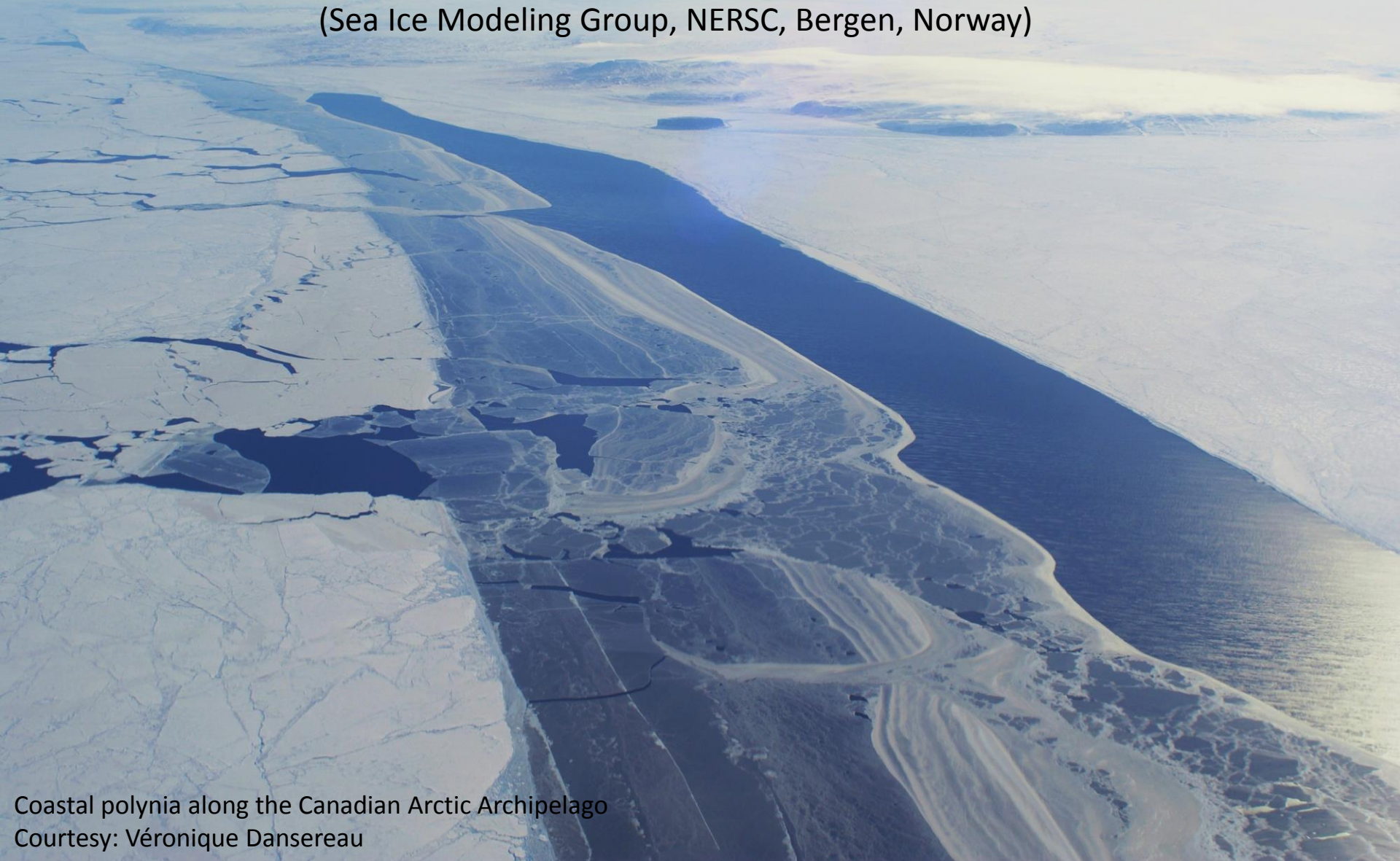


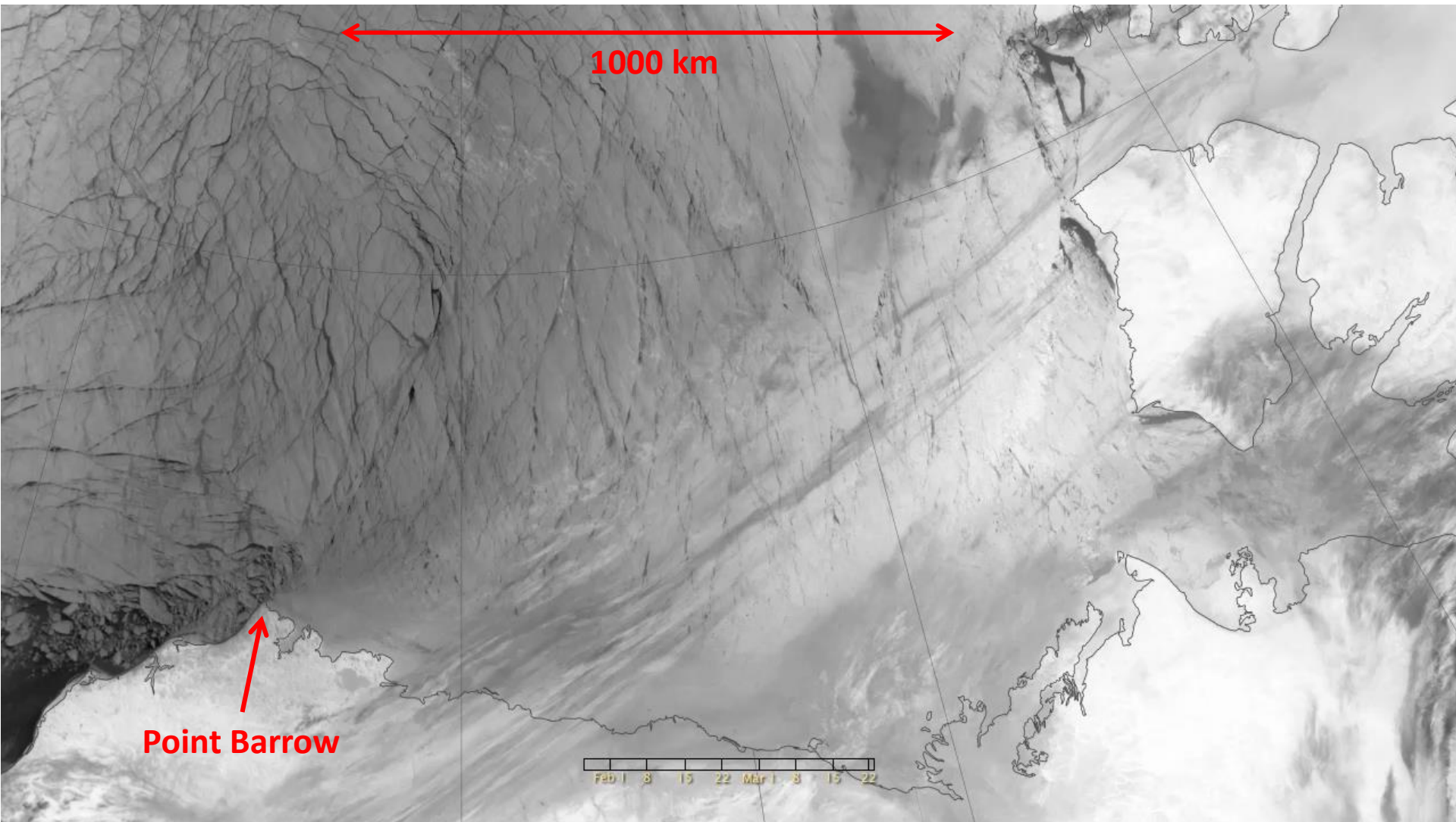
# Sea-ice role in Earth-system models

Pierre Rampal, **Sylvain Bouillon**, Einar Olason, Abdoulaye Samaké,  
Philipp Griewanck, Tim Williams, Natalia Ivanova, Jon Bergh  
(Sea Ice Modeling Group, NERSC, Bergen, Norway)



Coastal polynia along the Canadian Arctic Archipelago  
Courtesy: Véronique Dansereau

# Why modeling sea ice is a real challenge?



In this example: Large **breaking event** in Beaufort Sea , February-March 2013

“Seamless prediction”?

“What Earth system processes are needed, and what level of complexity is required to further **extend atmospheric predictive skill**?”

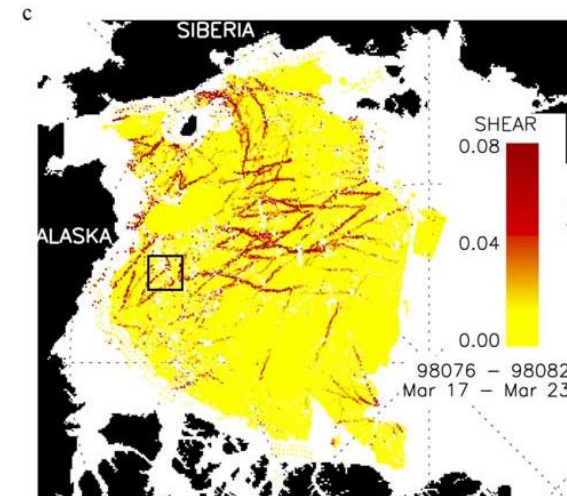
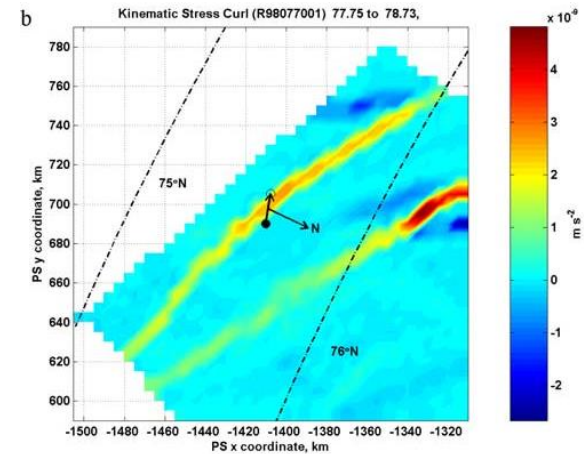
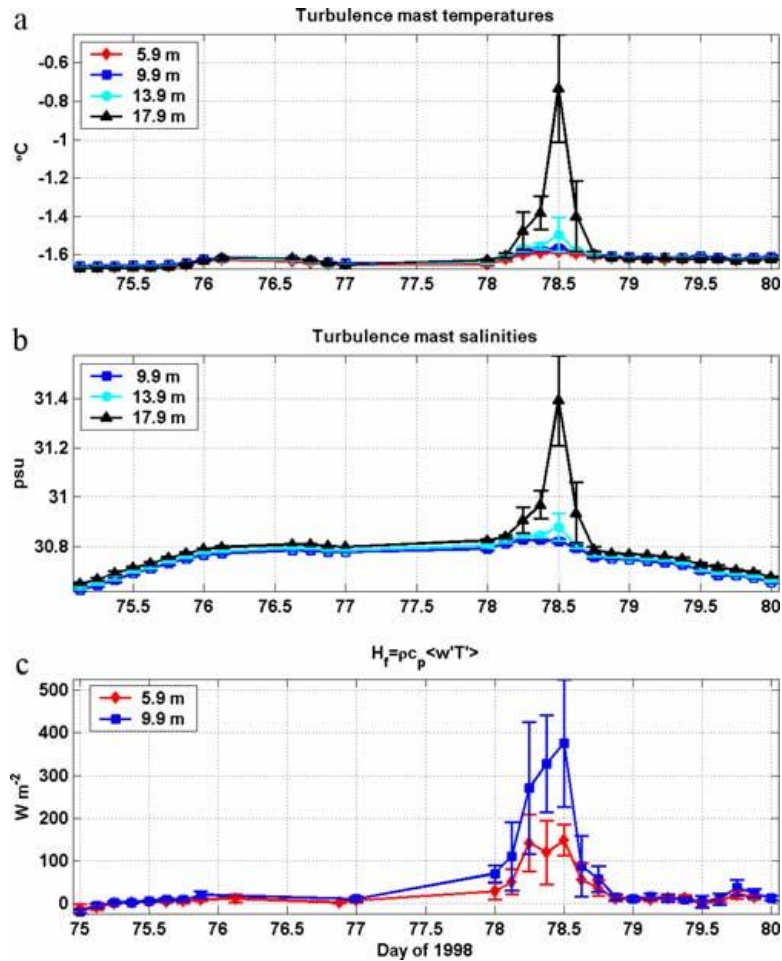
“...Earth system **modelling** and **assimilation** as the way to improve further skill in the **1-day to 1-year forecast** range covered by the ECMWF forecasts.”

“If a model cannot **simulate a phenomena**, it cannot **predict that phenomena**.”

*“...climate prediction at **the model resolutions and levels of complexity considered essential** for the most advanced and reliable representations of the climate system that **technology and our scientific understanding of the problem** can deliver...”*

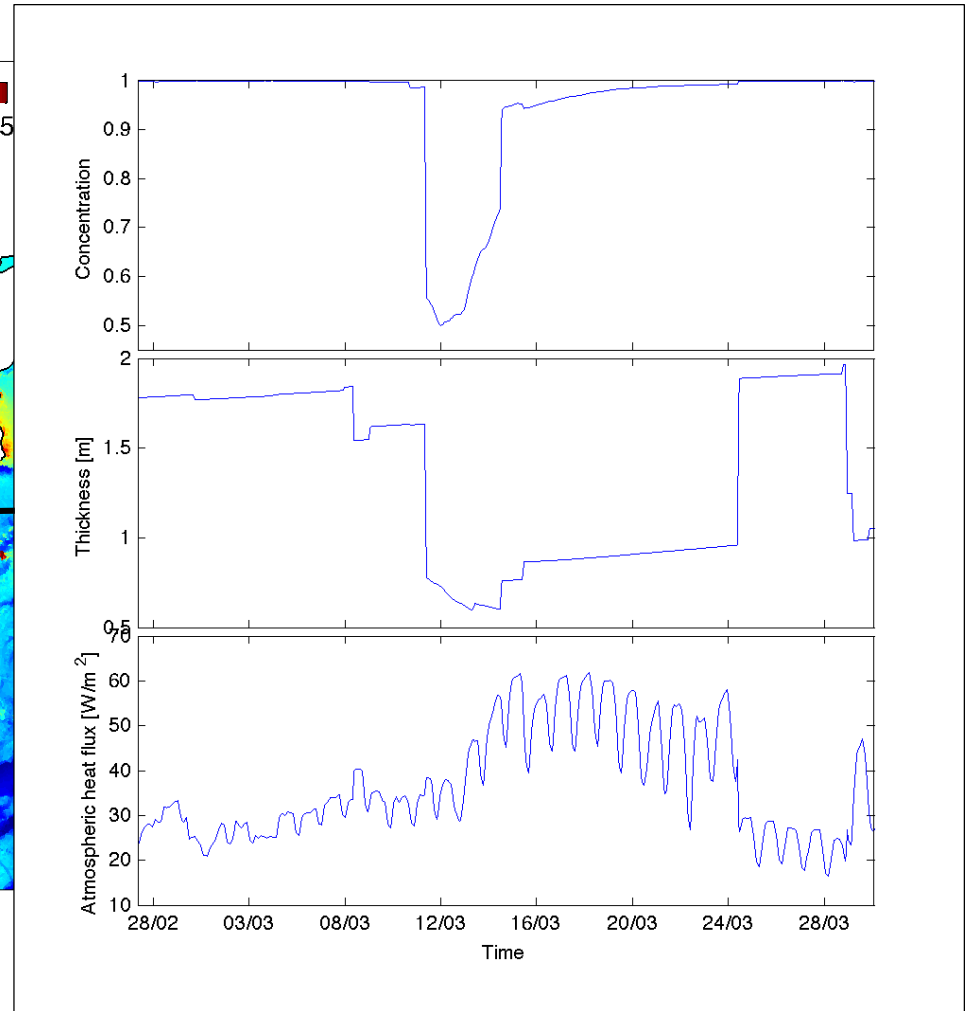
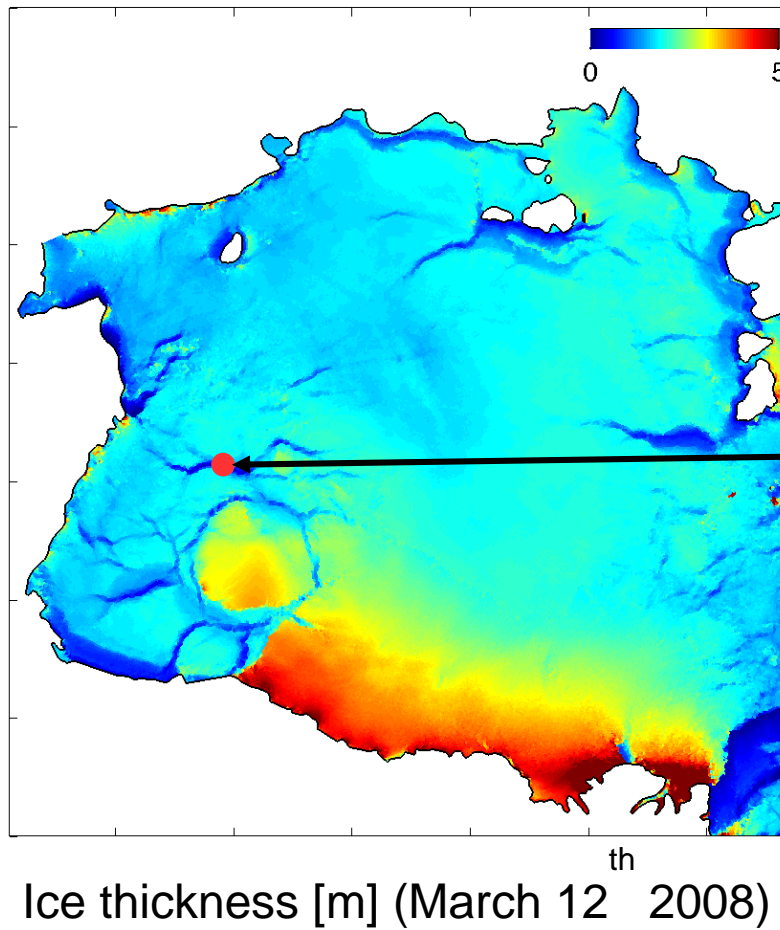
- Intense oceanic heat fluxes occur where sea ice is deforming.

## Example from observation

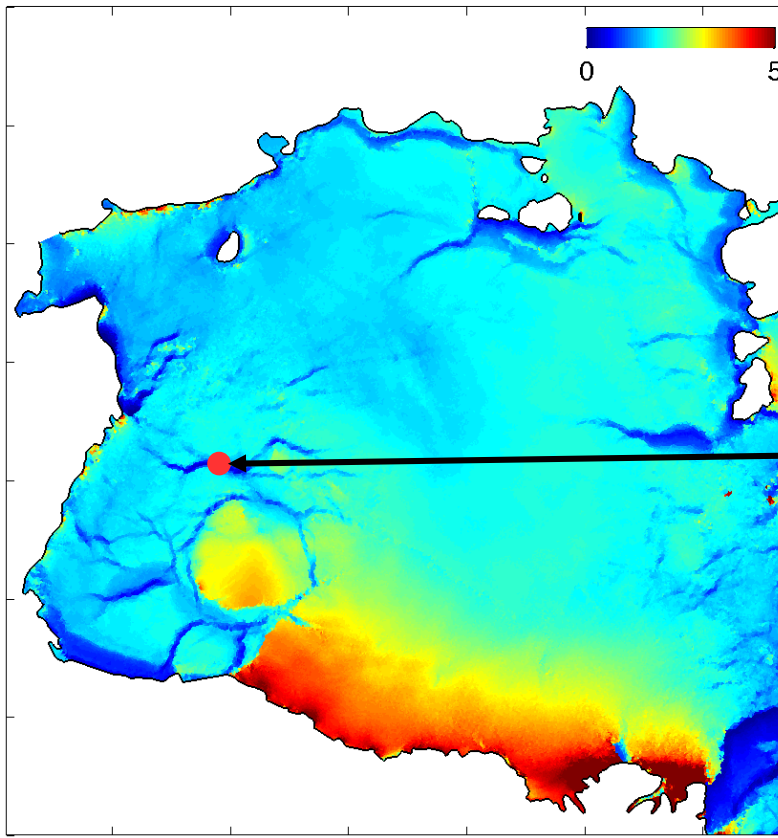


- Intense atmospheric heat fluxes occur where sea ice opens.

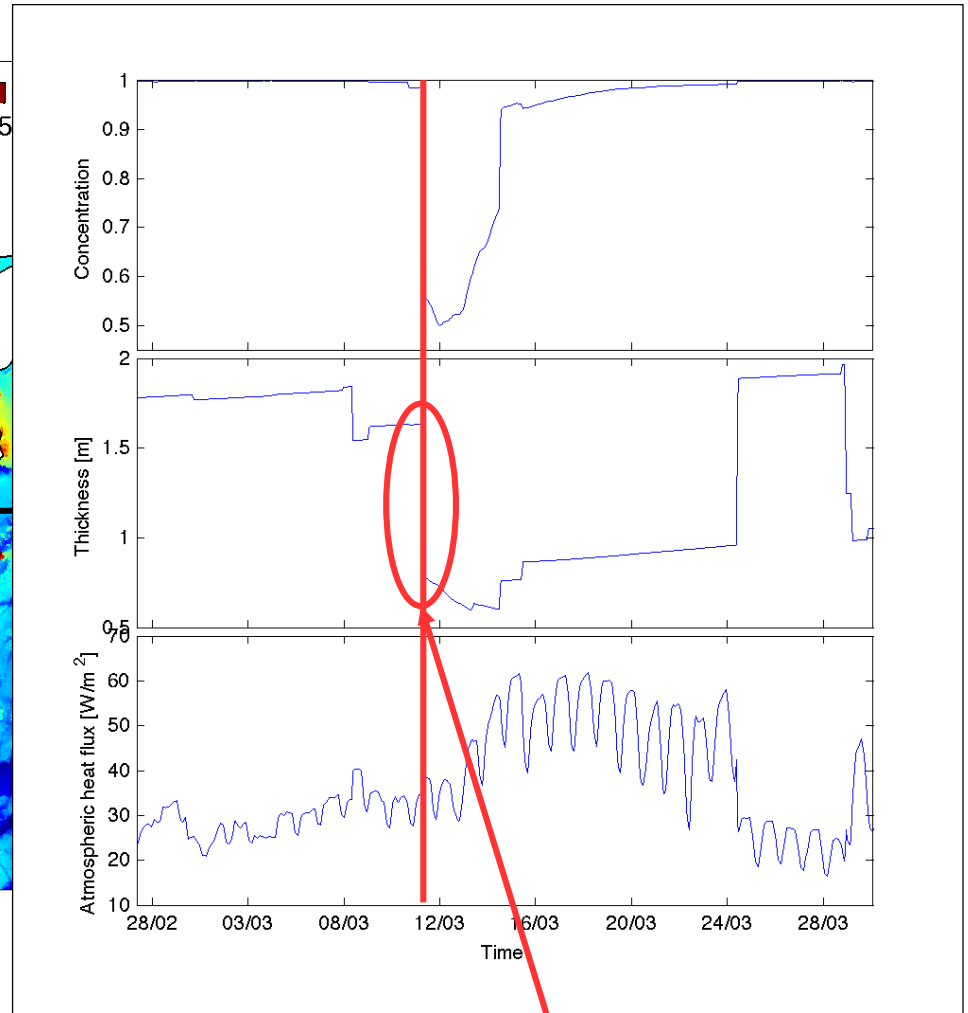
## Example from simulation



# Example from simulation



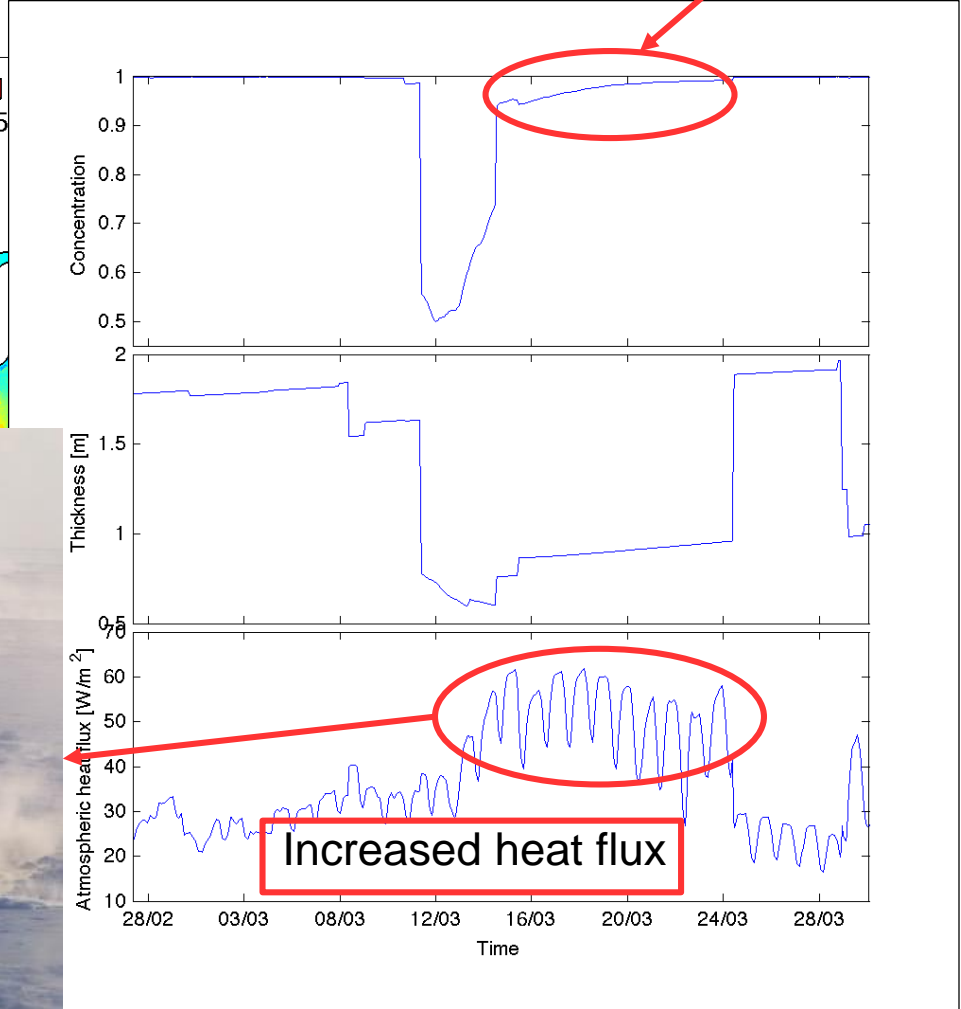
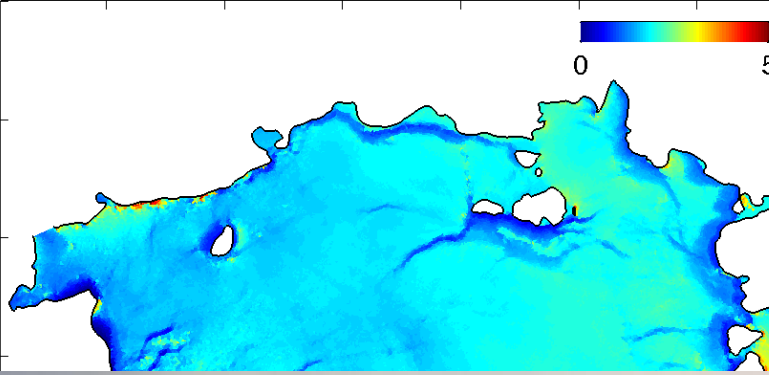
Ice thickness [m] (March 12 2008)

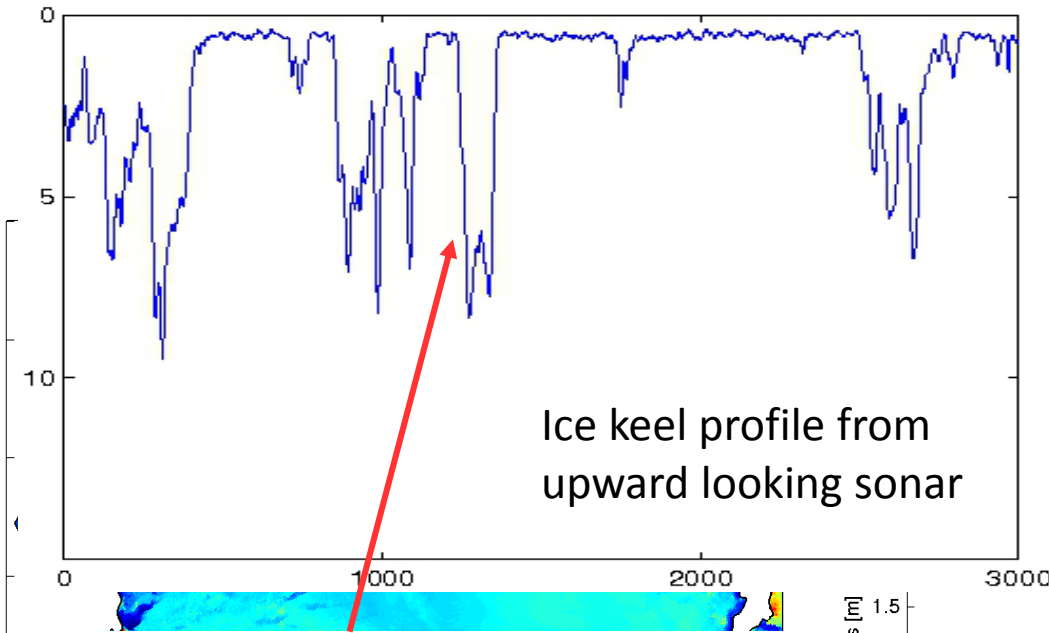


Mechanical opening

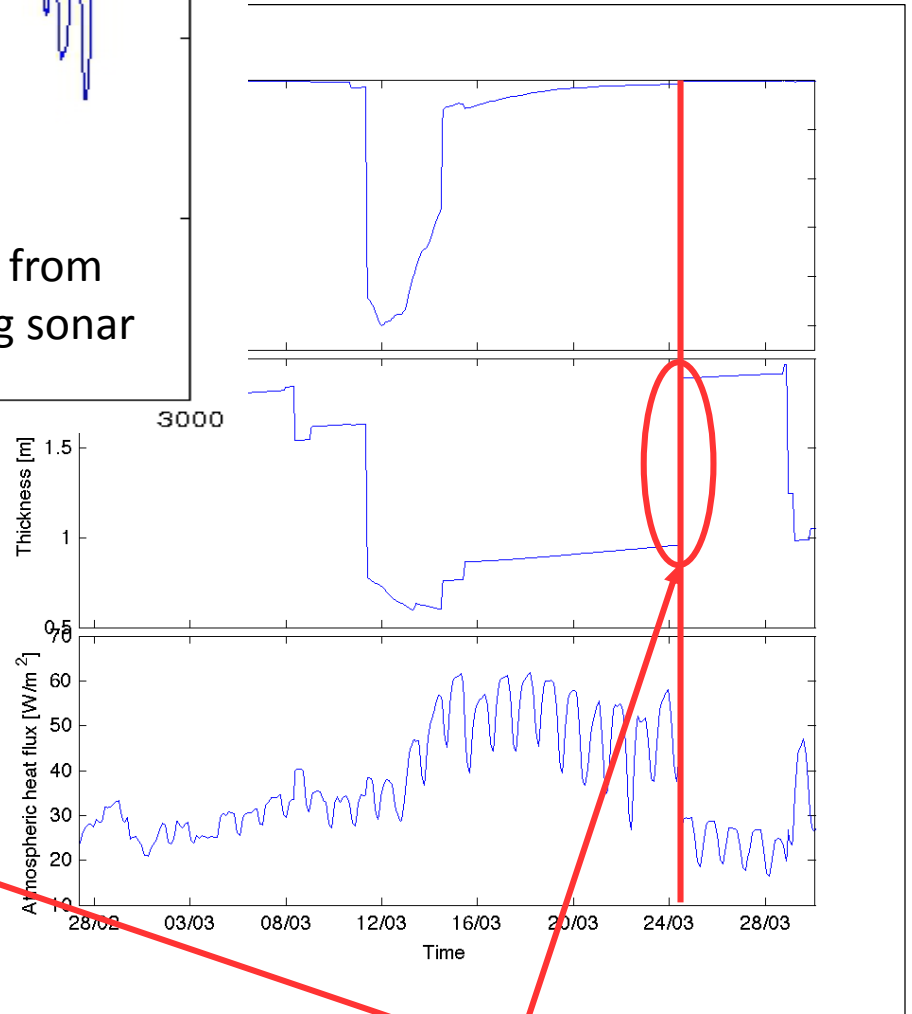
# Example from simulation

Thermodynamical closing





lation



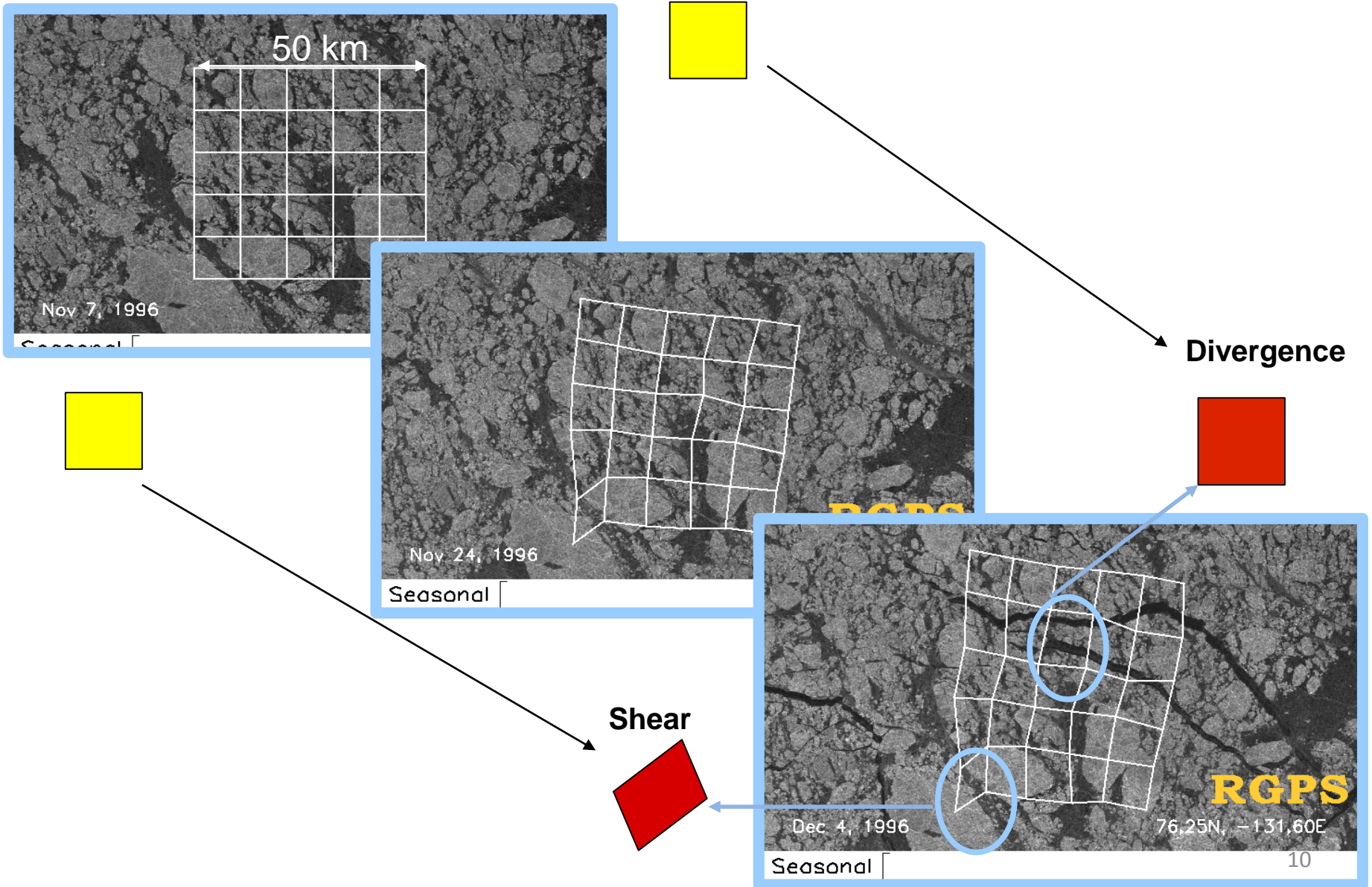
Mechanical closing



**Physical processes :**  
**Sea ice drift and deformation**

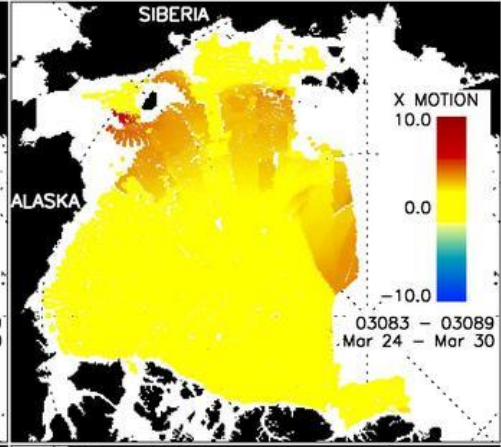
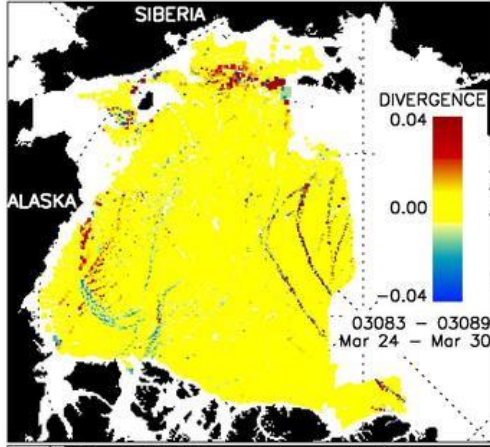
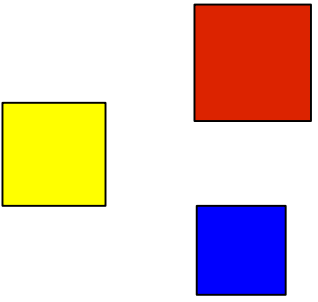
- 1. Observations** from SAR-derived drift
- 2. Simulations** from the neXtSIM sea ice model
- 3. Assimilation** for operational forecasts

# Observations from SAR-derived drift

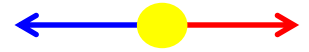


3000 km

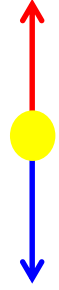
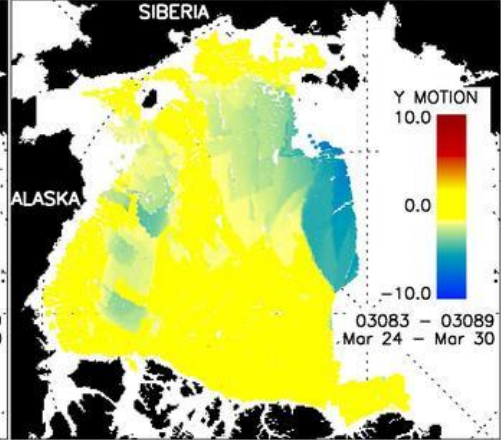
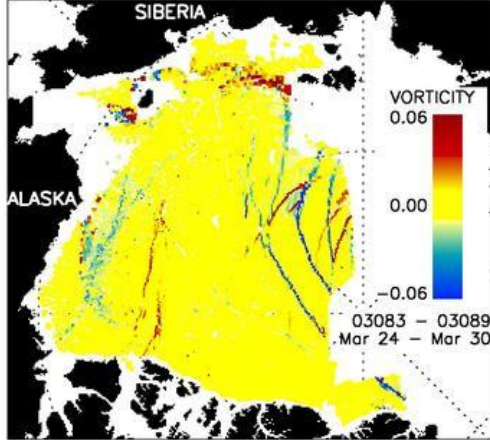
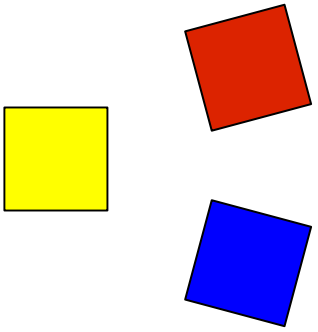
Divergence rate (/day)



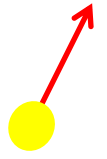
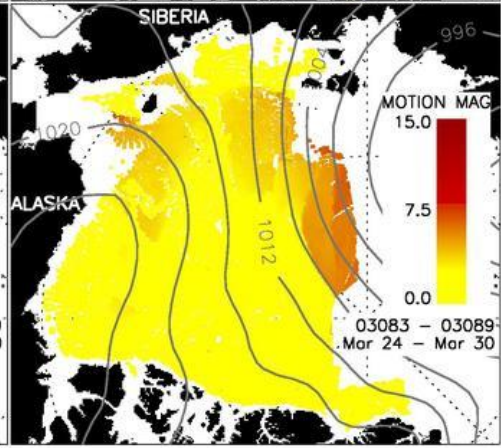
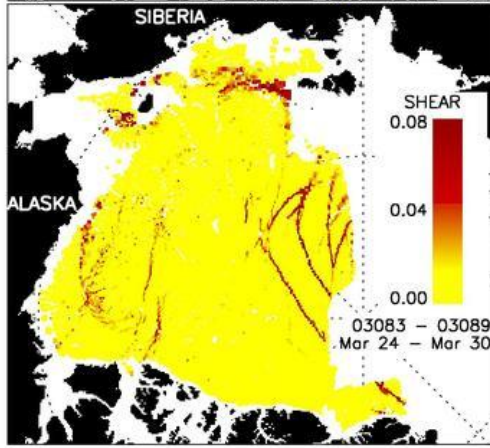
Velocity (km/day)



Vorticity (/day)

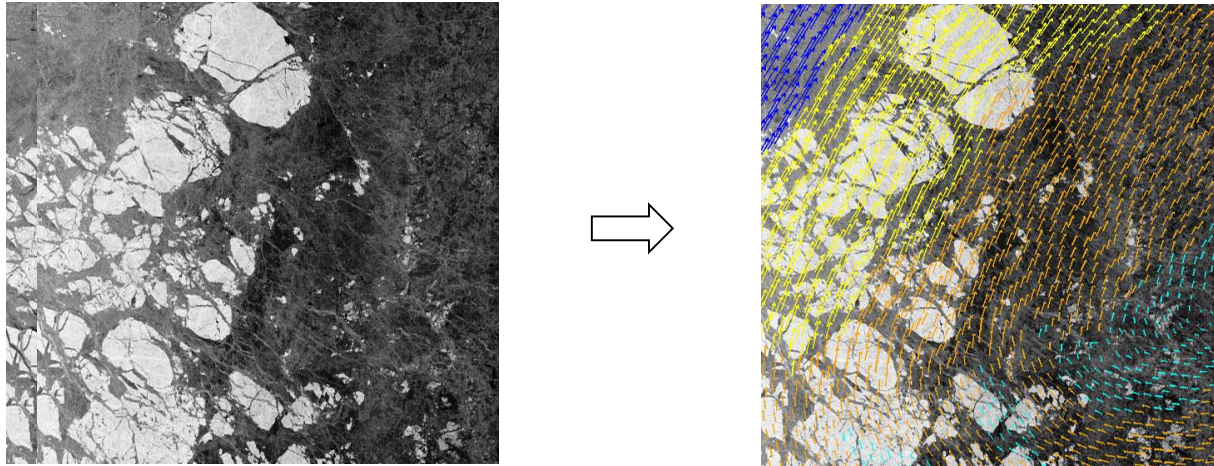


Shear rate (/day)



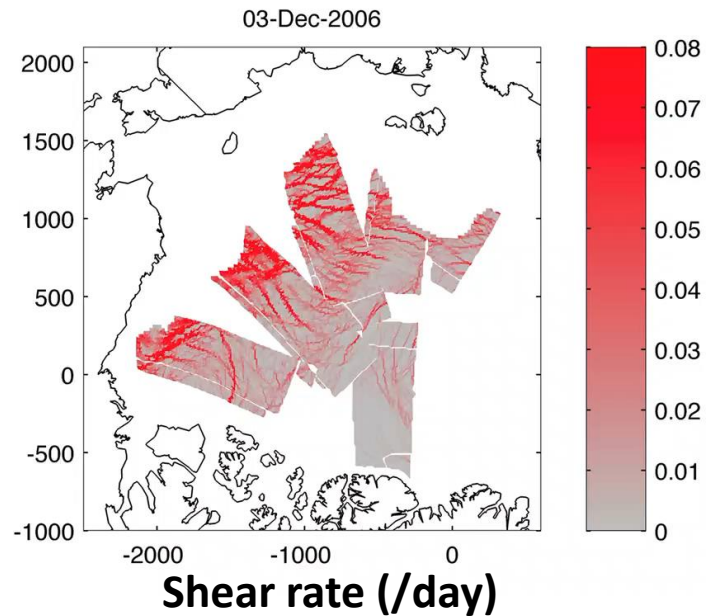
# Observations from SAR-derived drift

Level 1 product:  
**Drift**



Images courtesy: University College London

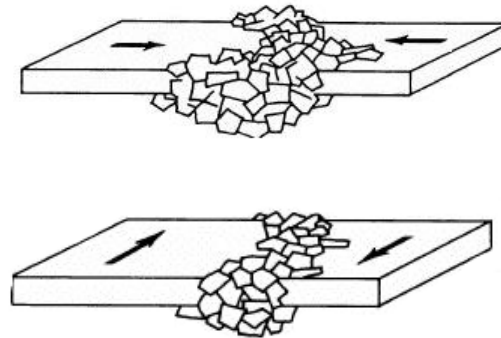
Level 2 product:  
**Deformation**



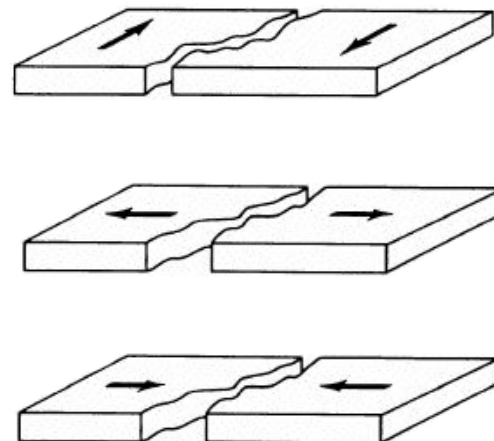
# “The sea ice thickness distribution is controlled by localized deformation events”

(Hutchings and Hibler, 2008)

## Ridging (a few hours)



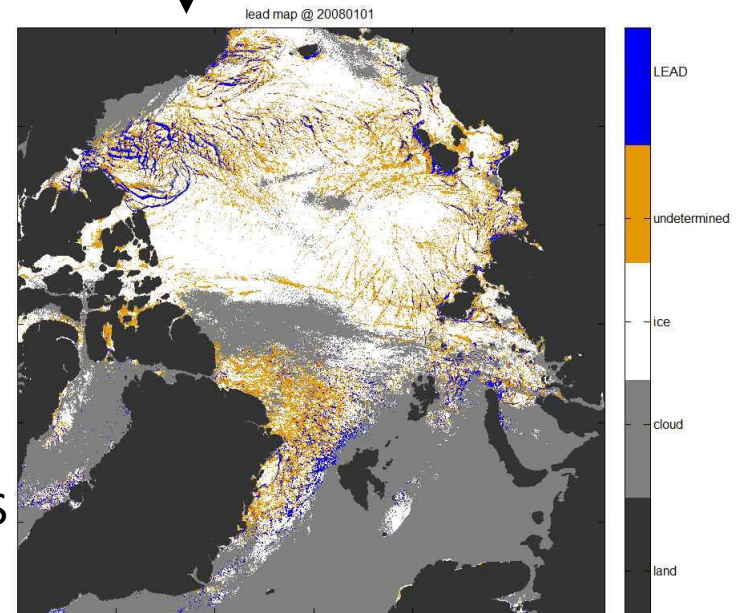
## Lead opening/closing (a few hours)



**“a change of the lead fraction by 1% could cause a near-surface air temperature signal of up to 3.5K”  
(Lüpkes et al., 2008b)**



Leads or fractures (from 1 m to 50 km)



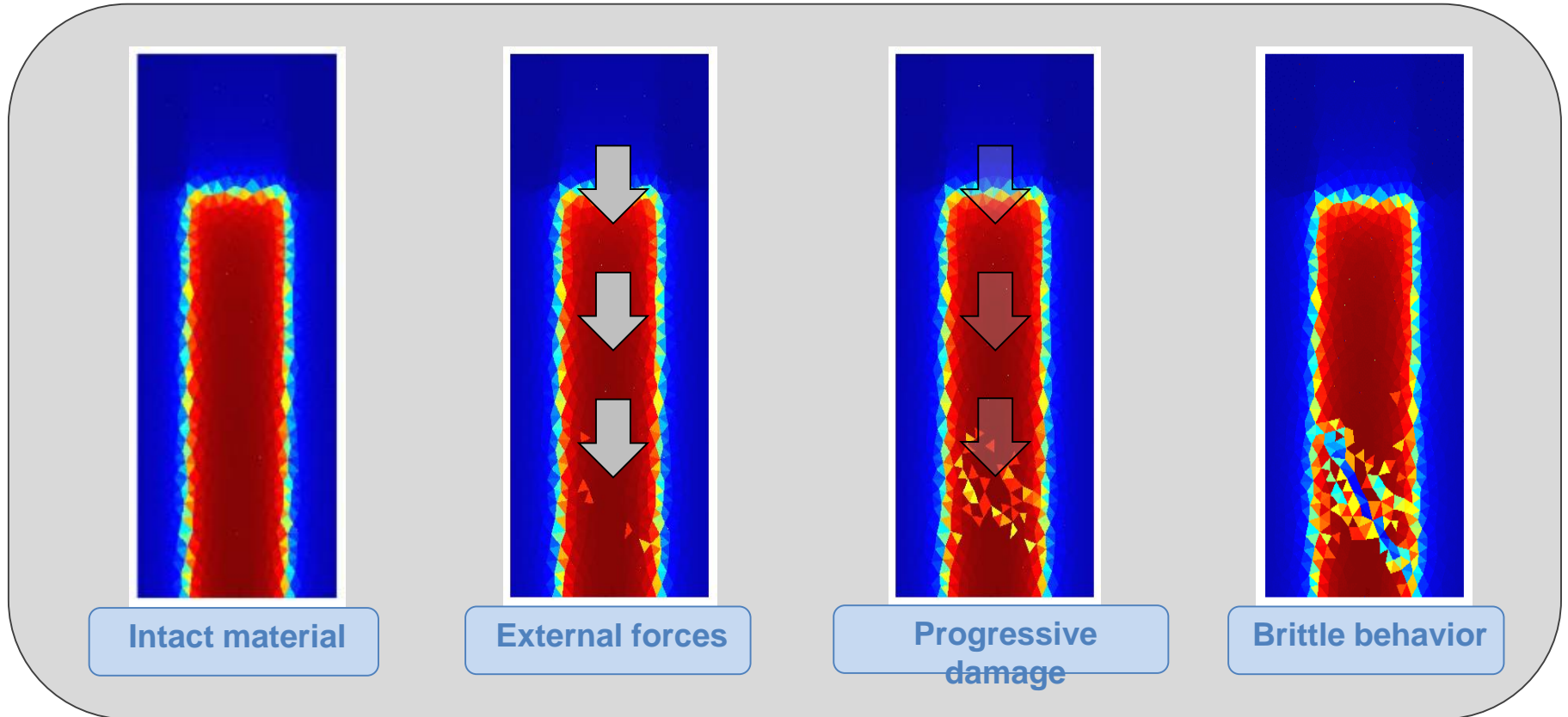
Willmes, S. and Heinemann, G. (2015)  
“Pan-Arctic lead detection from MODIS  
thermal infrared imagery”

# What is neXtSIM ?

## A simple approach...

Mechanical modeling framework **inherited from solid mechanics**

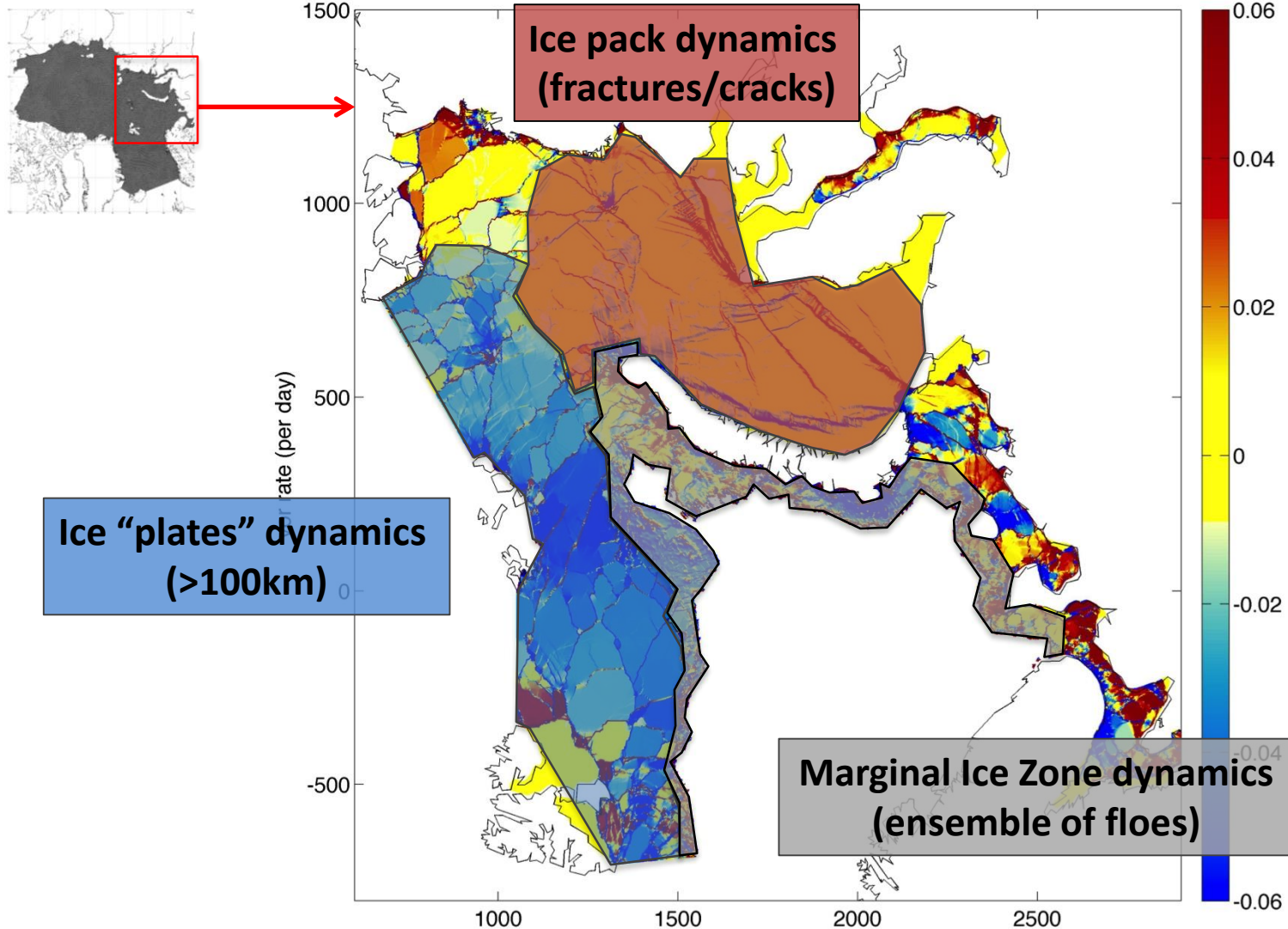
Concept:



Inspired from Amitrano et al. (1999)

# ... to produce complex behaviors

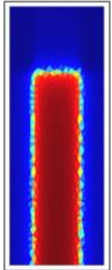
Sea ice vorticity (/day)



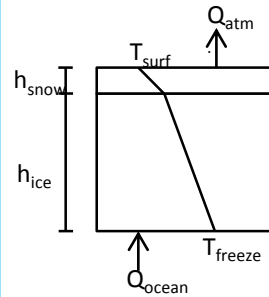


# neXtSIM at a glance

## Physics



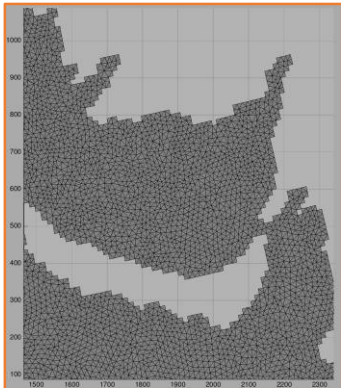
- **Dynamics: EB rheology**  
localize the deformation  
simulate ice failure



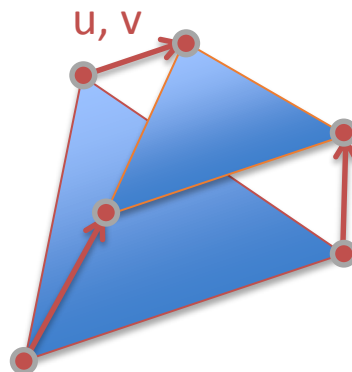
- **Thermodynamics:**  
2 ice categories, zero layer thermodynamics  
(3 categories also available)

## Numerics

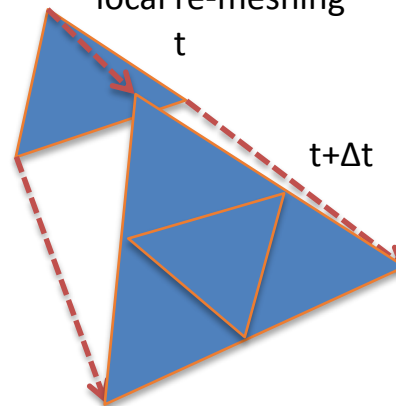
- **Unstructured grid**



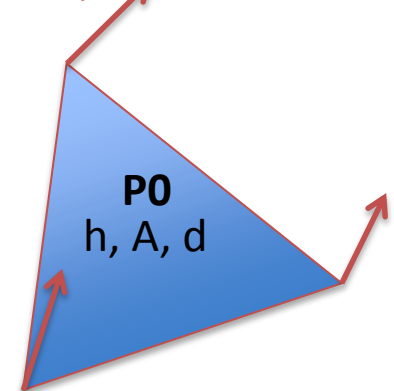
- **Fully Lagrangian**



- **Adaptive mesh**  
local re-meshing



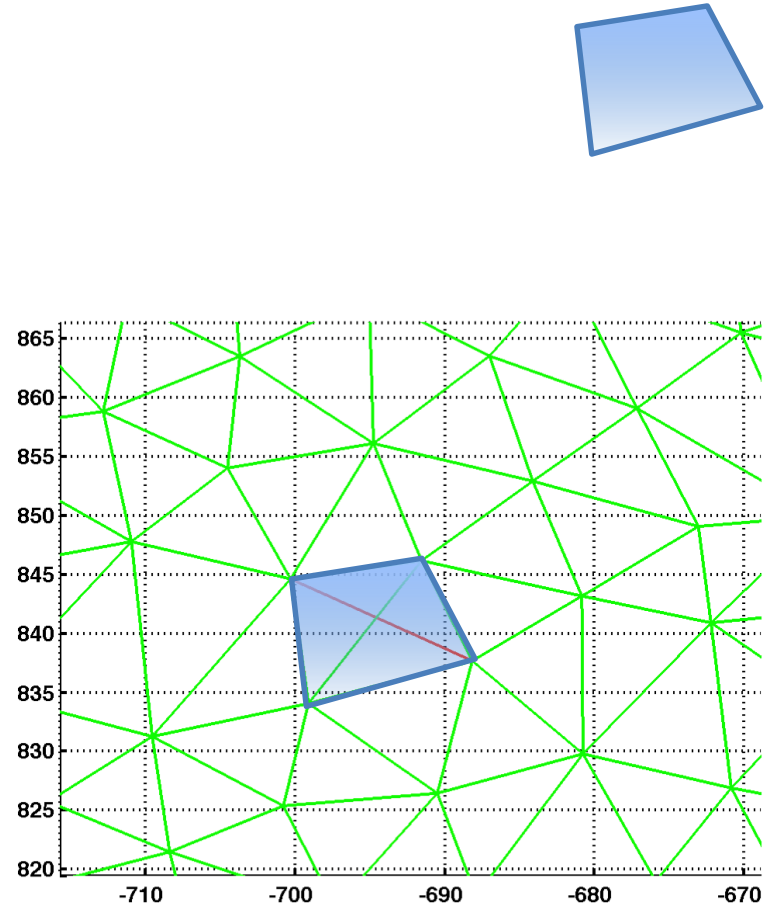
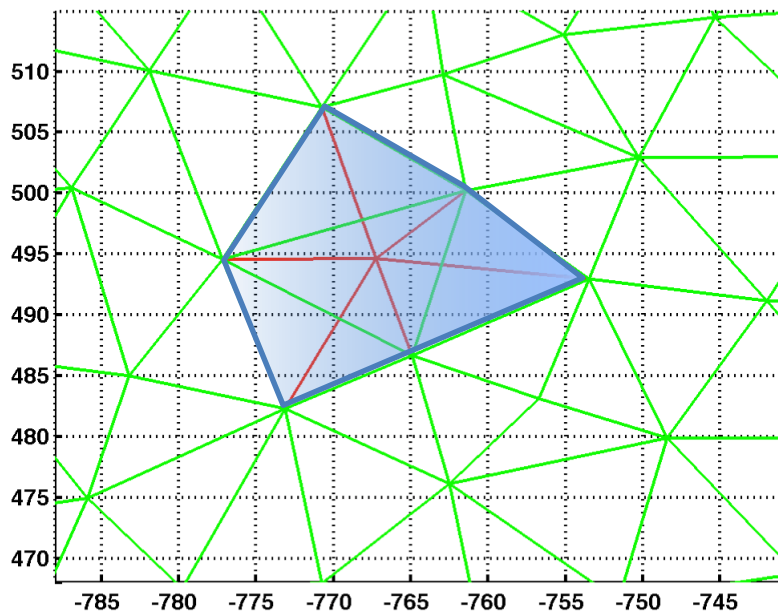
- **Finite element method**  
**P1**  $u, v$



# Conservation after the mesh adaptation

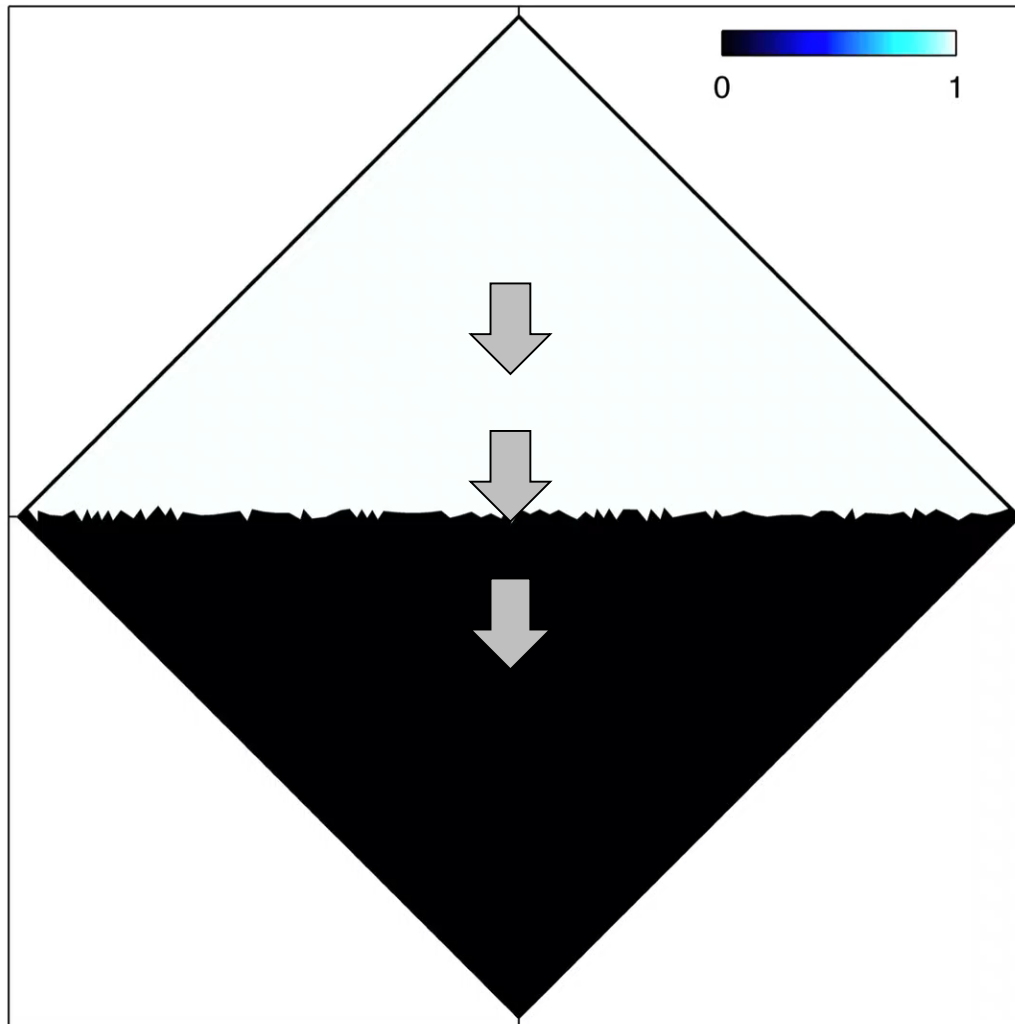
- Examples of mesh adaptation with BAMG

Adaptation are limited to small cavities

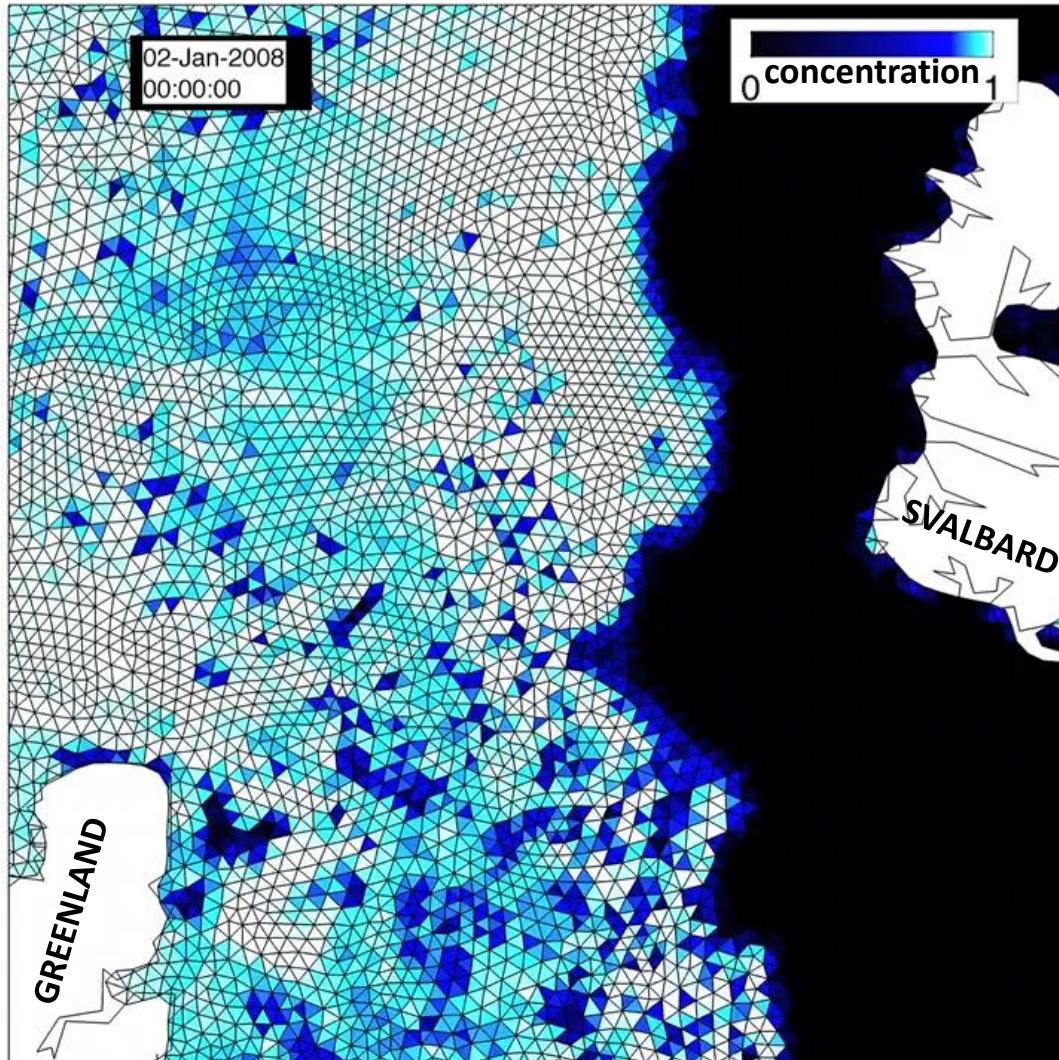
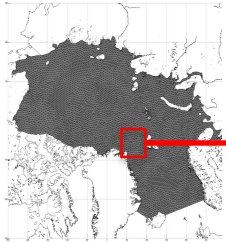


# Conservation after the mesh adaptation

- Numerical diffusion is limited

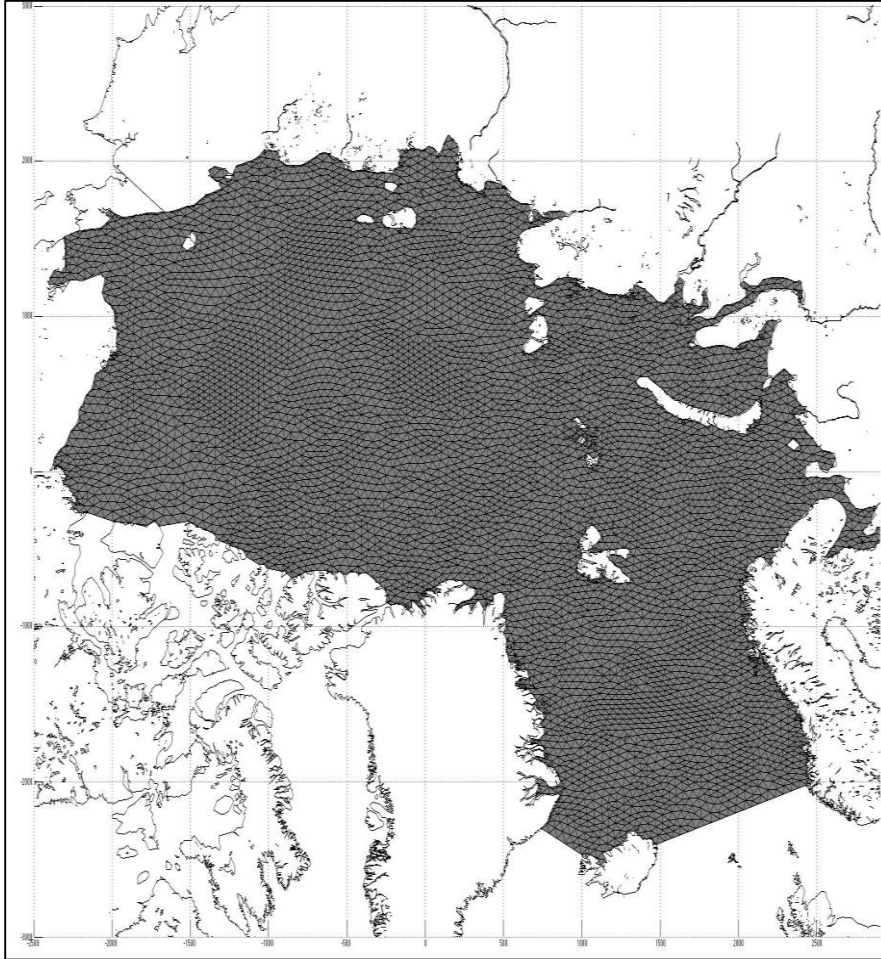


# Simulating cracks/leads in the Fram Strait (with local remeshing)



# pan-Arctic configuration

**Resolution: 7km**



**stand-alone simulation**

Jan 1<sup>st</sup> – Apr 15<sup>th</sup> 2008

**Boundary conditions:**

No slip at coasts  
open at straits

**External forcing:**

ASR winds (30km, 3-hourly)  
TOPAZ ocean currents at 30m (10km, daily)

**Initial conditions:**

Combined AMSR-E ice concentration and **lead fraction**  
TOPAZ ice thickness (modulated)

**Undamaged ice cover!**

**1 year simulation → 2days with a 2.7GHz Intel quad core i7 processor**

In neXtSIM, the ice motion looks like this...

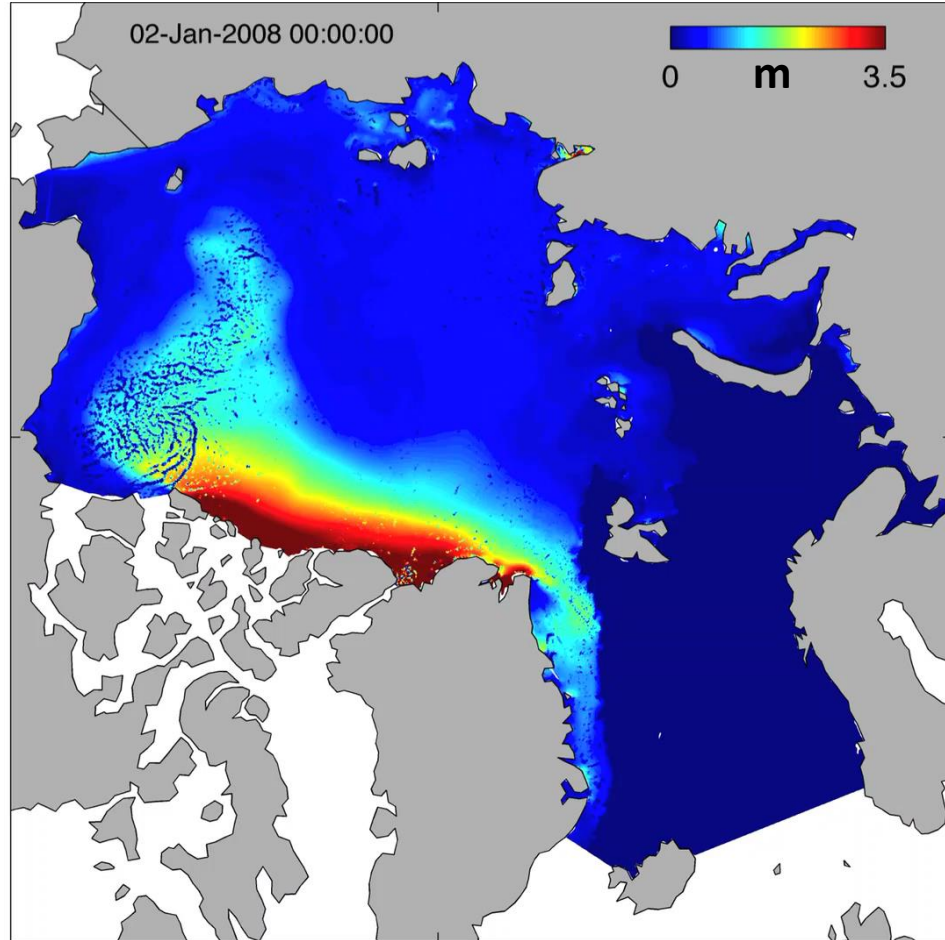
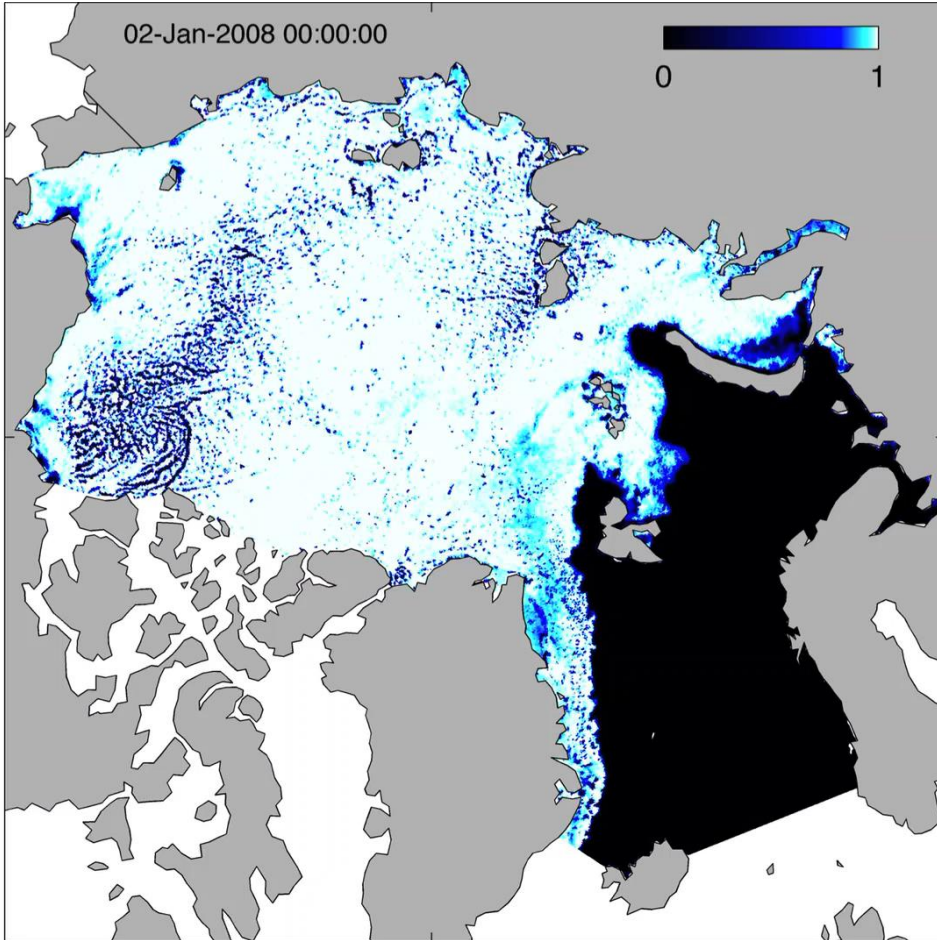


“the **ice cover concentrates gradients** in the forcing wind field into narrow bands of intense shear” (Mac Phee et al., 2005)<sup>22</sup>

# Sea ice concentration and thickness simulated by neXtSIM

ice concentration

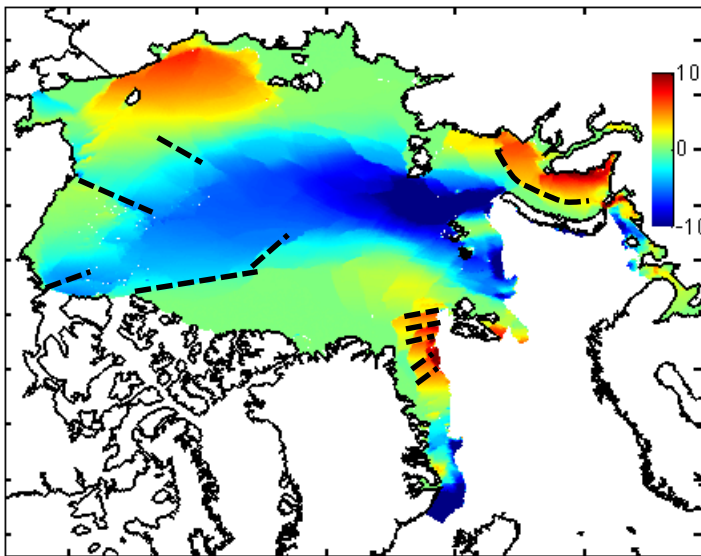
ice thickness



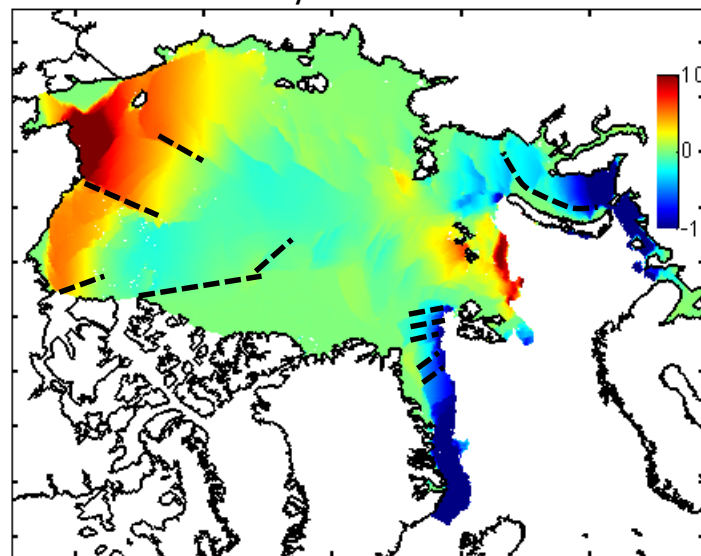
# Sea ice drift and deformation simulated by neXtSIM

Ice velocity

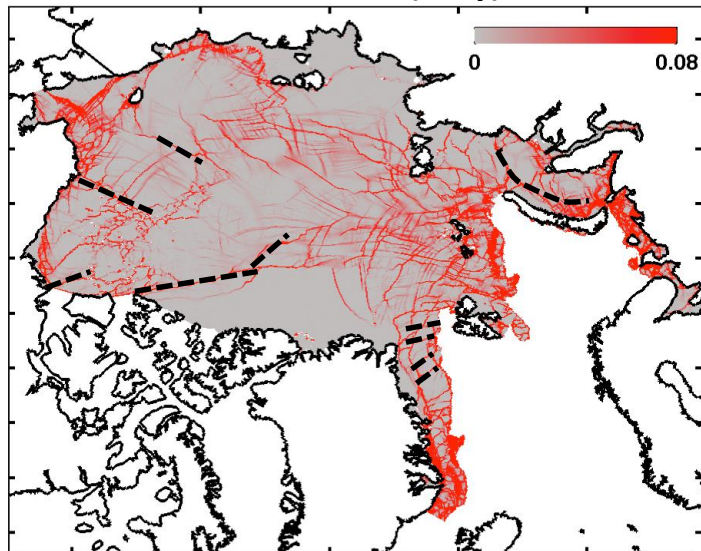
$U_x$  (km/day)



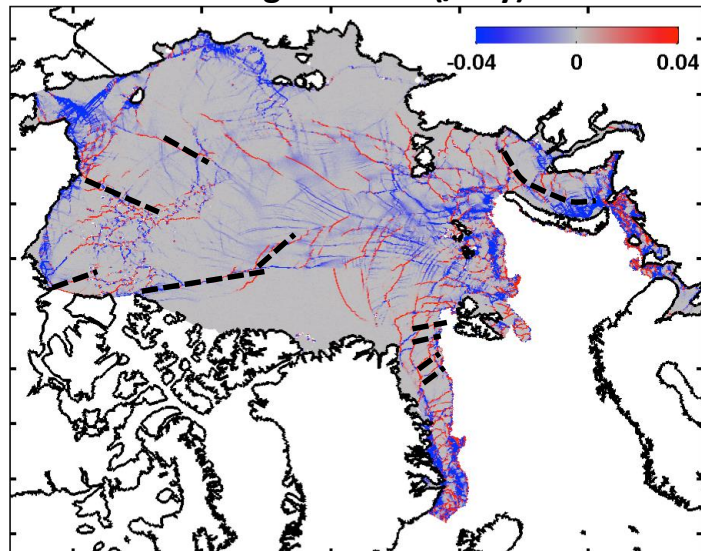
$U_y$  (km/day)



Shear rate (/day)



Divergence rate (/day)

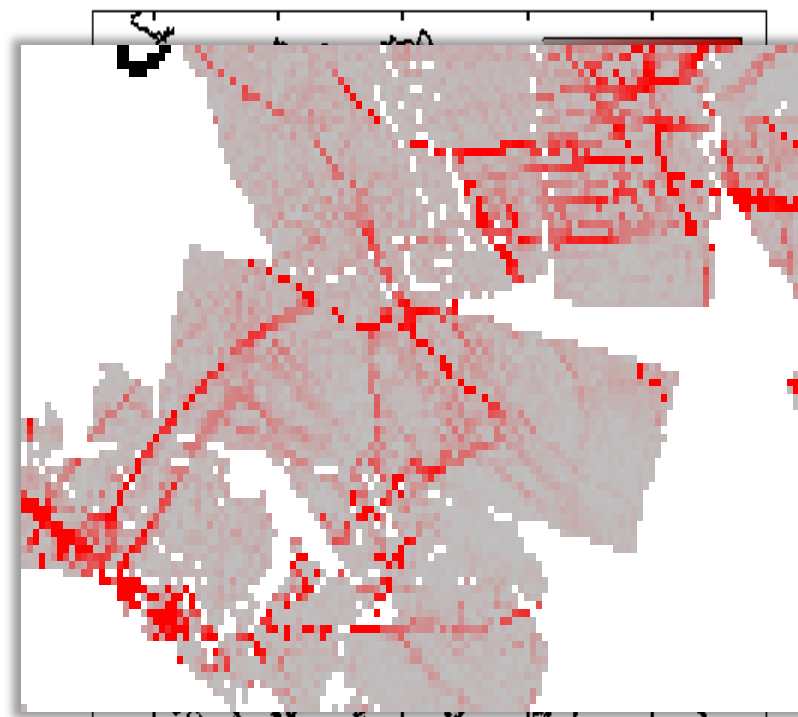
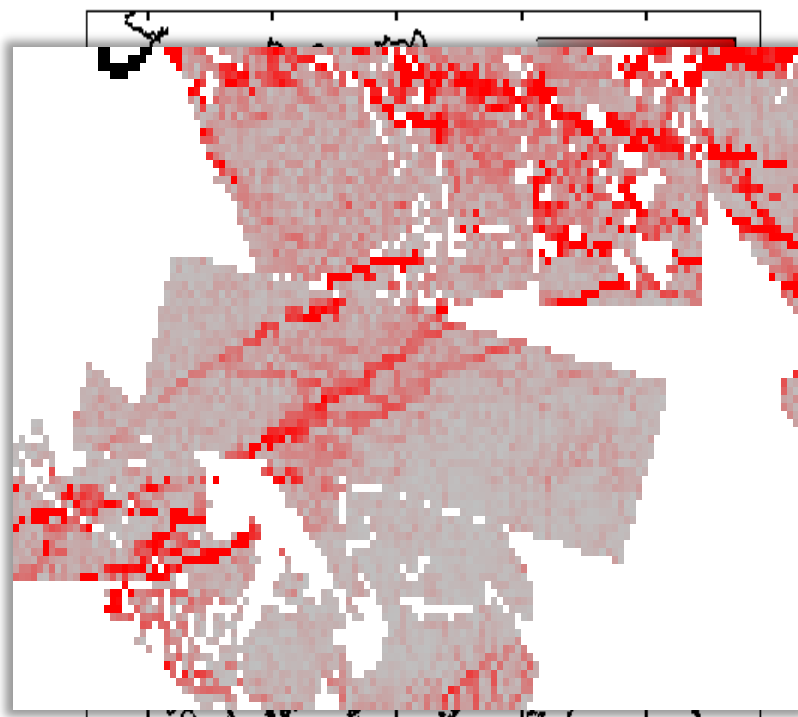


Ice Deformation

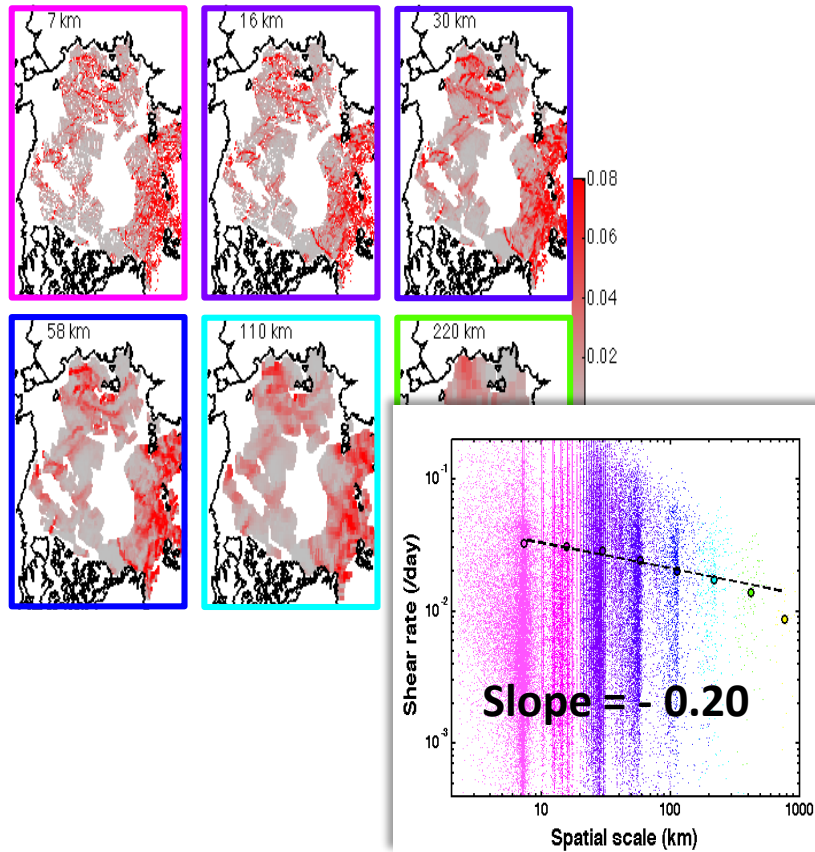


## SAR (ENVISAT & RADARSAT)

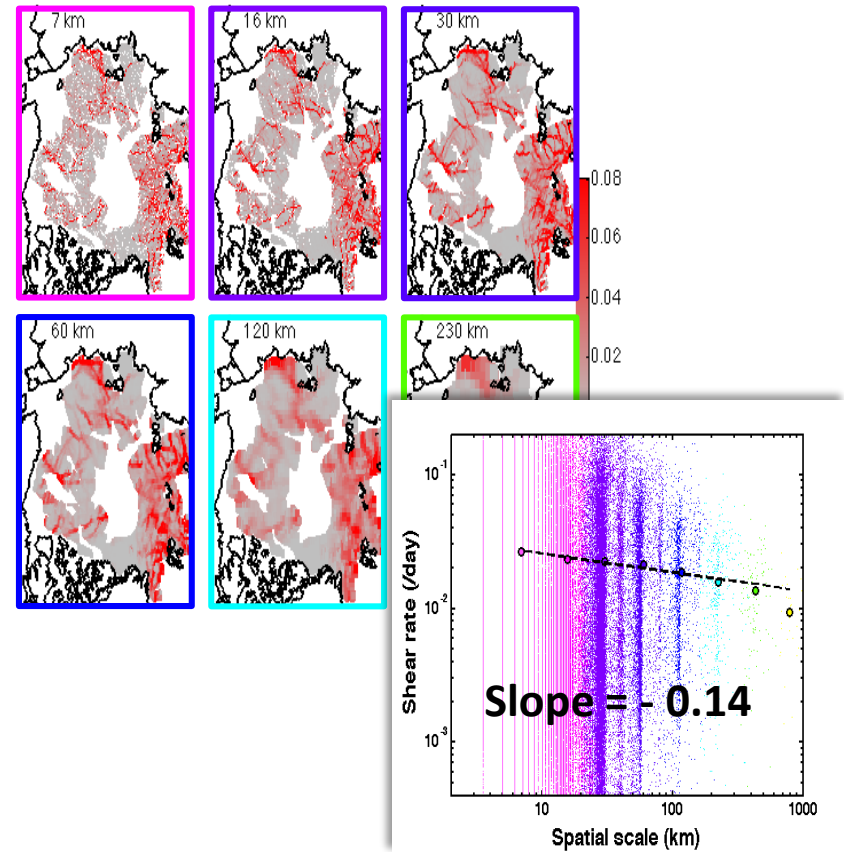
## neXtSIM



# SAR (ENVISAT & RADARSAT)

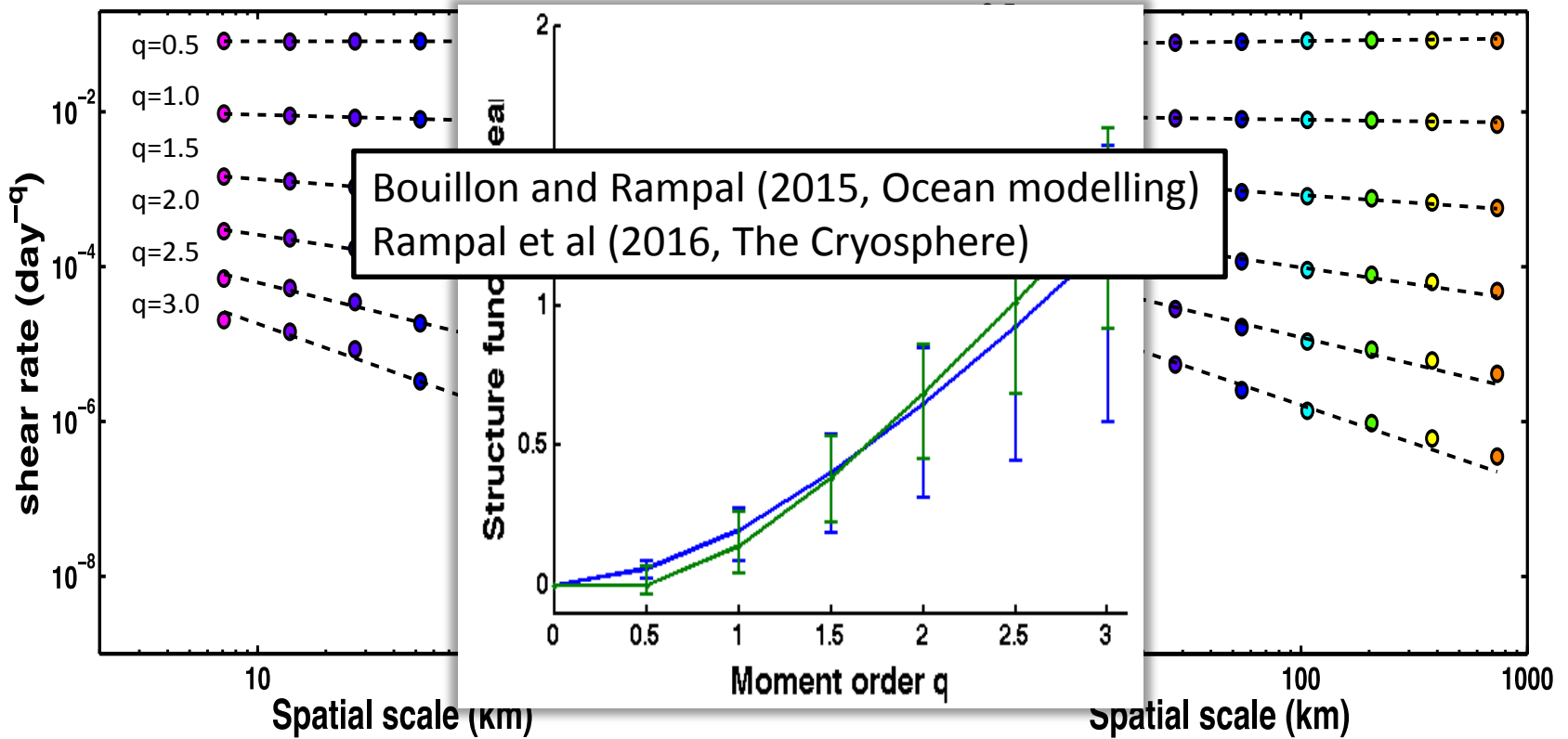


# neXtSIM

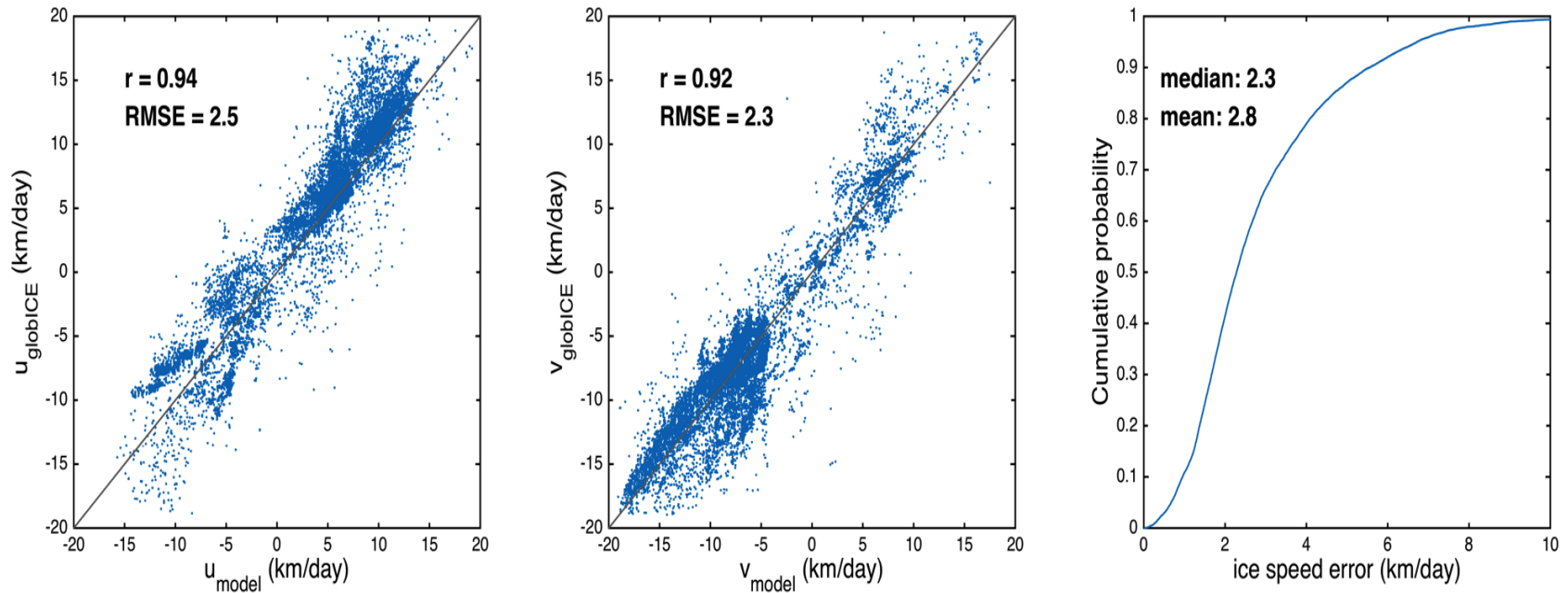


# SAR (ENVISAT & RADARSAT)

# neXtSIM

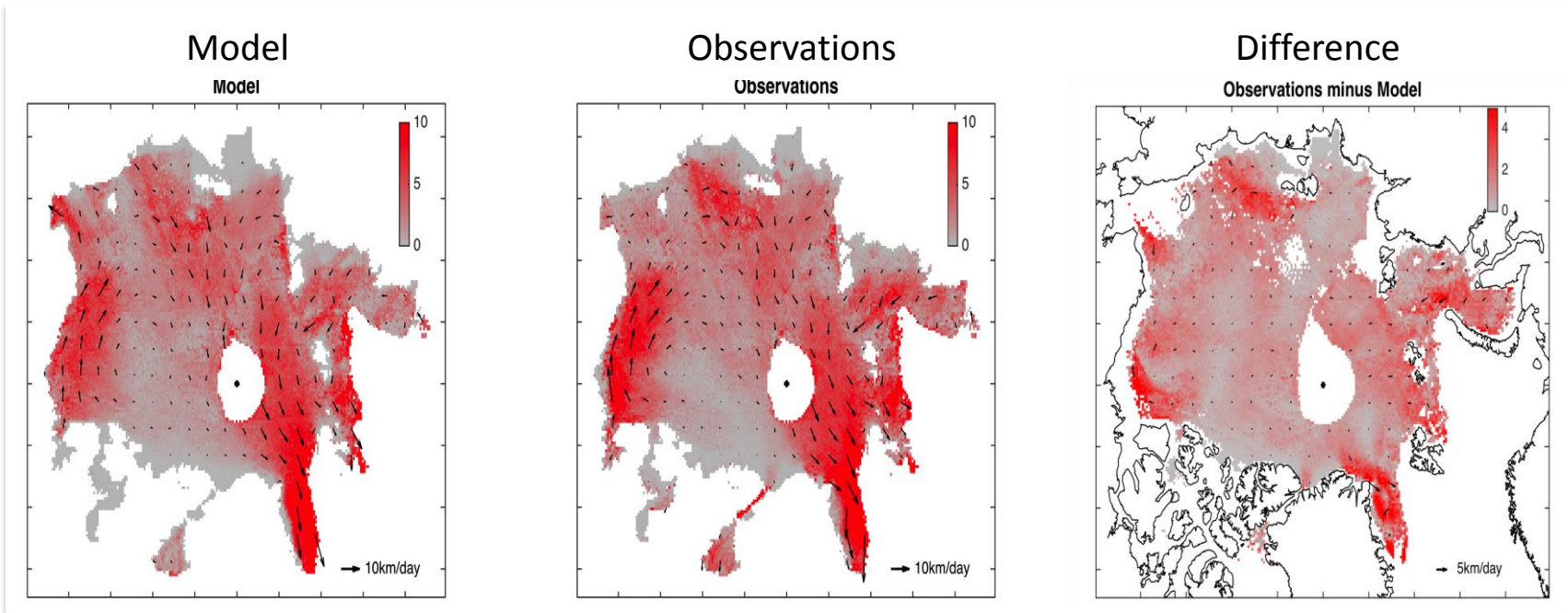


# Simulated vs. observed drift



- High correlation between simulated and observed drift
- Holds for comparison done over the entire model domain, not just free drift cases.
- No bias
- RMSE 2.4 km/day for ASR and 3.6 km/day for ERA-Interim

# Winter mean drift

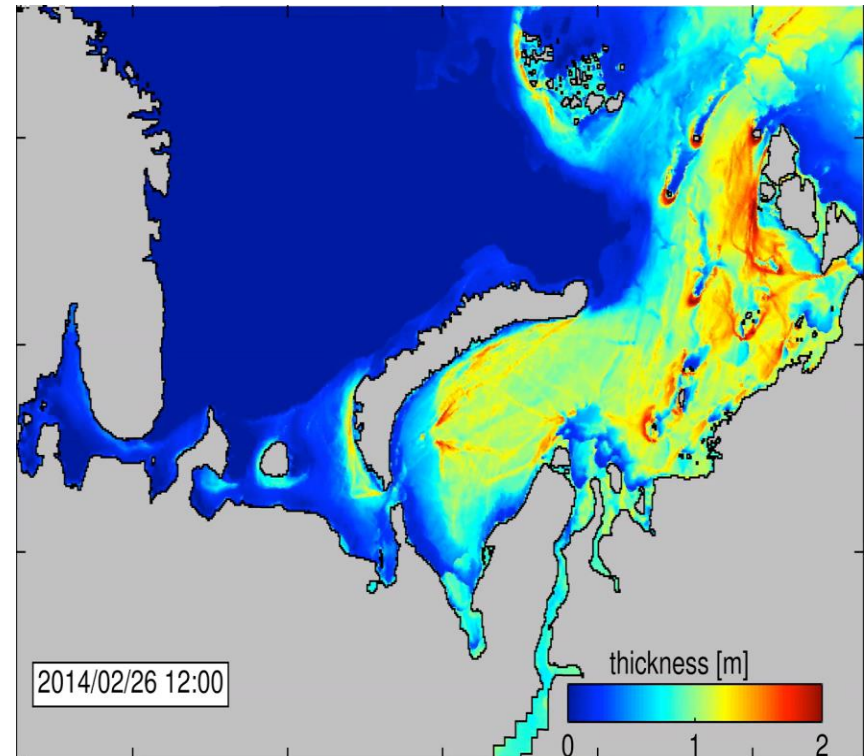



- Error below 1 km/day in most of the area
- Areas of large errors may be related to model/forcing shortcomings

Rampal et al (2016, The Cryosphere) for details

## Application for operational forecast

- neXtSIM-F is a sea ice forecast platform for the Kara Sea
- Forced by ECMWF and ARC MFC forecasts
- Assimilates
  - Concentration (AMSR2)
  - Thin ice thickness (SMOS)
- [www.nersc.no/data/neXtSIM-F](http://www.nersc.no/data/neXtSIM-F)



NERSC  **Nansen Environmental and Remote Sensing Center**  
- a non-profit climate and environmental research foundation founded in 1986.


Log In

25 years  
in science  
1986 - 2011

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Data  Search

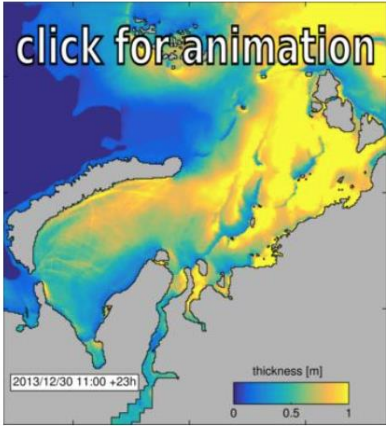
**neXtSIM-F**

 neXtSIM-F provides daily sea-ice forecasts for the Barents and Kara Seas

**Contact Person:**  
Philipp J. Griewank

**Department:**  
Mohn-Sverdrup Center for Global Ocean Studies  
and Operational Oceanography


**Animation**



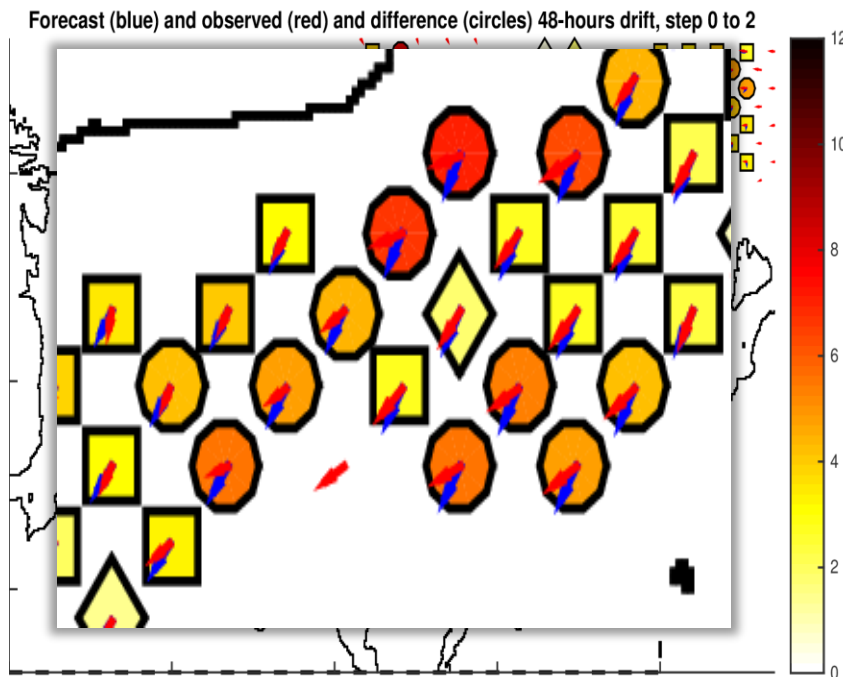
Forecasts are generated daily using neXtSIM-F on a 3km Lagrangian grid. neXtSIM-F is currently under development and is based on the neXtSIM sea ice model which is currently being developed at NERSC. The initial forecast conditions are computed by assimilating daily satellite thickness and concentration fields from SMOS and AMSR2-ASI into the previous forecast. The model is forced with ECMWF and TOPAZ forecasts of the atmosphere and ocean.

The latest forecast can be downloaded from the following ftp server <ftp://ftp.nerisc.no/pub/Philipp/forecasts>

Currently each forecast is represented by a single panel of plots depicting ice concentration, thickness, and the volume fraction of ridged ice. The arrows show the drift over the last 24 hours. Soon more output will be included, such as ice stress and drift convergence. If you are interested in a specific aspect feel free to contact us.

We would like to to thank TOTAL who have helped fund the development of neXtSIM-F. 

# OSI SAF drift comparison

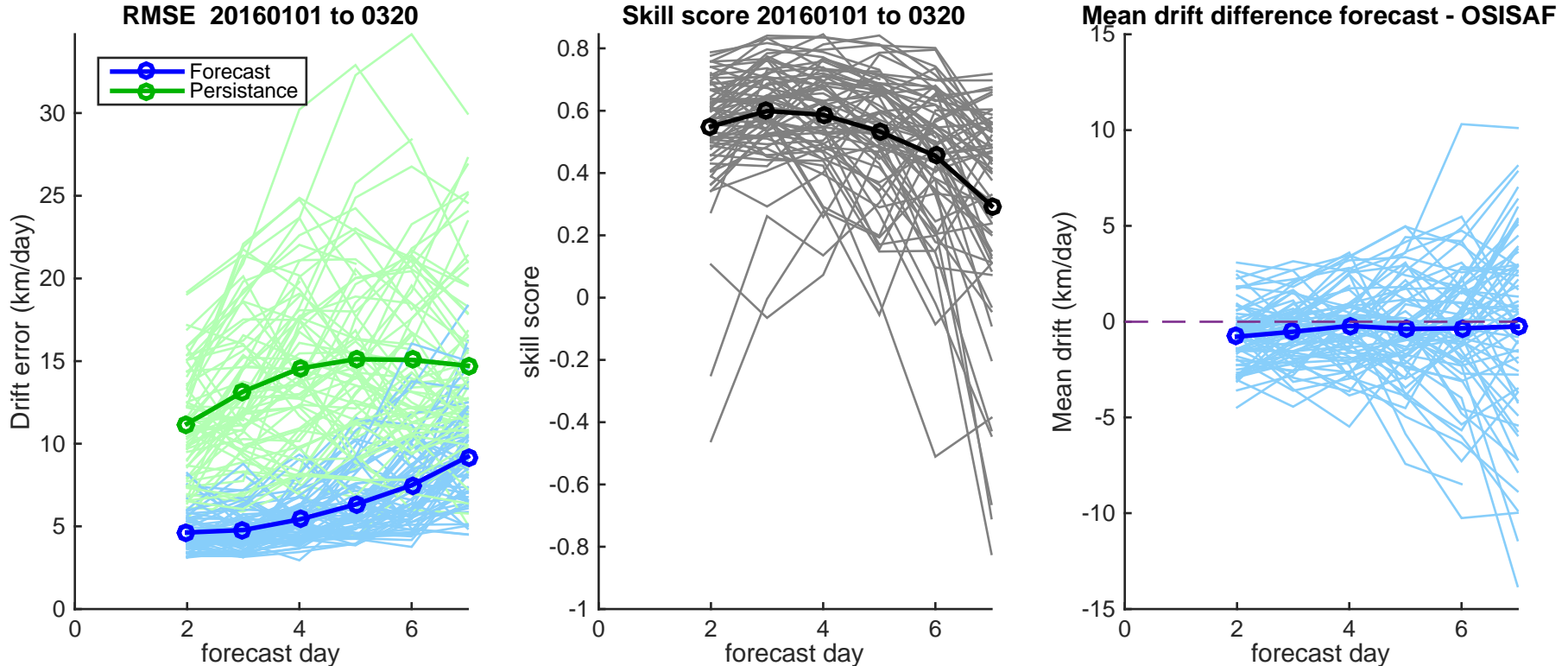


- Forecast evaluation
  - AMSR2 concentration
  - SMOS thin ice thickness
  - OSI SAF ice drift
- Daily forecast and evaluation

[www.nersc.no/data/nextsim-f](http://www.nersc.no/data/nextsim-f)



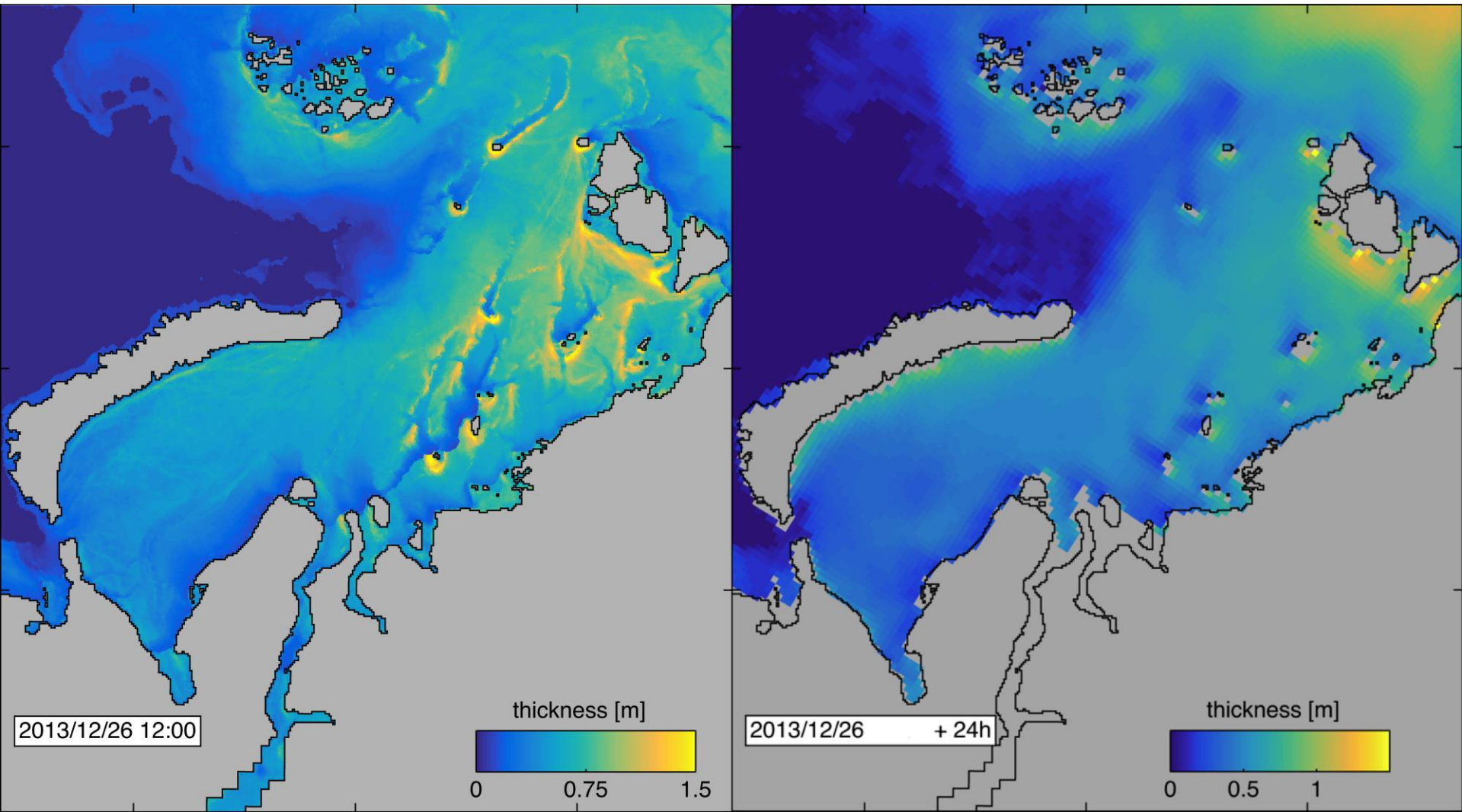
# OSI SAF drift comparison



- Forecast has skill throughout forecast period, partially thanks to weak persistence forecast.
- Time increase in forecast error is mostly due to errors of ECMWF forecast
- Mean drift speed matches well

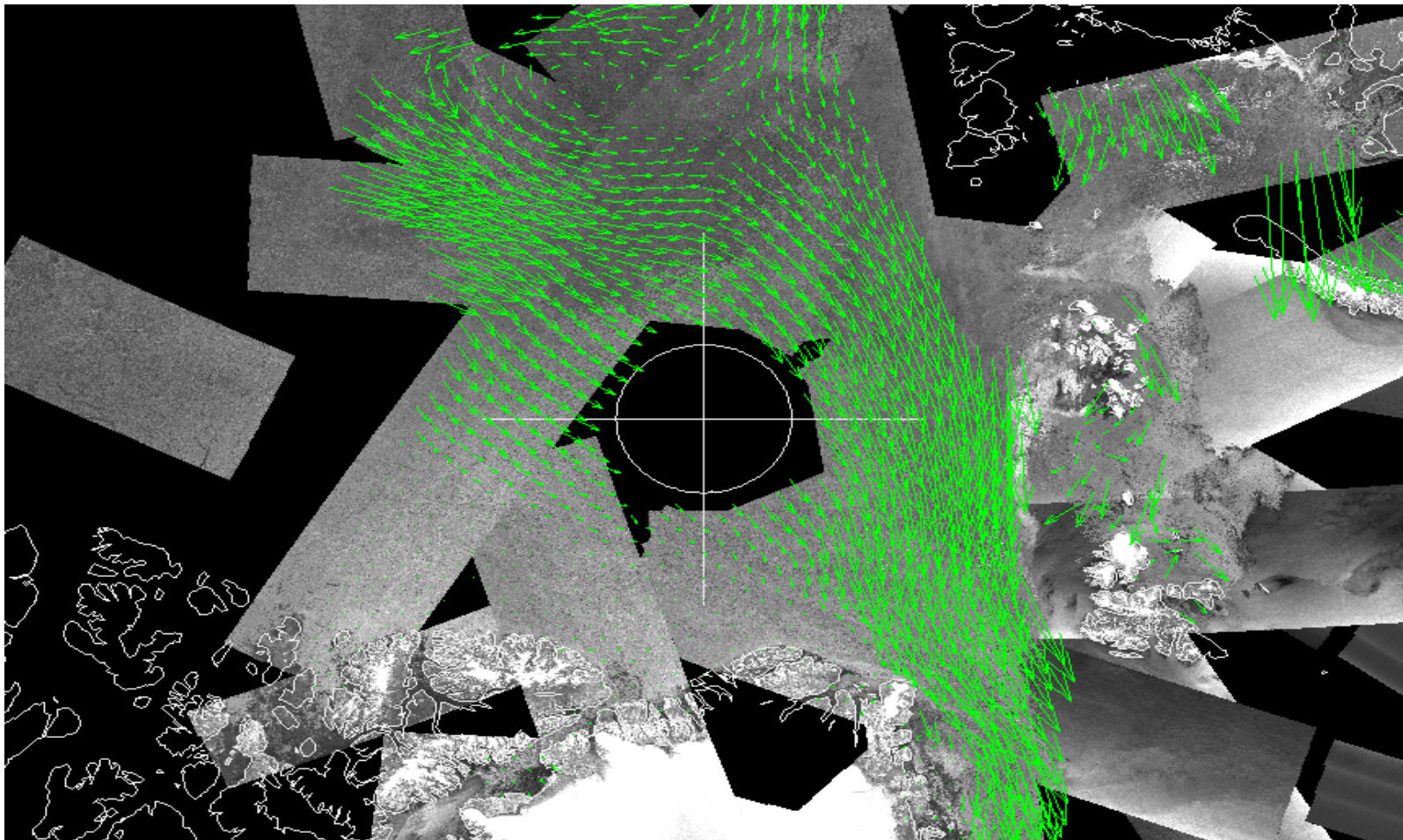
# neXtSIM-F vs TOPAZ

neXtSIM-F thickness is more heterogeneous than TOPAZ.



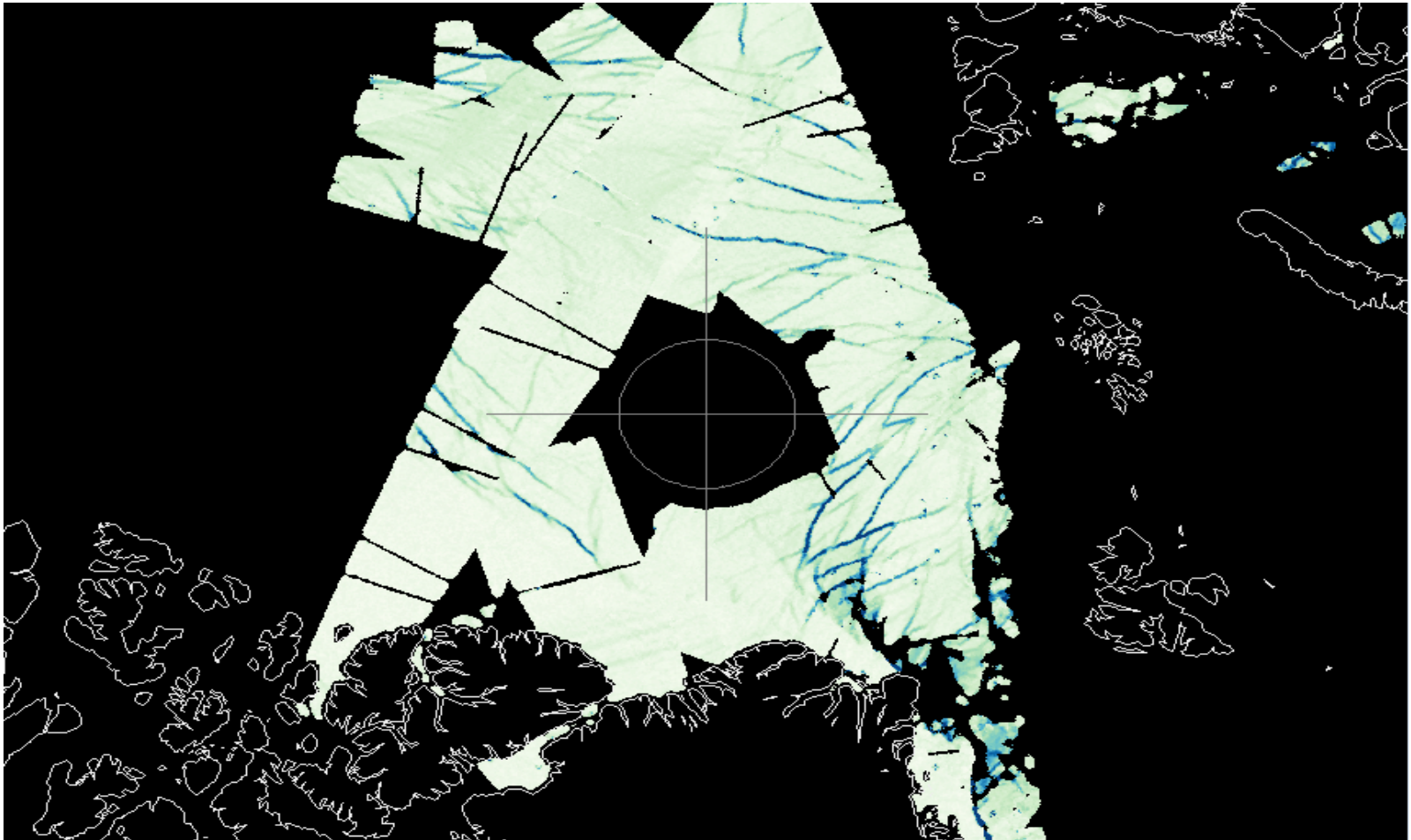
# Data assimilation of sea ice drift and deformation

Operational products: daily sea ice drift from Sentinel satellites  
(DTU, Copernicus Marine Service)



2016-02-28

# Data assimilation of sea ice drift and deformation



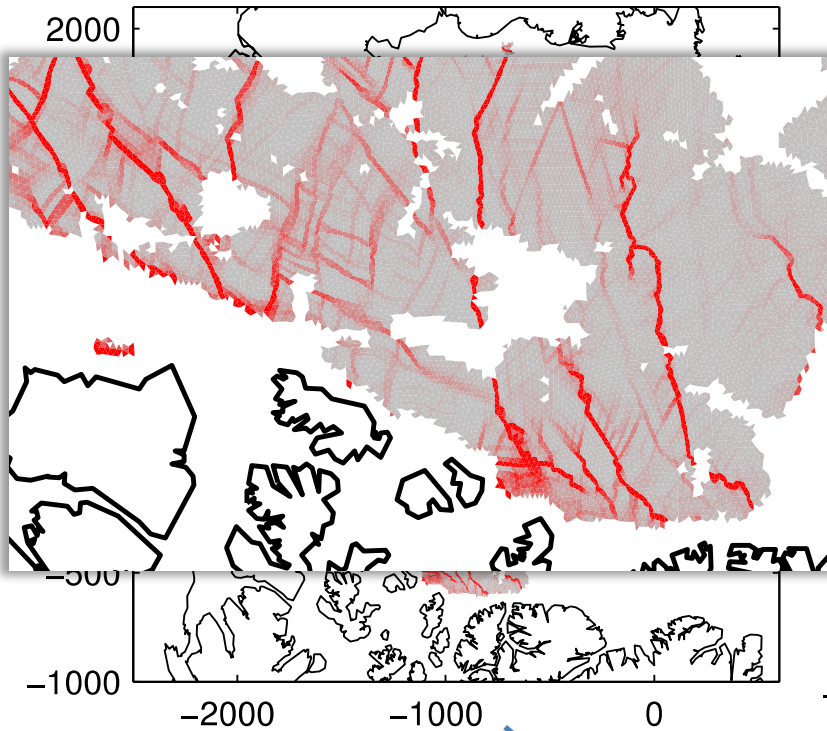
2016-02-27 ->28 Shear rate

From more than 500.000 ice drift vectors at 2 km spacing

# Data assimilation of sea ice drift and deformation

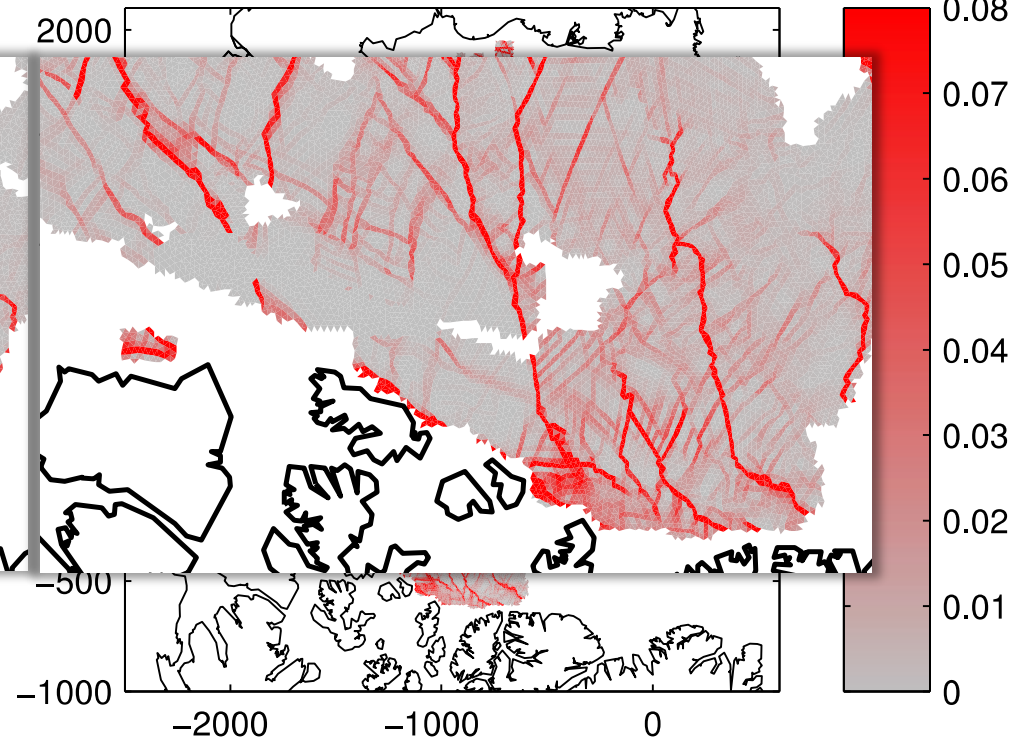
**Observed shear rate (/day)**

27–30 March 2007

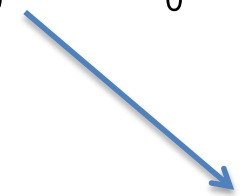


**Simulated shear rate (/day)**

27–30 March 2007



**“Only damaged  
sea ice deforms”**



**Damage field**



**Initial conditions  
for the simulation**

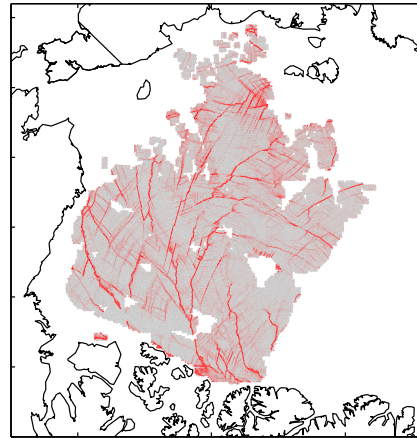
# Conclusions and perspectives

## Modelling

- Coupling with the atmosphere (weather forecast, feedback,...)
- Coupling with the ocean (inertial oscillation, enhanced fluxes, waves...)
- Sub-grid scale parameterizations

## Observations

- Operationalization
- Track the discontinuities
- Link deformation, thickness and lead datasets



## Data assimilation

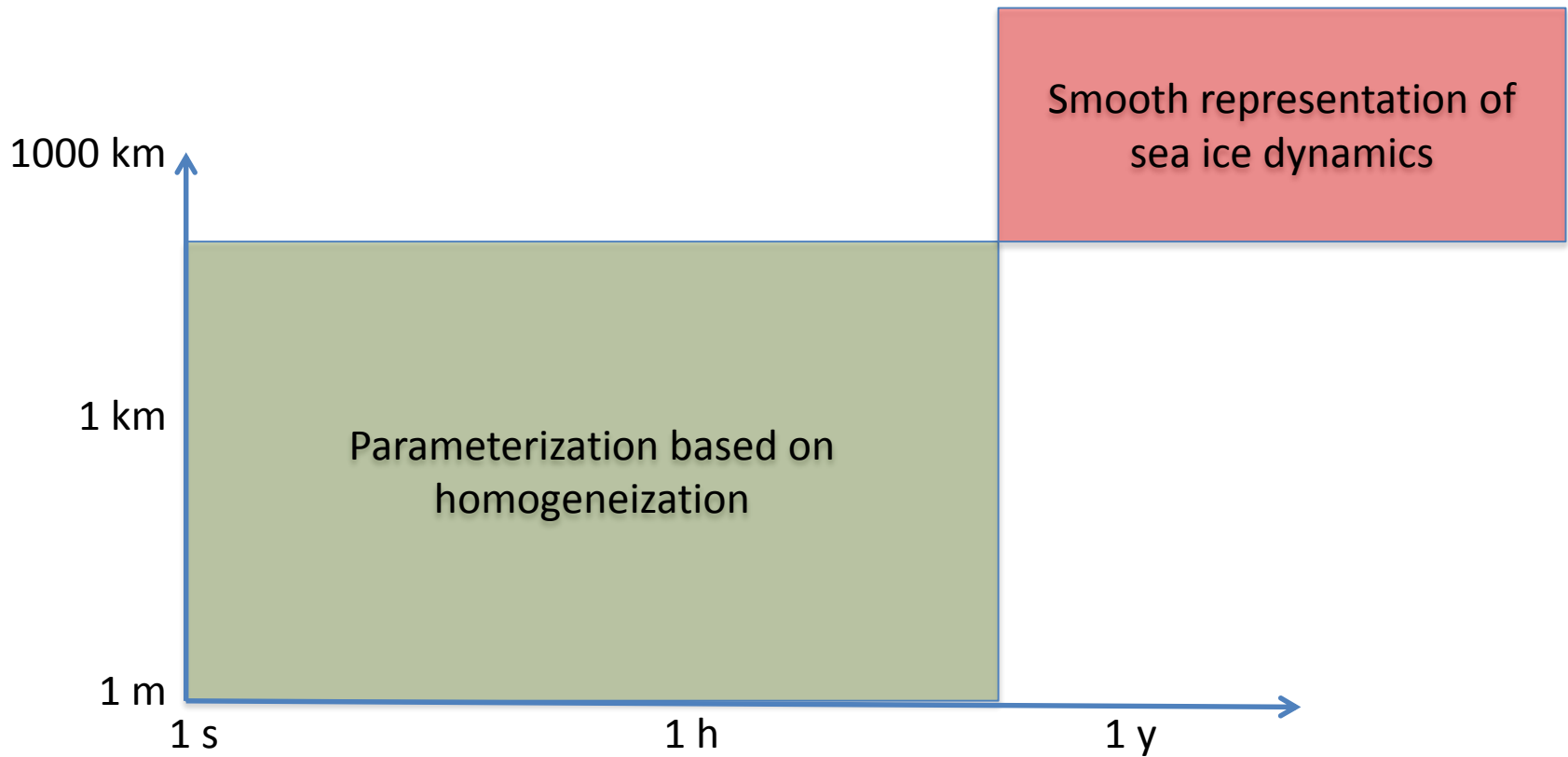
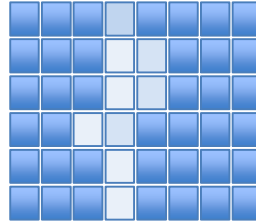
- Assimilation of sea ice drift and deformation
- Assimilation of sea ice thickness data (CrySat and SMOS)

List of the on-going projects on: [www.nersc.no/group/sea-ice-modelling](http://www.nersc.no/group/sea-ice-modelling)  
[www.nersc.no/group/data-assimilation](http://www.nersc.no/group/data-assimilation)



Classical sea ice models parameterize most of the processes of interest.

- **Classical continuous Eulerian model**  
with increased resolution





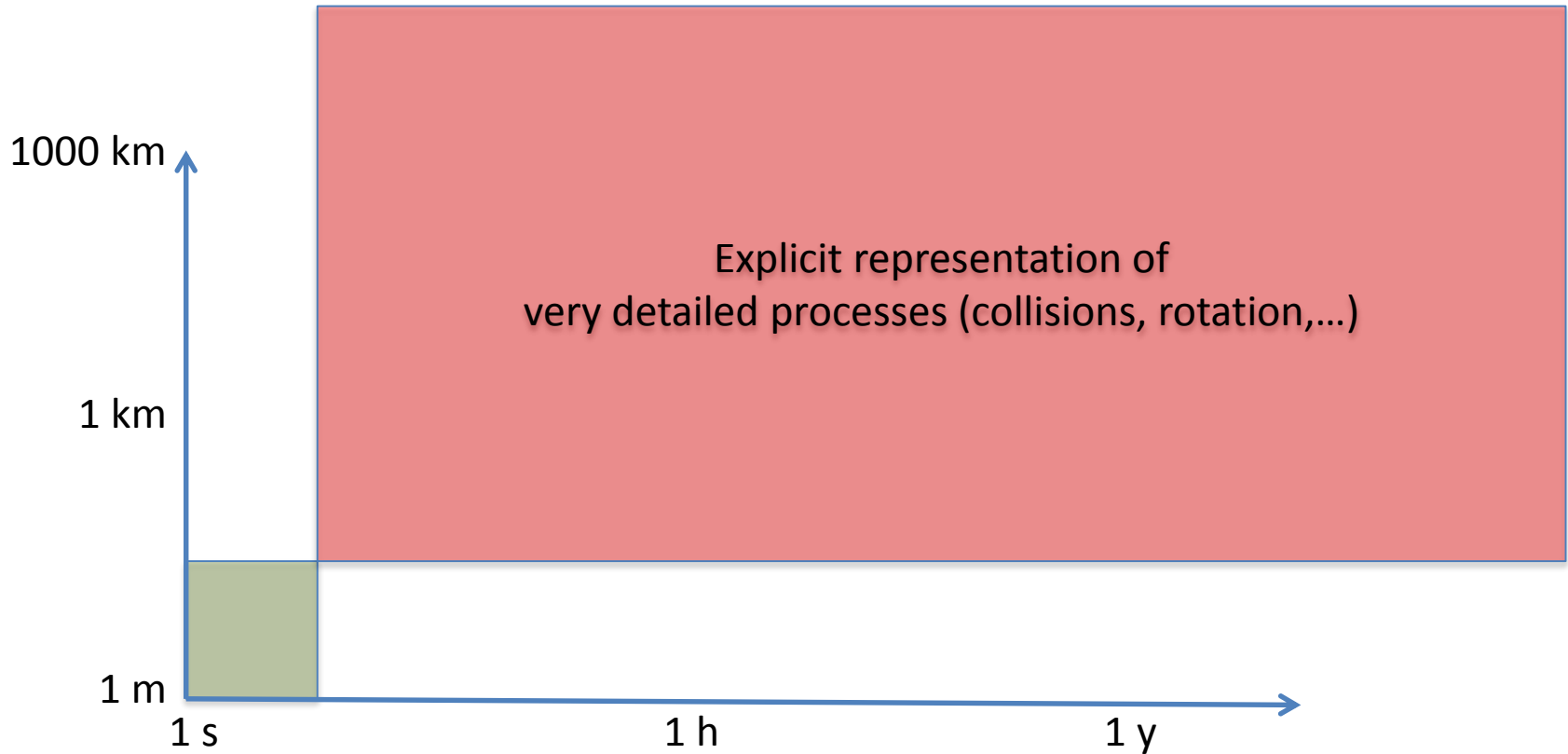
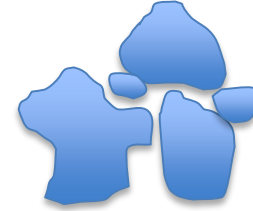
Discrete sea ice models are maybe not suited for long simulations on large domains.

- **Discrete model**

- with simplistic or realistic shapes

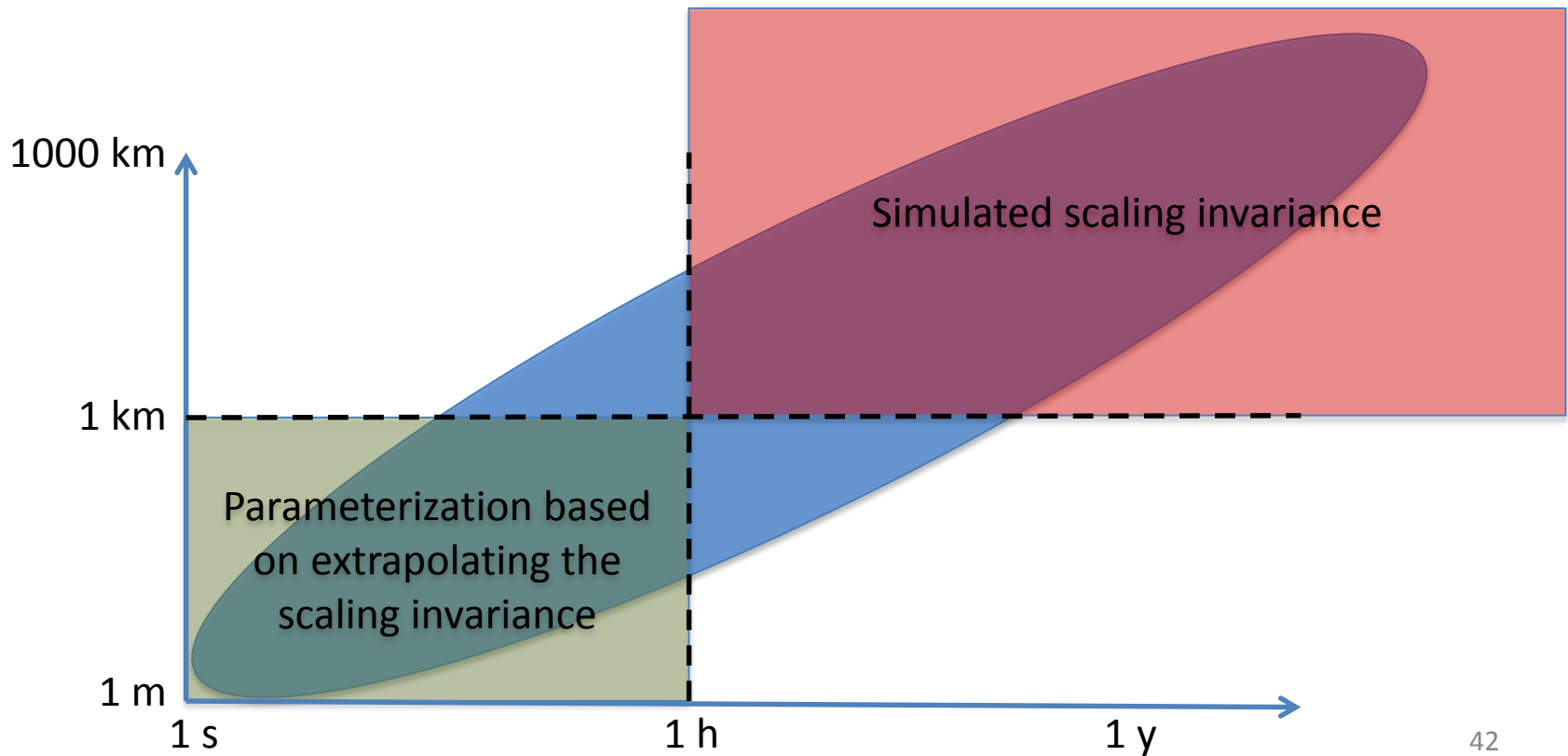
- with refreezing/breaking of the floes

- with a precise representation of the collisions



neXtSIM reproduces the scaling invariance down to its nominal resolution

- Sea ice models should **simulate and/or parameterize** deformation scaling.



# Drag optimisation

- The momentum equation of sea ice is

$$\rho_i h \frac{D\mathbf{u}_i}{Dt} = \nabla \cdot (\boldsymbol{\sigma}h) + A(\boldsymbol{\tau}_a + \boldsymbol{\tau}_w) - \rho_i h f \mathbf{k} \times \mathbf{u}_i - \rho_i h g \nabla \eta$$

Inertial term

Internal force

Drag terms

Coriolis force

Ocean tilt term

- In free drift we can ignore most terms, giving:

$$\mathbf{u}_i = \mathbf{u}_w + \mathbf{u}_a Na$$

$\mathbf{u}_i$  is ice velocity  
 $\mathbf{u}_w$  is water velocity  
 $\mathbf{u}_a$  is wind velocity

Nansen number