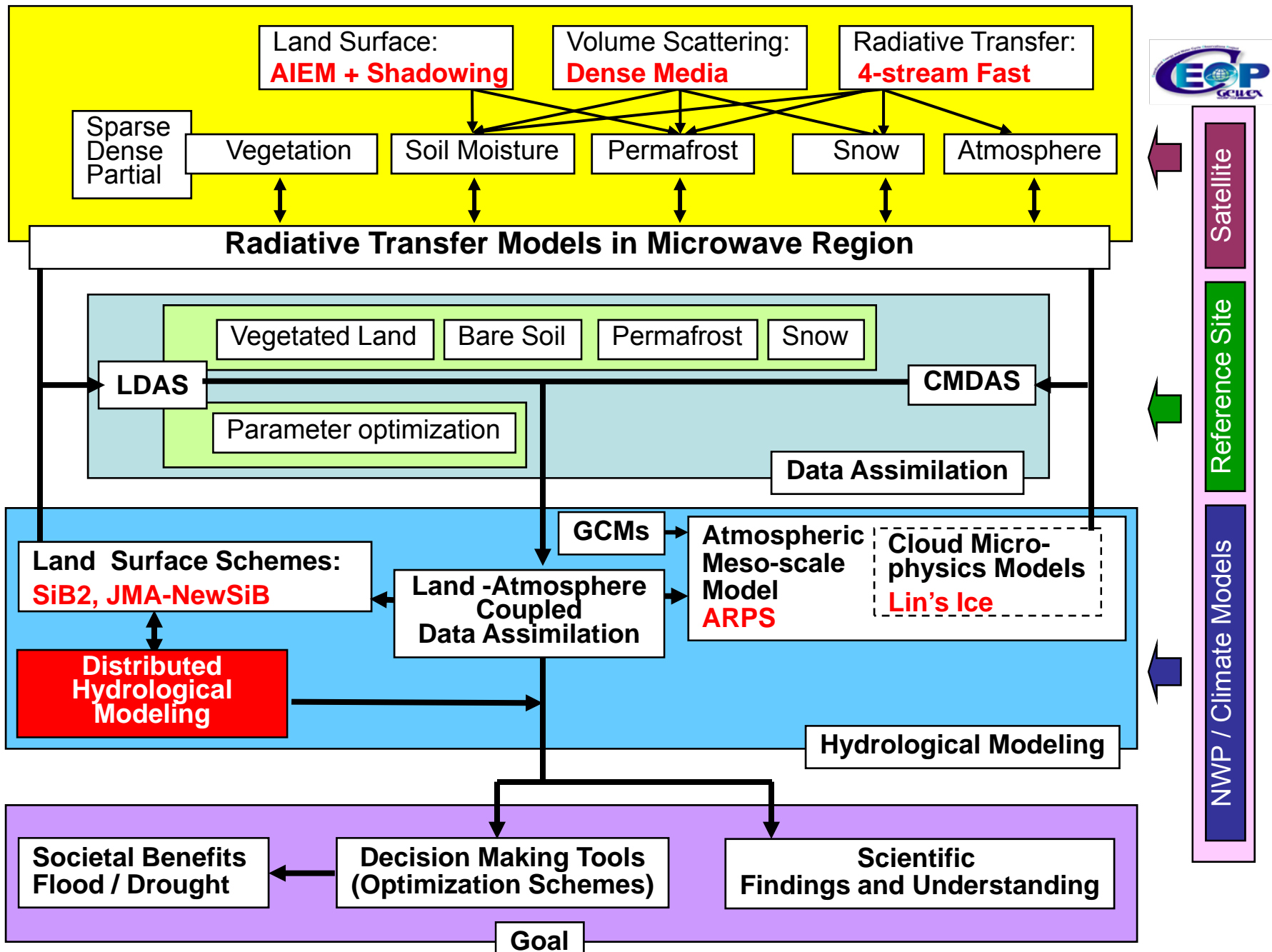


CMDAS Framework

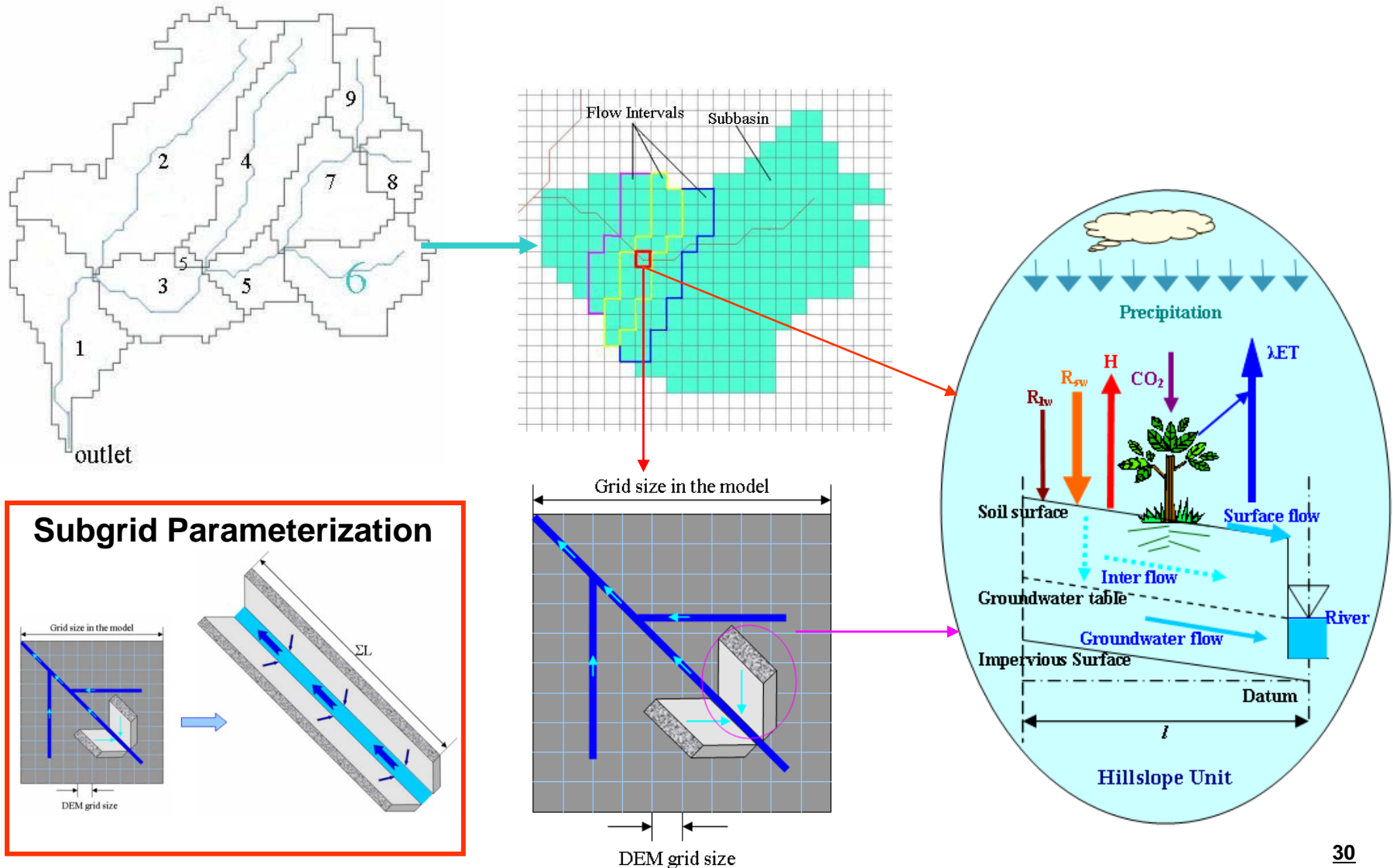


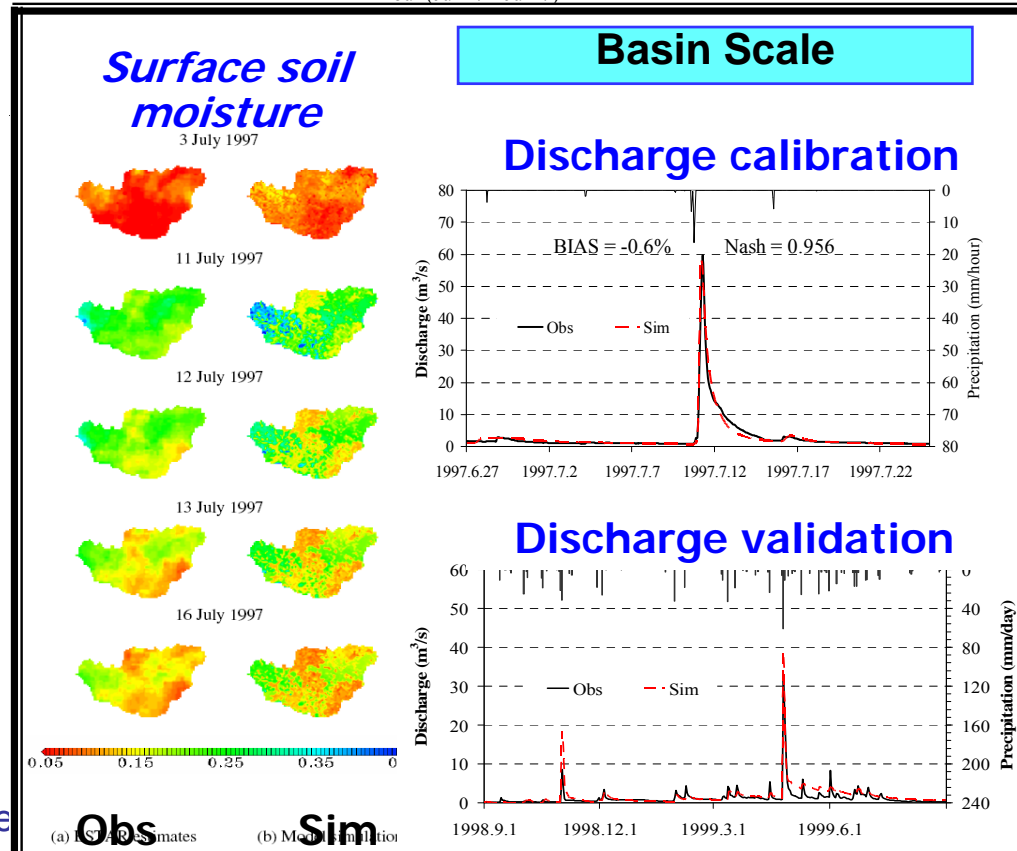
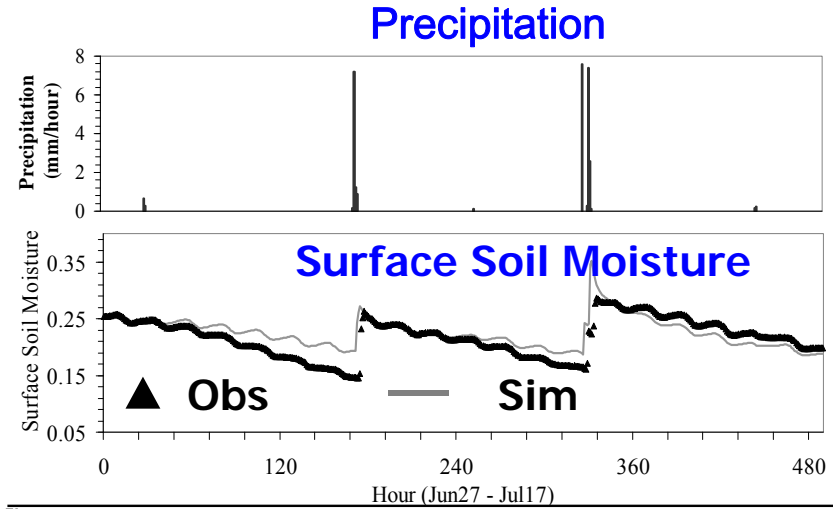
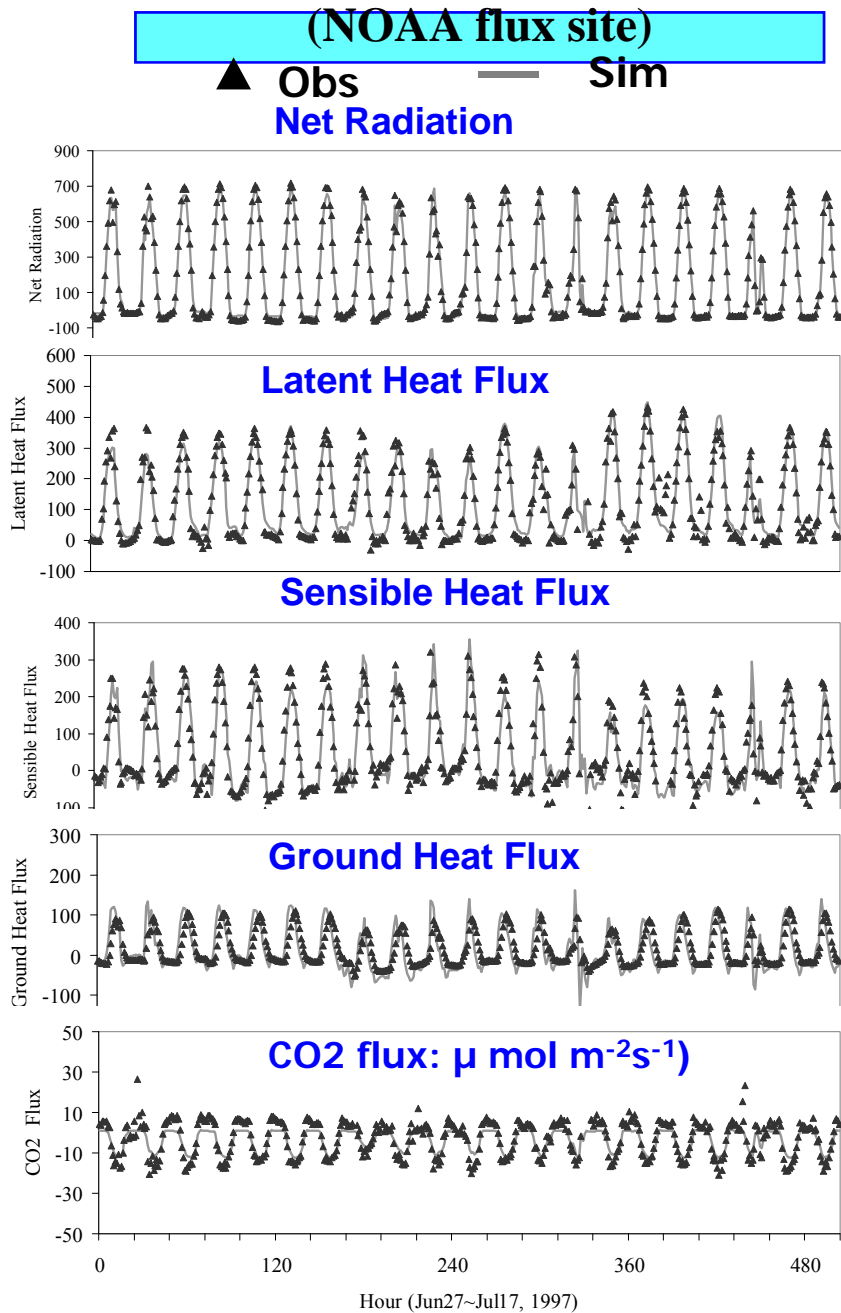
(Mirza et al. 2007)

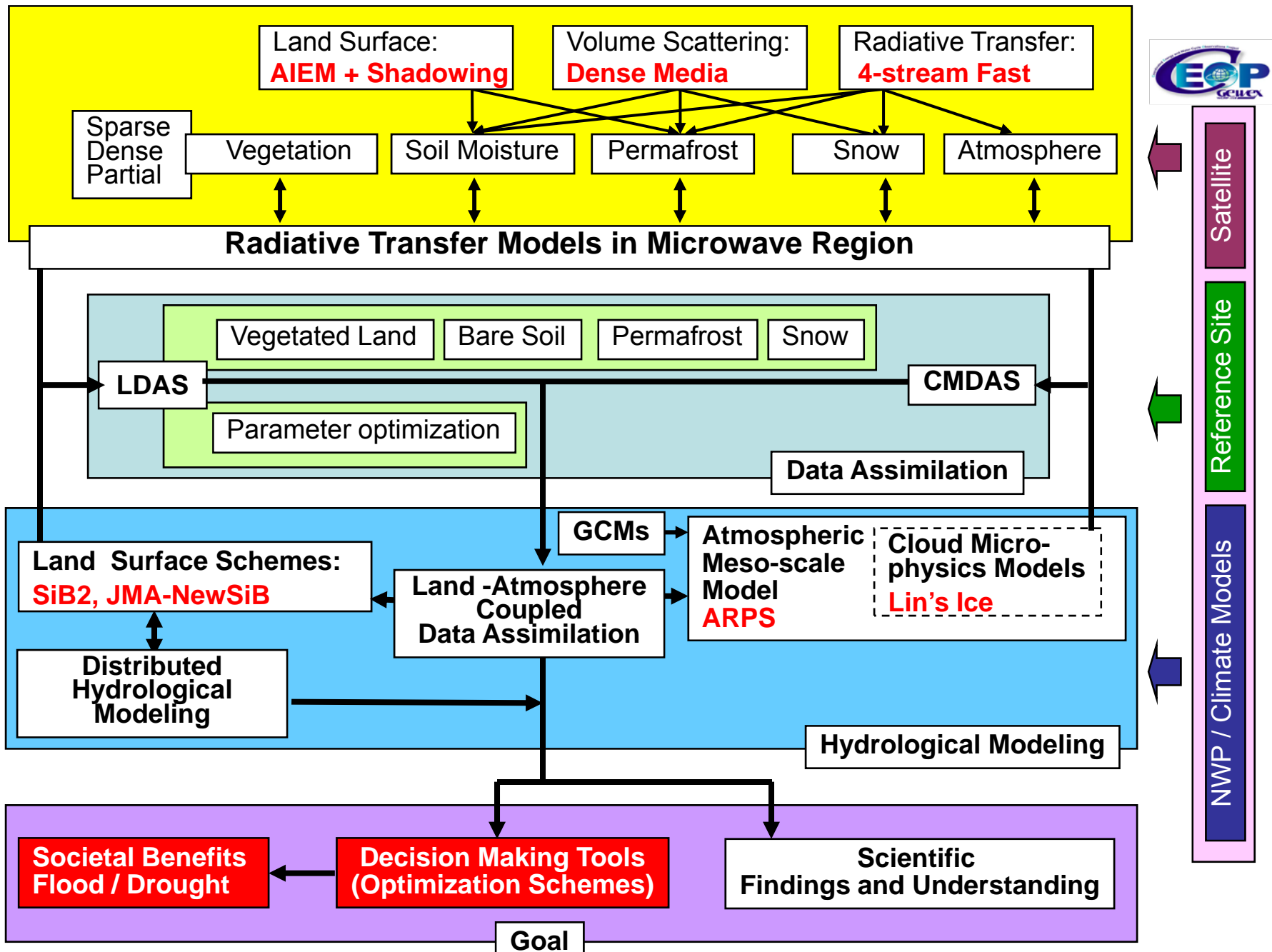




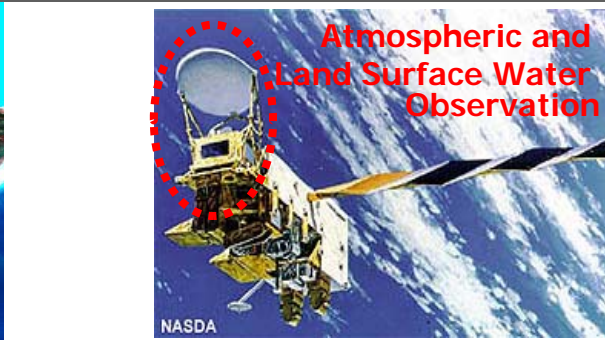
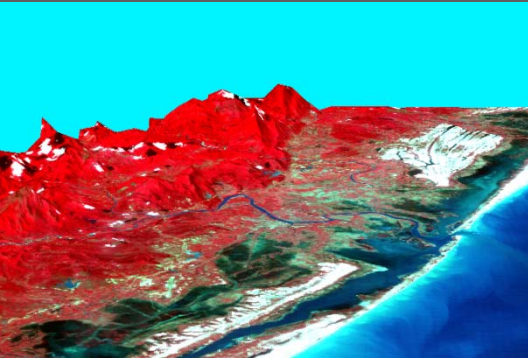
(Water and Energy Budget-based Distributed Hydrological Model)



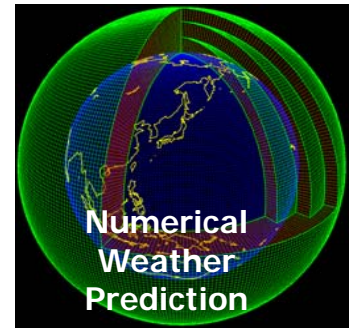




GEOSS/AWCI-SAFE Flood Prediction System in Vietnam (Huong R.)

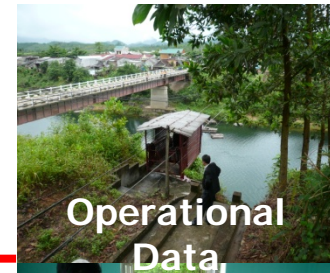
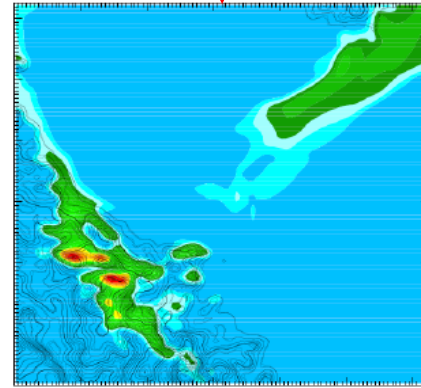
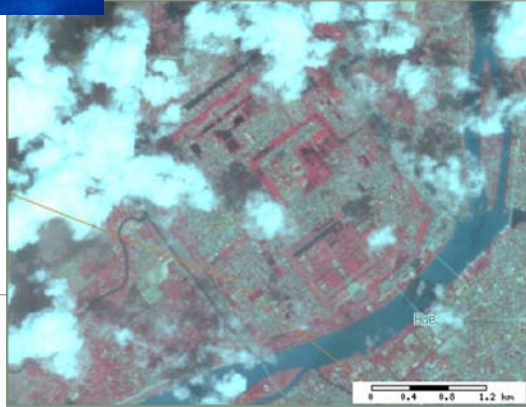


Heavy Rainfall Prediction Coupled with Satellite Data Assimilation



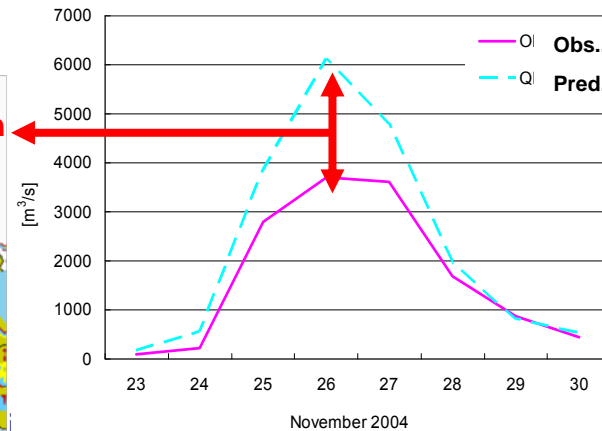
Topography and River Channel Network

Land-use



Flood Prediction

Prediction of the inundation Area and Depth

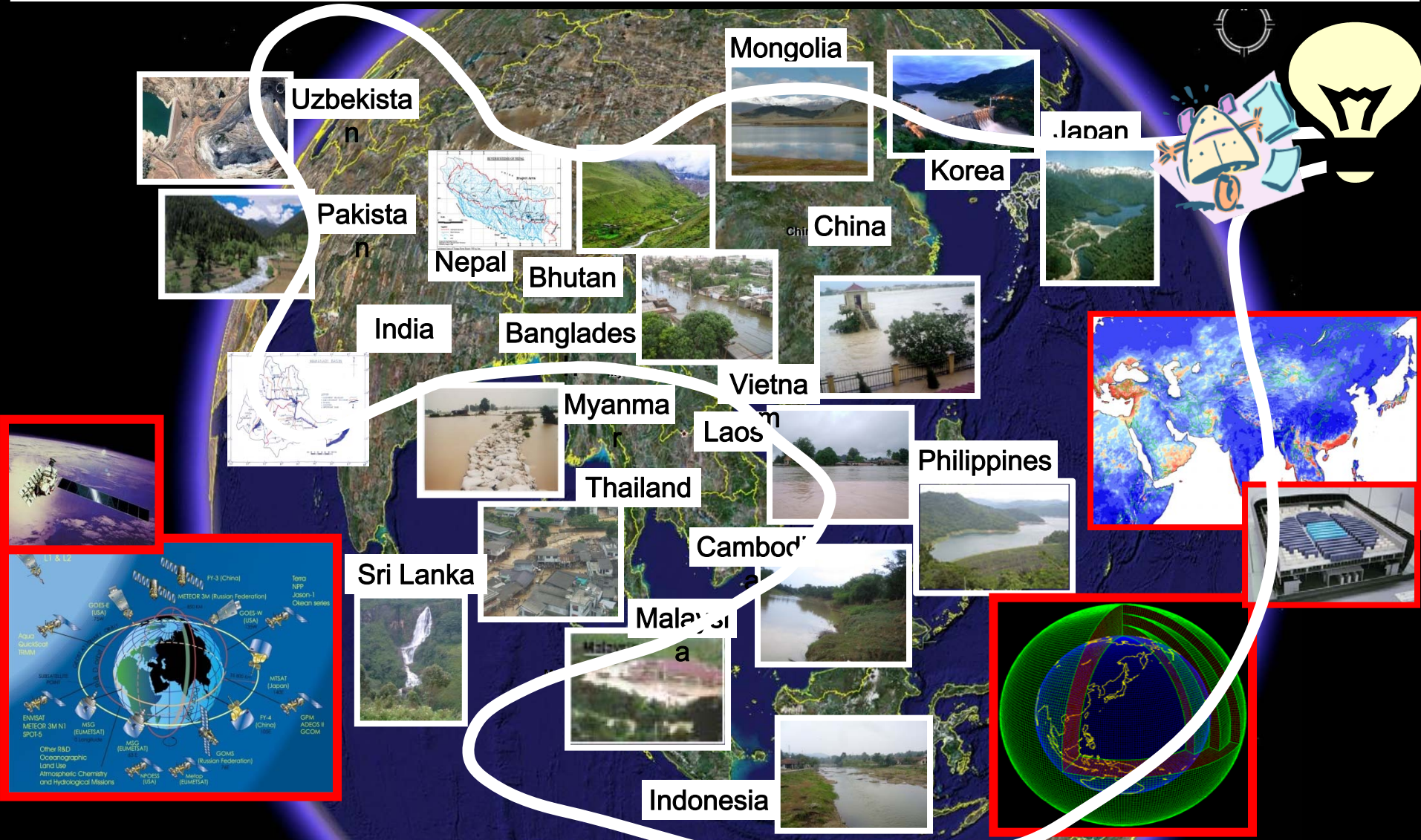


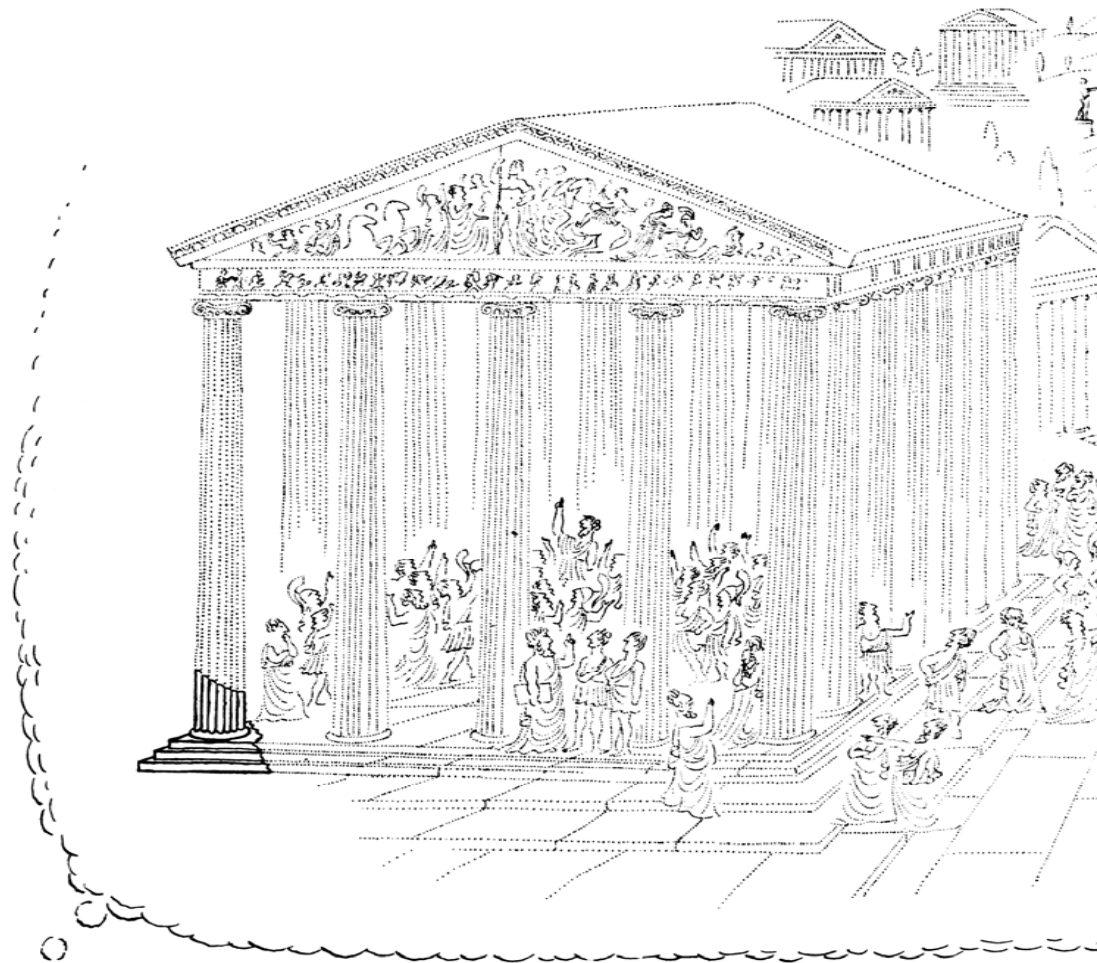
Evacuation Instruction

GEOSS Asian Water Cycle Initiative (AWCI)

19 Member Countries

18 River Basins for Initial Demonstration





Thank you

SEMPÉ.



Look Up Table

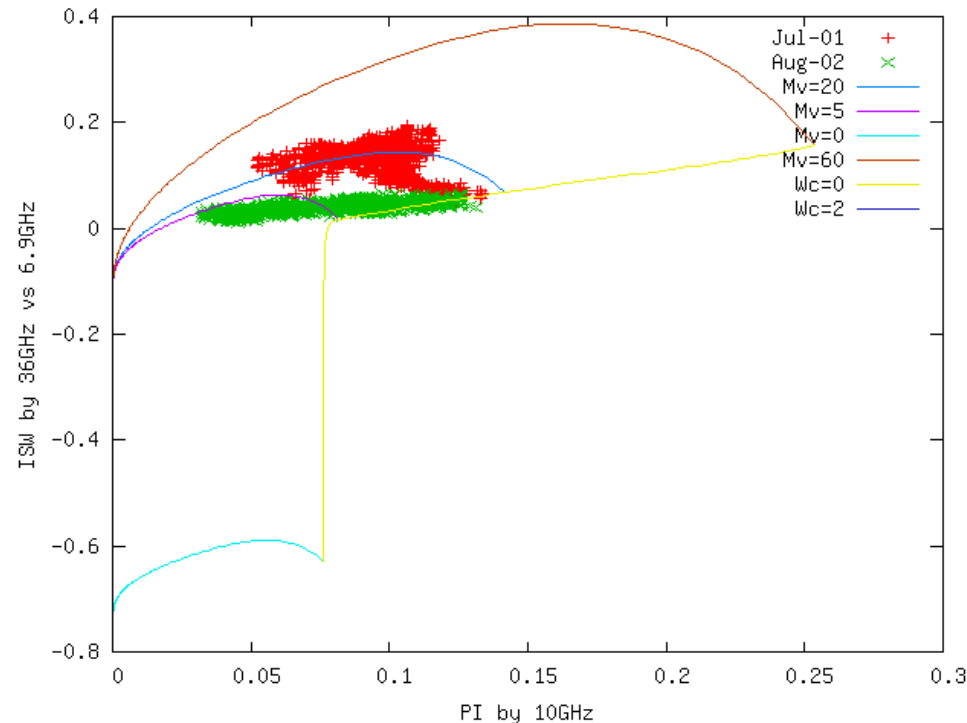
- Index of Soil Wetness (ISW)

$$ISW = \frac{T_{b36h} - T_{b6.9h}}{\frac{1}{2}(T_{b36h} + T_{b6.9h})}$$

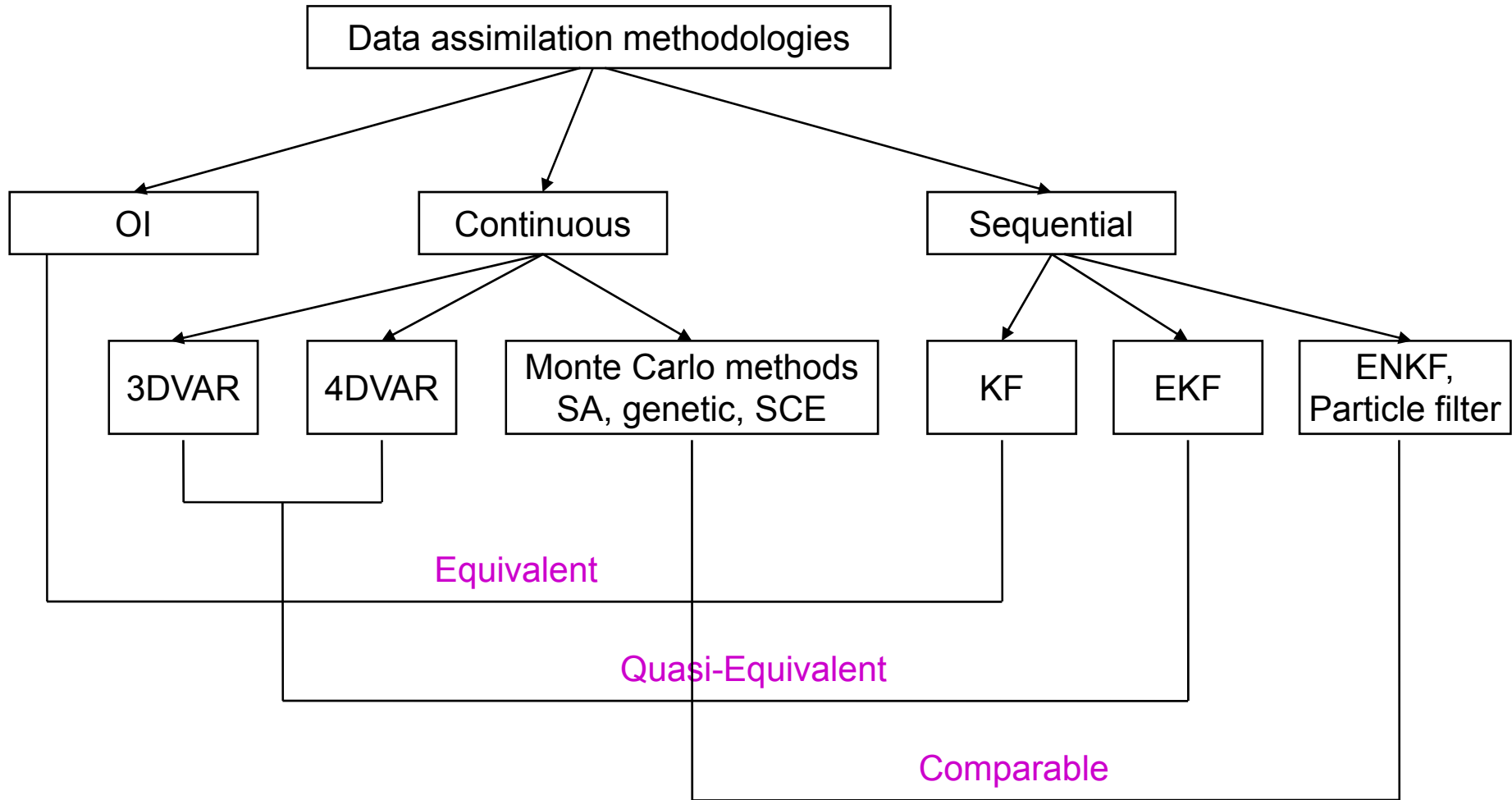
- Polarization Index (PI)

$$PI = \frac{T_{b10v} - T_{b10h}}{\frac{1}{2}(T_{b10v} + T_{b10h})}$$

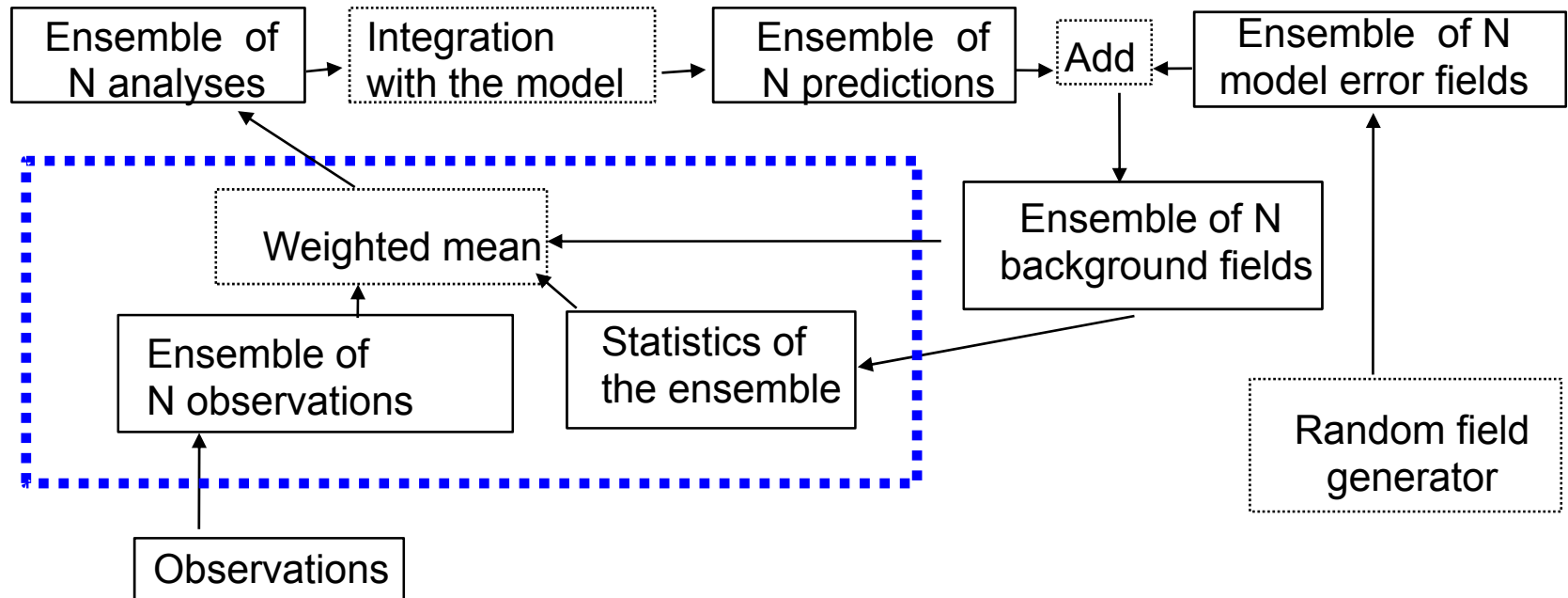
- Changing Mv from 0% to 60%, Wc from 0 to 2 every 0.01, running forward model, making look-up table



DA Classification

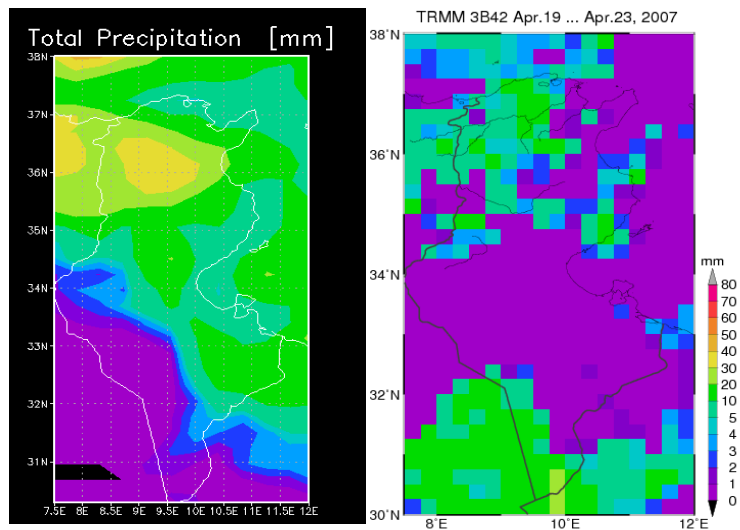


Ensemble Kalman filter

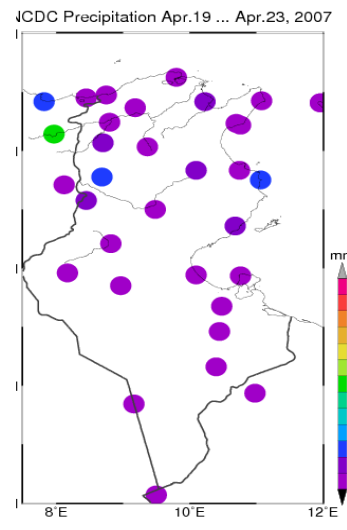


Precipitation over Tunisia

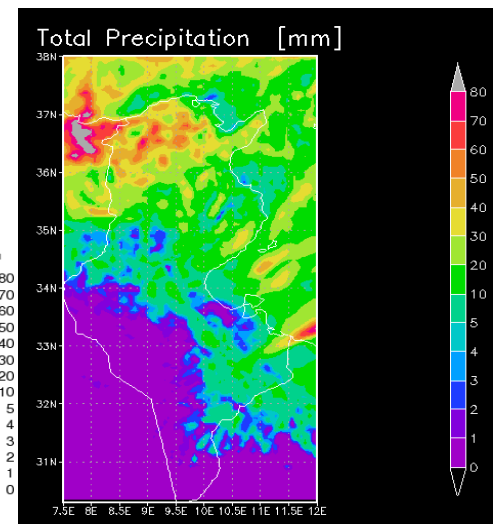
Without coupled System TRMM product



NCDC product



With coupled System



(Boussetta et al. 2009)