



Developing a km-scale model system over the Alpine arc

HPC and other challenges

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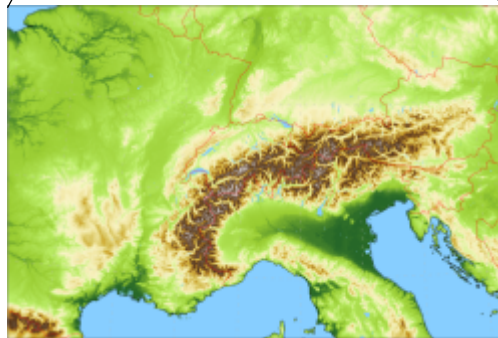
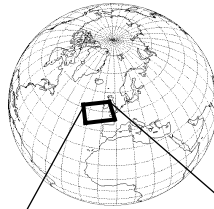
⁸University of Innsbruck

Greyzone Workshop, ECMWF, November 13-16, 2017



Operational system since 2016

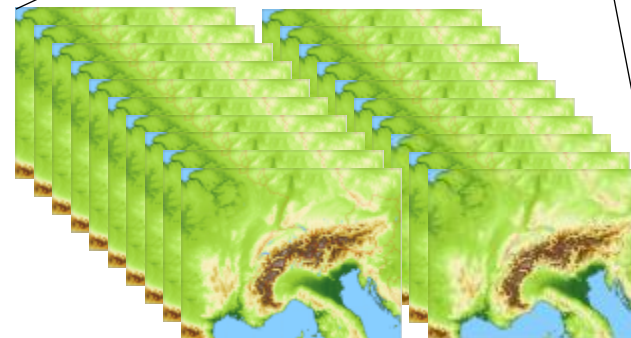
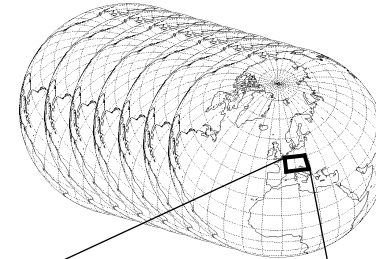
IFS HRES



COSMO-1

1.1 km gridsacing
8 x per day
+33h forecast
deterministic

IFS ENS



COSMO-E

2.2 km gridsacing
2 x per day
+5d forecast
21 members

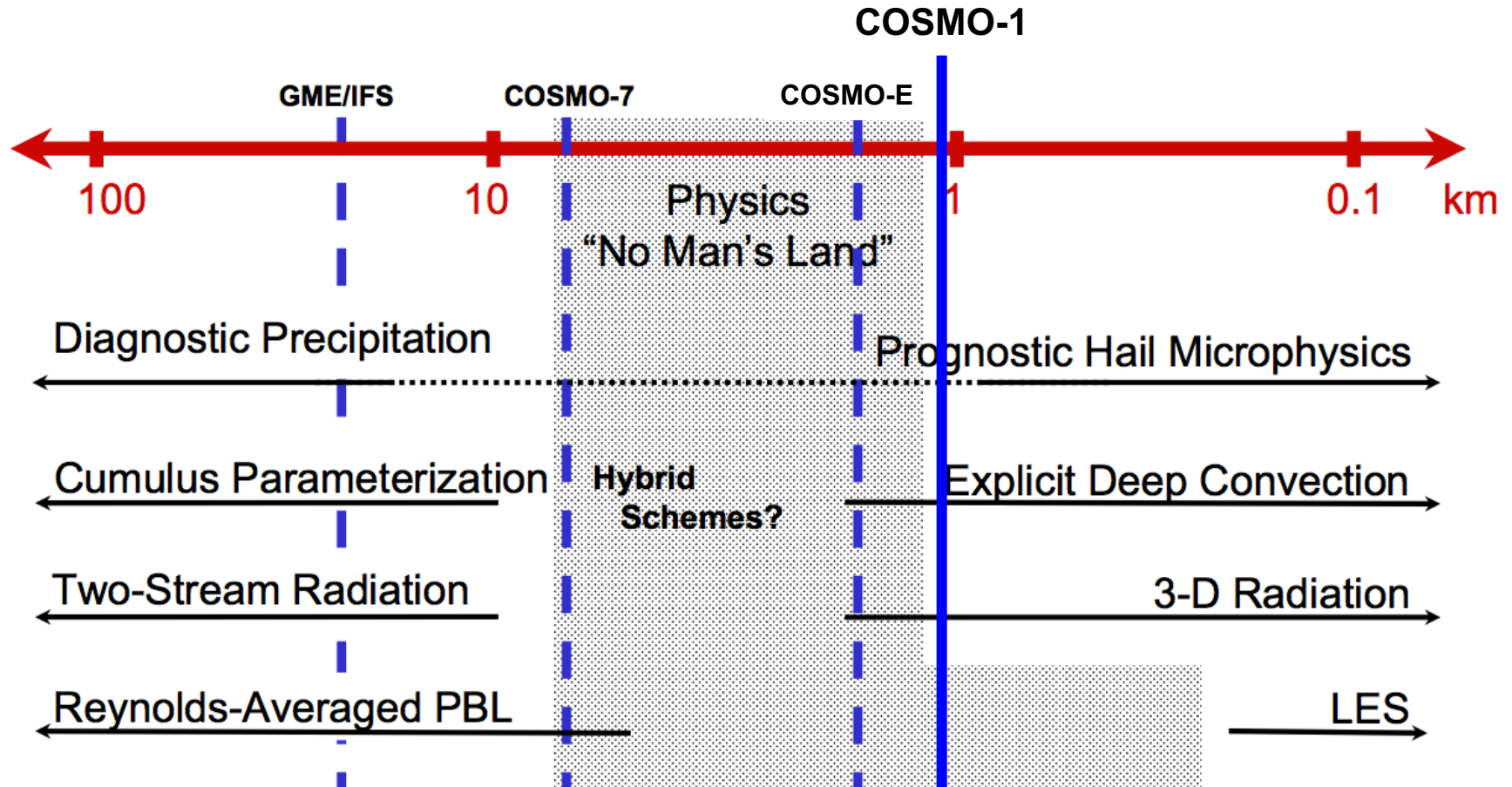
Ensemble data assimilation: LETKF (40 members)





Greyzone

(adapted from Klemp 2007)



COSMO-1 can steer clear of a large part of the "grey zone" by jumping ahead to $\Delta x = 1.1$ km



The challenge of NWP in Switzerland



Flat-terrain cloudy BL



Cloudy BL over the Alps (Eggishorn)

Two key issues for COSMO-1 and -E:

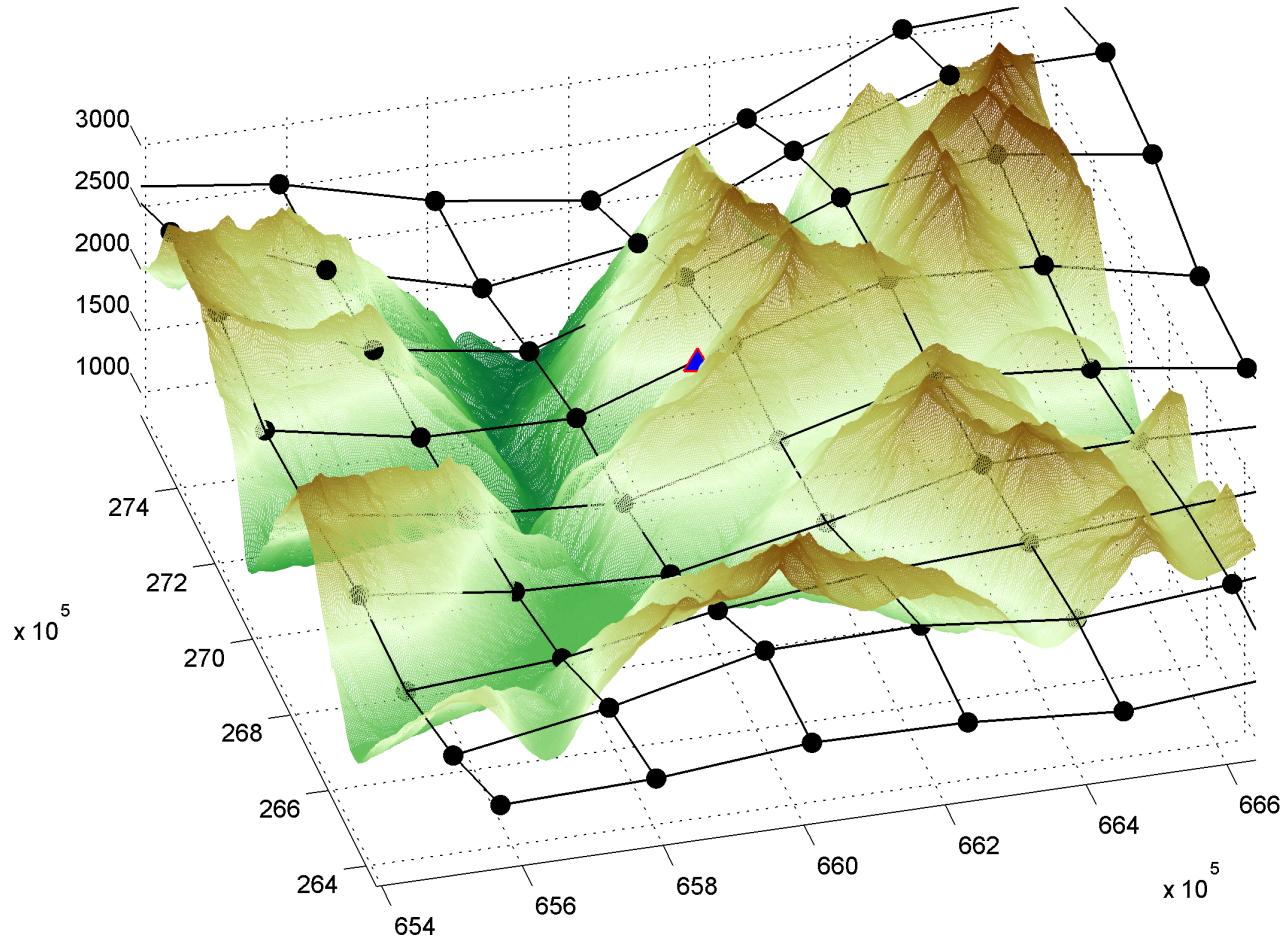
→ ABLs over complex terrain

→ Turbulence and shallow convection in greyzone



Complex topography

Model vs. real topography at $\Delta x = 2.2$ km (COSMO-E) at Guetsch (Andermatt)

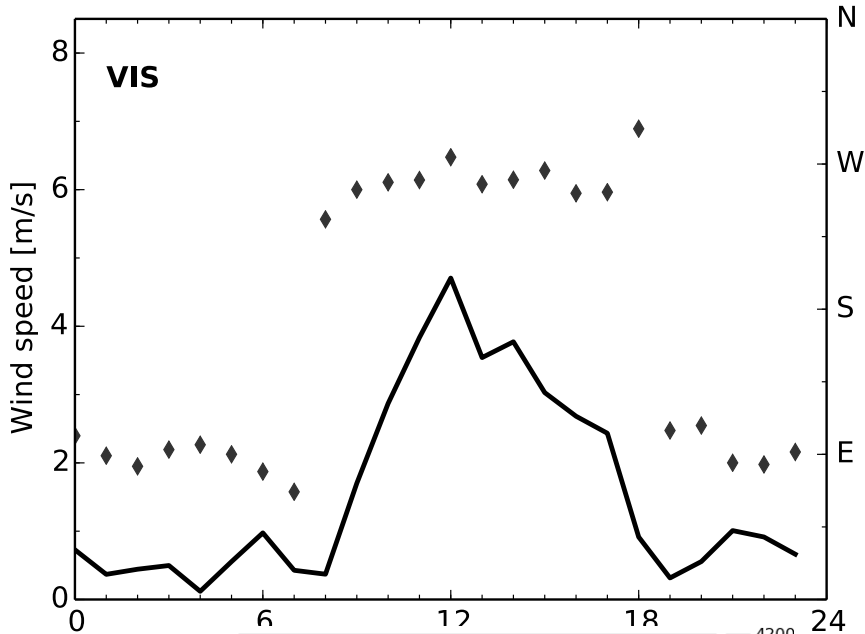




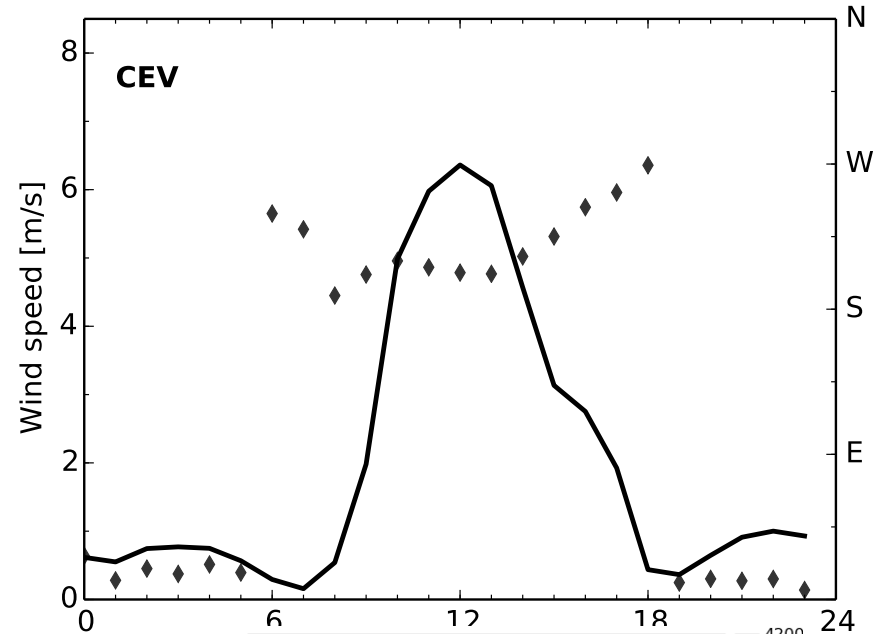
Mean diurnal cycle of valley winds

OBS

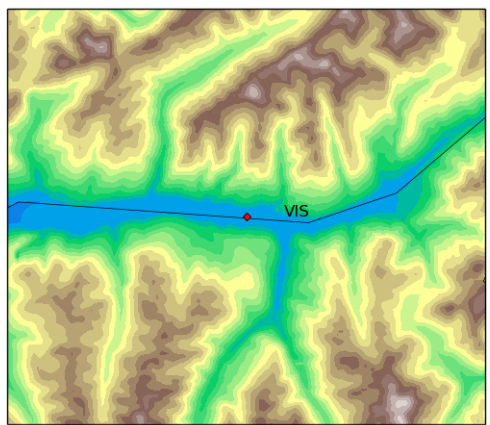
Visp (Rhone valley)



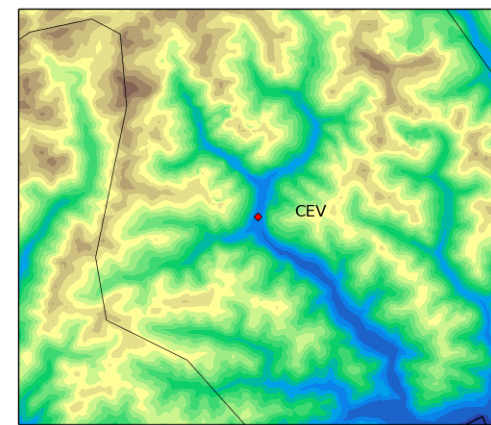
Cevio (Maggia valley)



average



27 July)



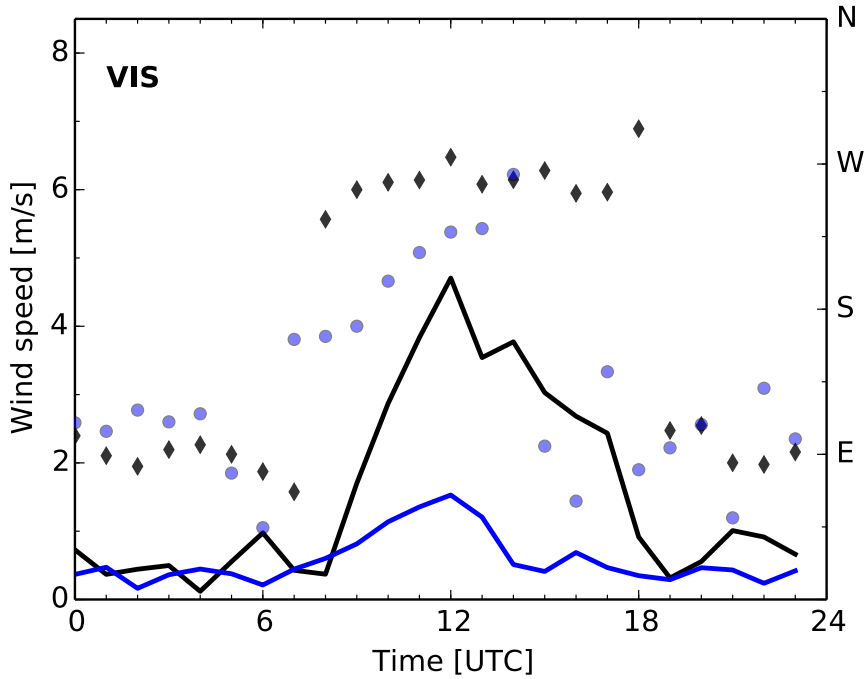
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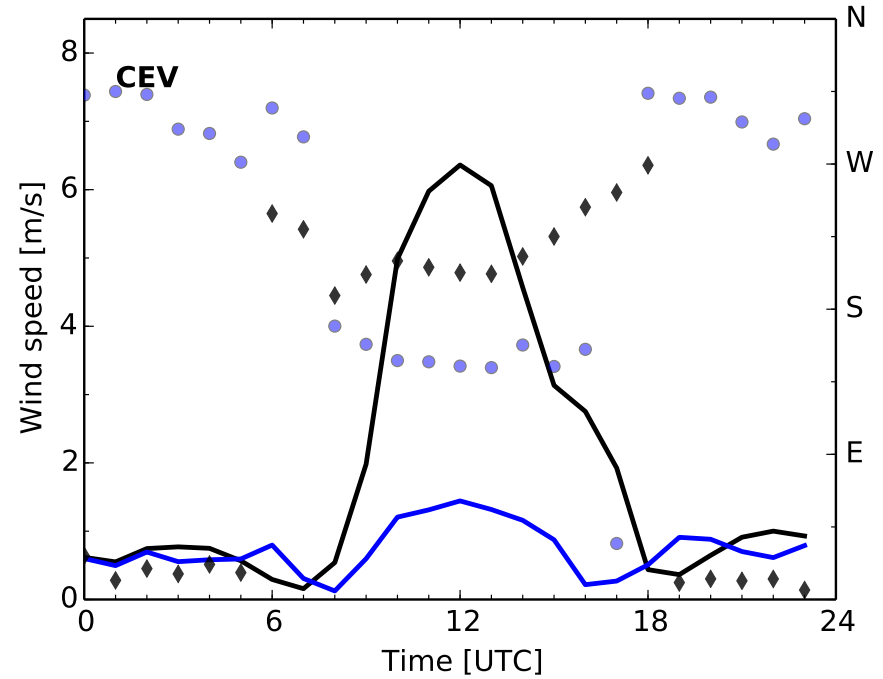
Mean diurnal cycle of valley winds

OBS 2 km

Visp (Rhone valley)



Cevio (Maggia valley)

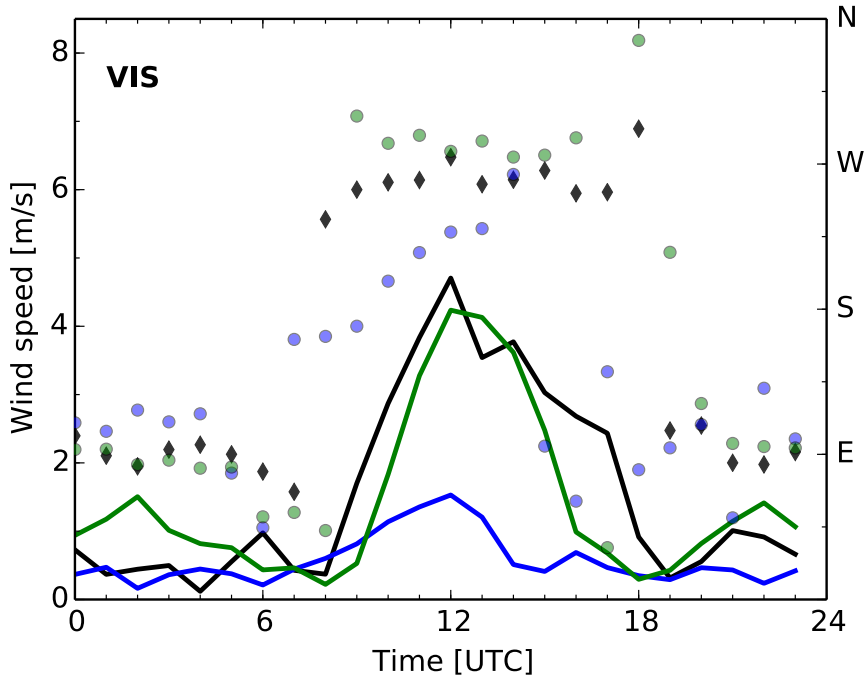




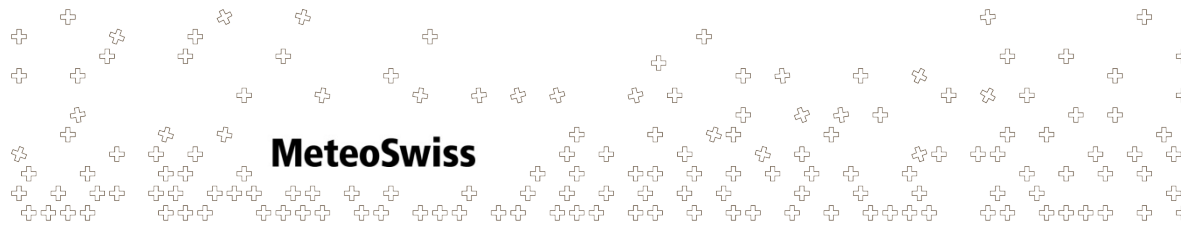
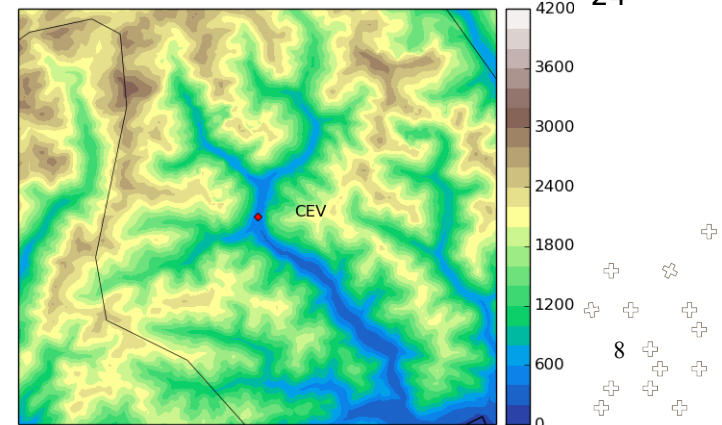
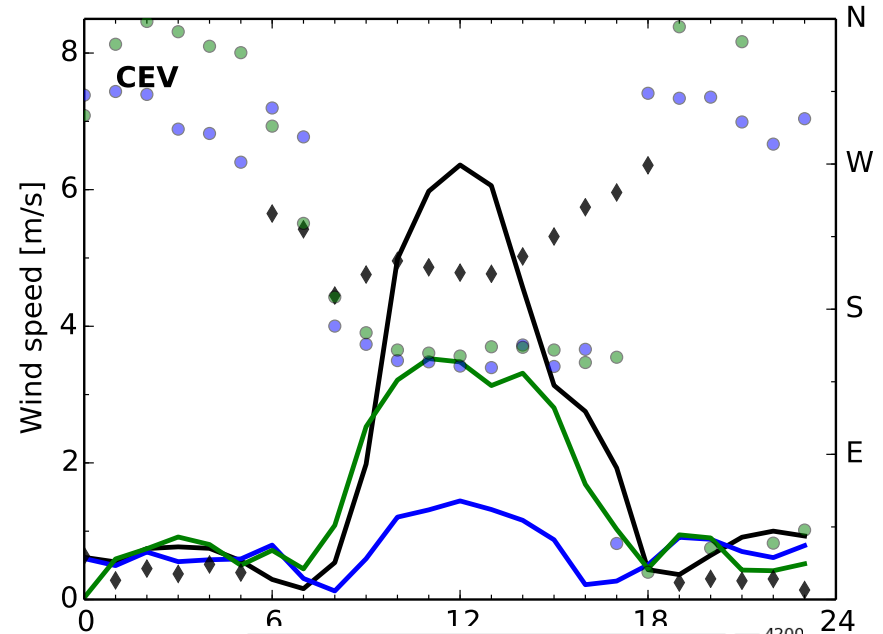
Mean diurnal cycle of valley winds

OBS 2 km 1 km

Visp (Rhone valley)



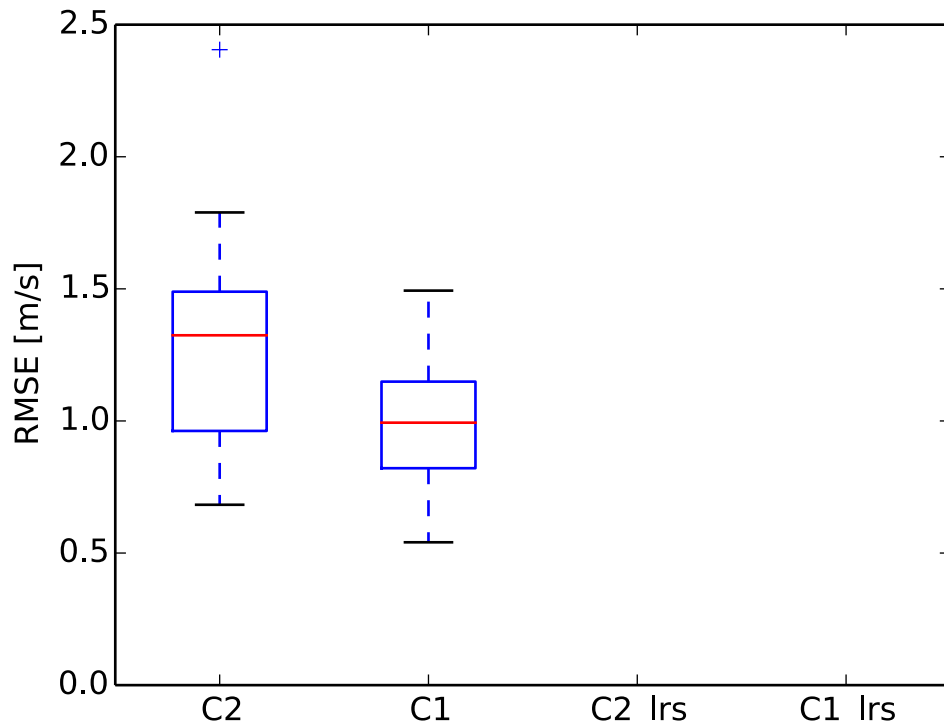
Cevio (Maggia valley)





Influence of surface data

“Diurnal wind” stations (21)



High-resolution surface data

- ASTER topography (30 m)
- GC2009 land cover (300 m)
- HWSD soil type (1 km)
- Raymond filter for topography (def: cutoff ~5 dx)

Low-resolution surface data (lrs)

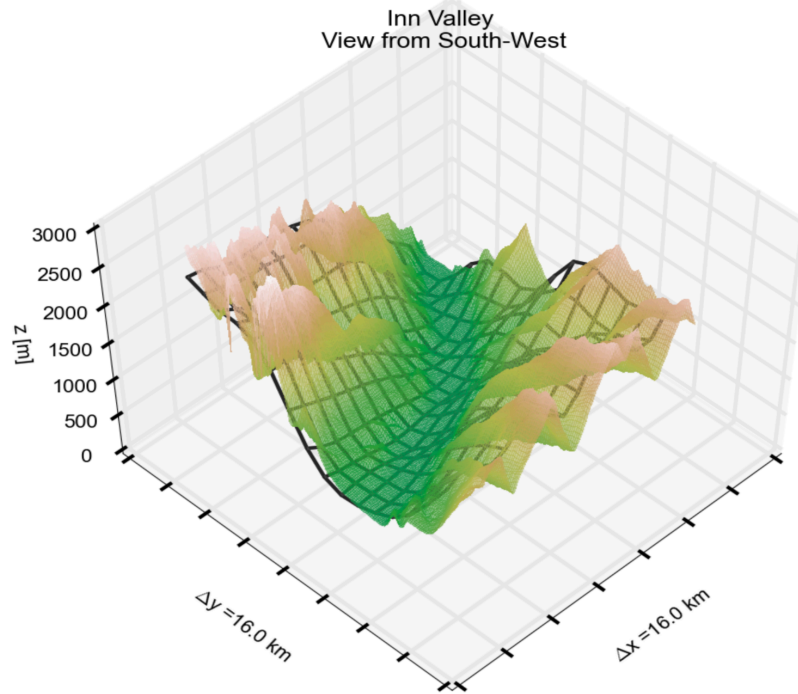
- GLOBE topography (1 km)
- GLC2000 land cover (1 km)
- FAO DSMW (10 km)
- Raymond filter for topography (def: cutoff ~5 dx)

→ Coarse surface data: Only minor improvement for 1km!

→ Need high-resolution surface data for 1km simulation!



TKE budget in the Inn valley (i-Box)



Kohlsass station (545 masl)

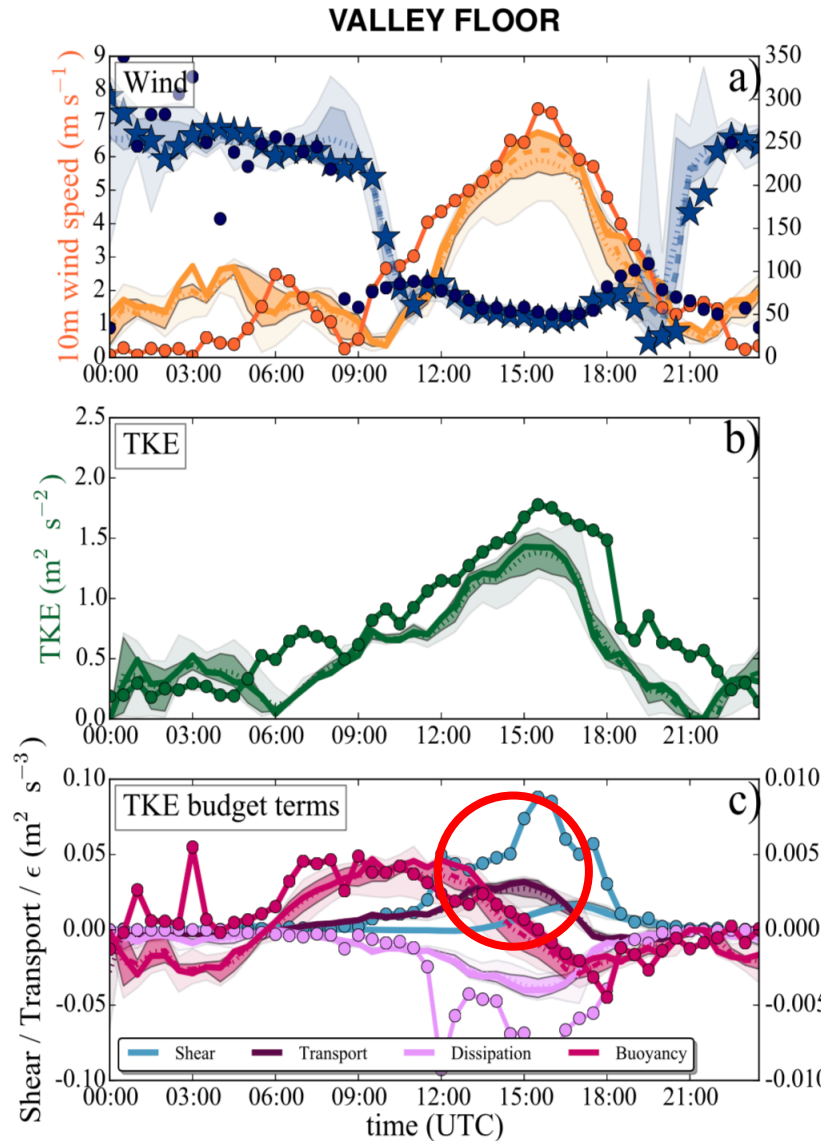


- Compare COSMO-1 against measurements (turbulent fluxes, TKE, TKE production terms)



1D Scheme

(1.5 order TKE closure)

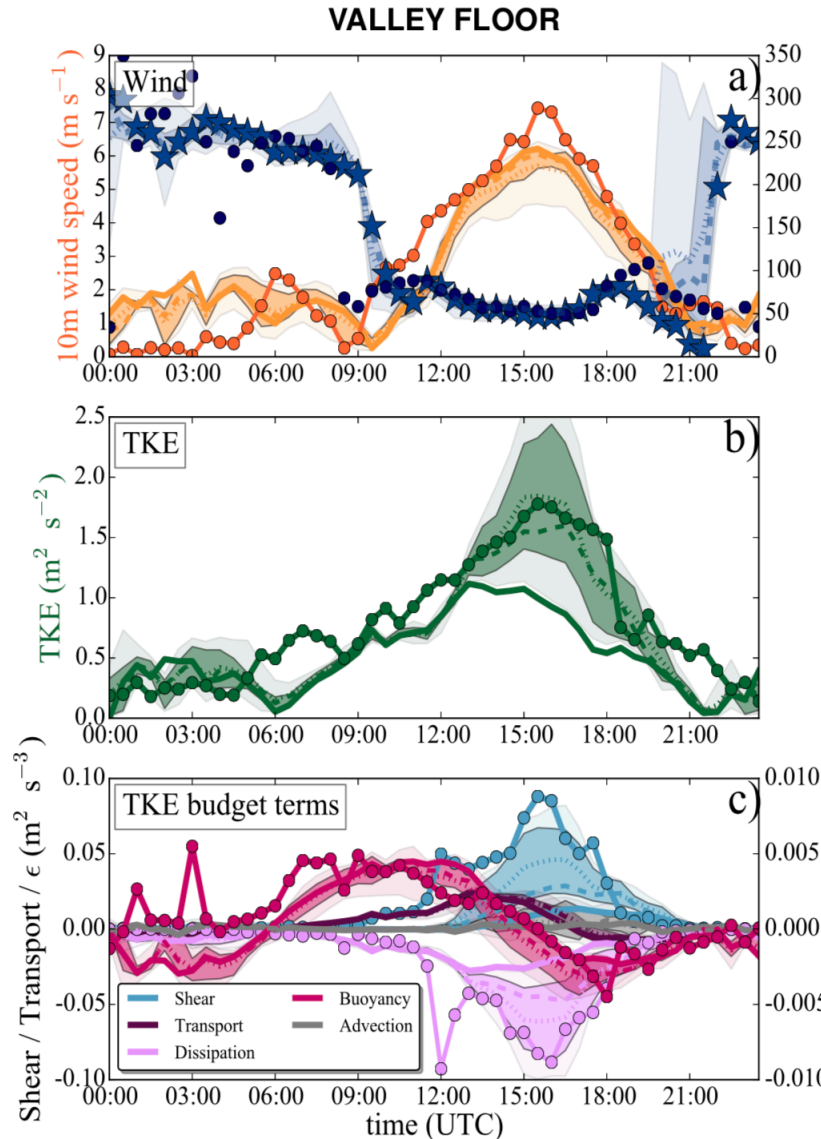


- **Morning**
 - Buoyant production dominates
 - TKE well simulated by model
- **Afternoon**
 - Vertical shear generation by valley wind
 - **Shear term drastically underestimated** (missing horizontal contributions)



Hybrid Scheme

(+ TKE advection + horizontal shear contribution after Smagorinsky & Lilly)



- Significant improvement in afternoon shear production

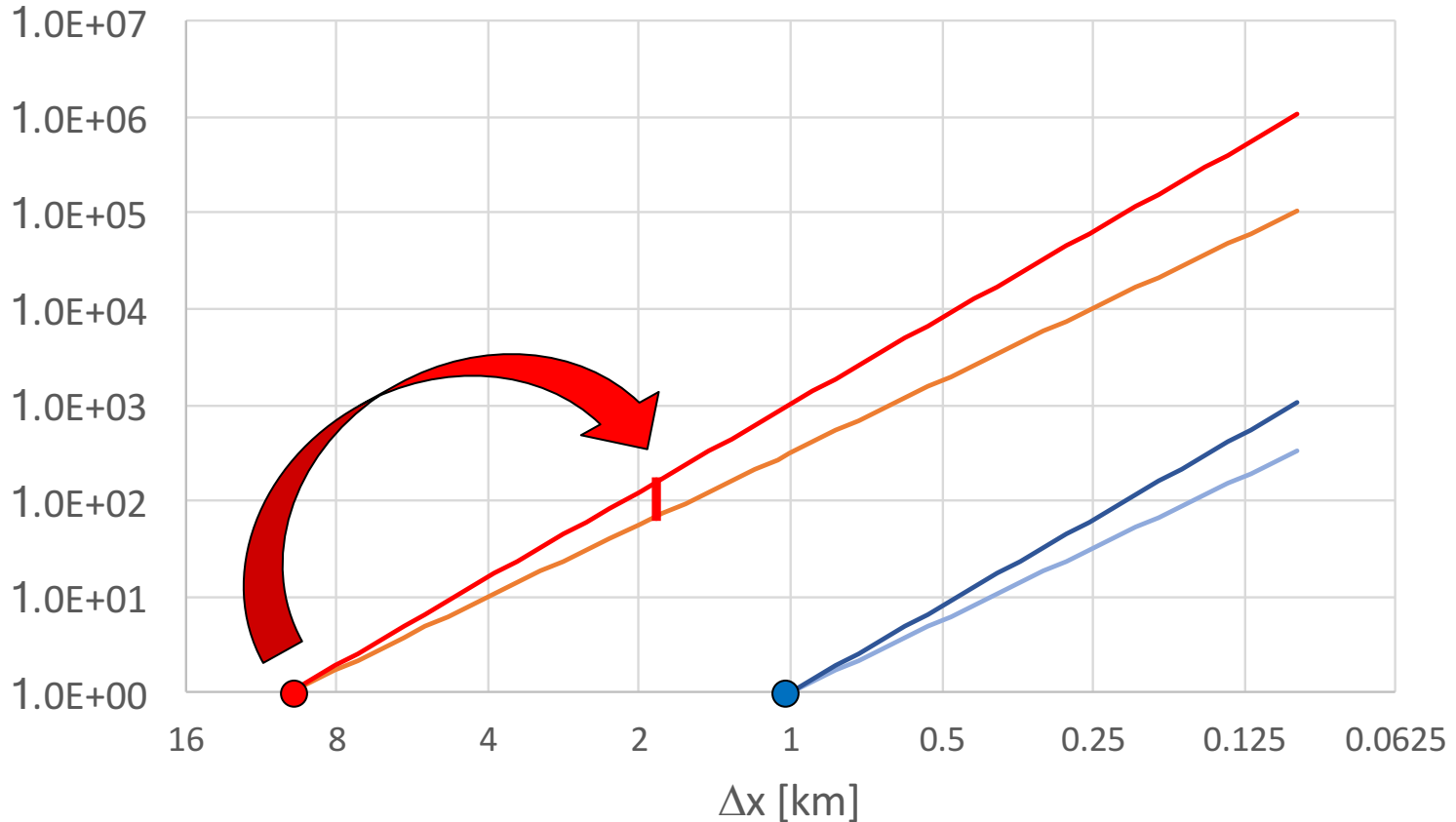
Many shades to grey...





Jump across greyzone?

Computational effort vs. 10 km / 1 km baseline



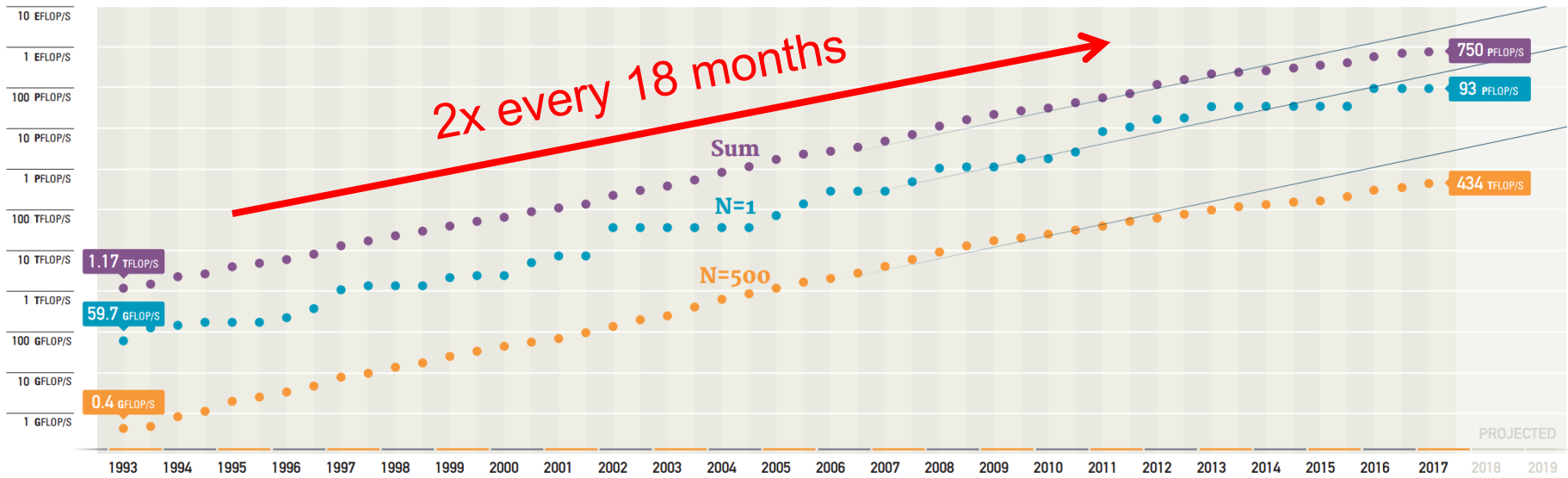
Computational effort grows by a factor ~100



How to achieve a factor 100?

- Option 1: Money
- Option 2: Wait 10 years (Moore's law)

PERFORMANCE DEVELOPMENT

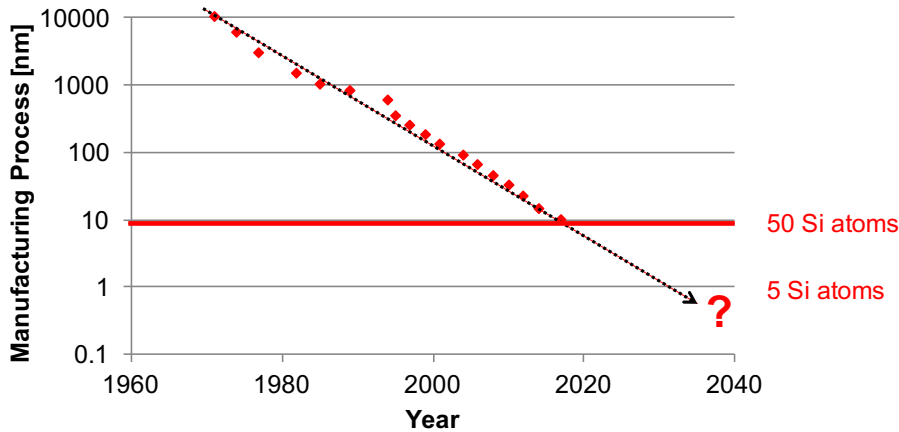


Source: top500.org

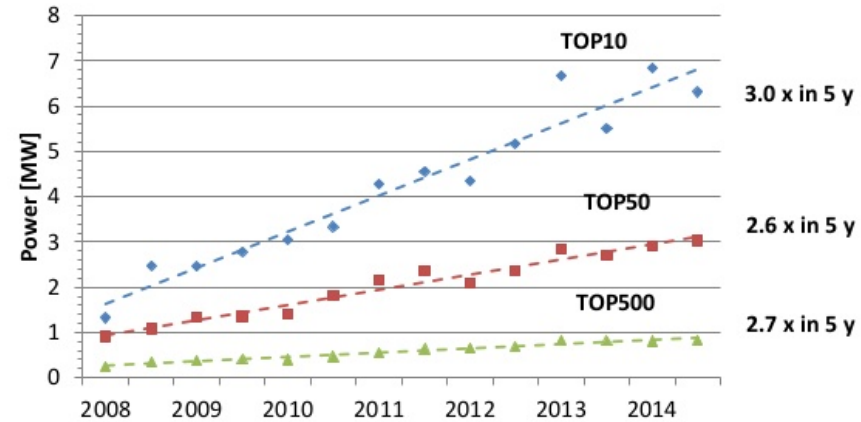


Moore's law is sick (or dead)

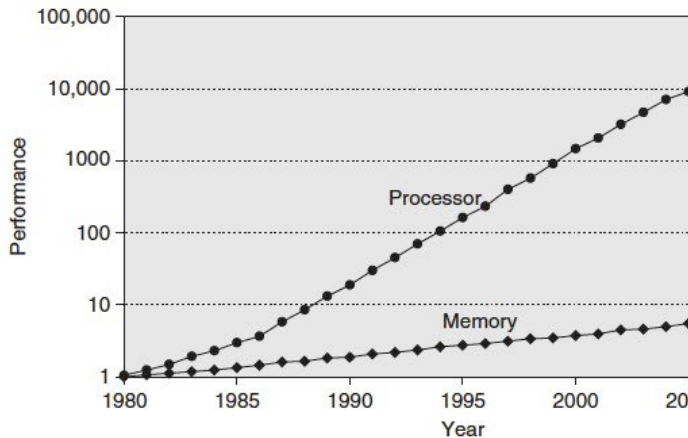
Decreasing feature size



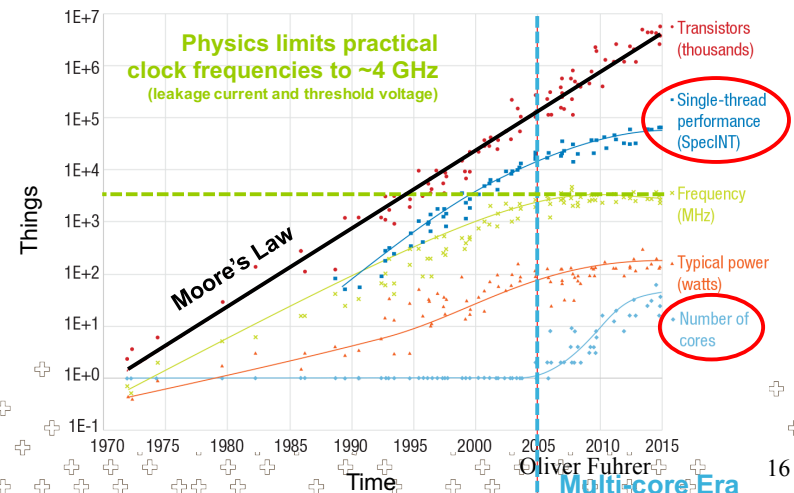
Increasing power consumption



Slower pace for bandwidth



Stagnating clock frequencies

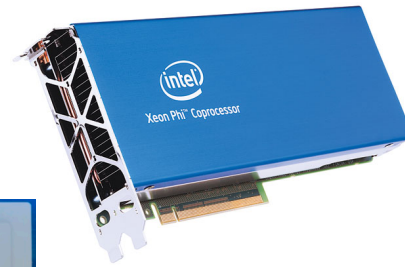
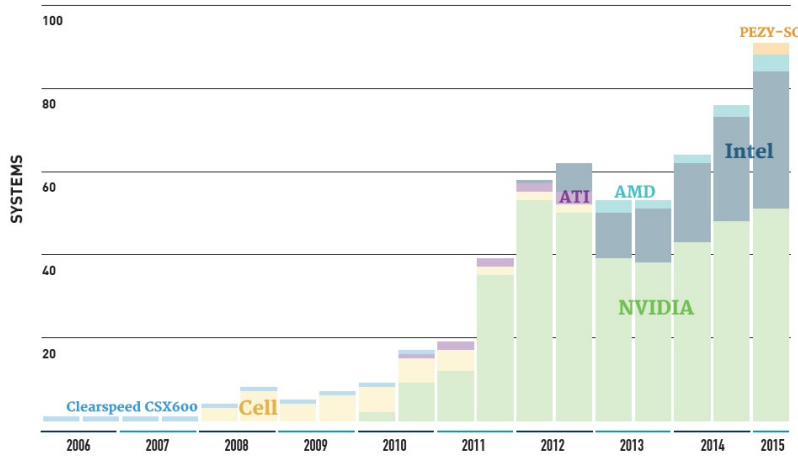




Specialization

20% Systems on Top 500

ACCELERATORS/CO-PROCESSORS



Many-core processors

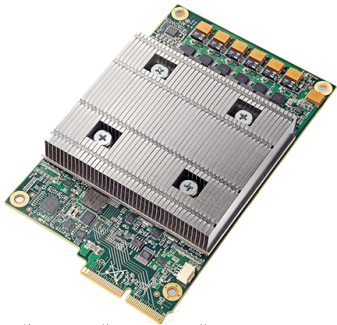


GPUs



AI Accelerators

(e.g. Google Tensor Flow, Intel Nervana)



Koenig et al. 2017, UCB
(accelerator for exact dot product)

ARM

(e.g. Mont Blanc)





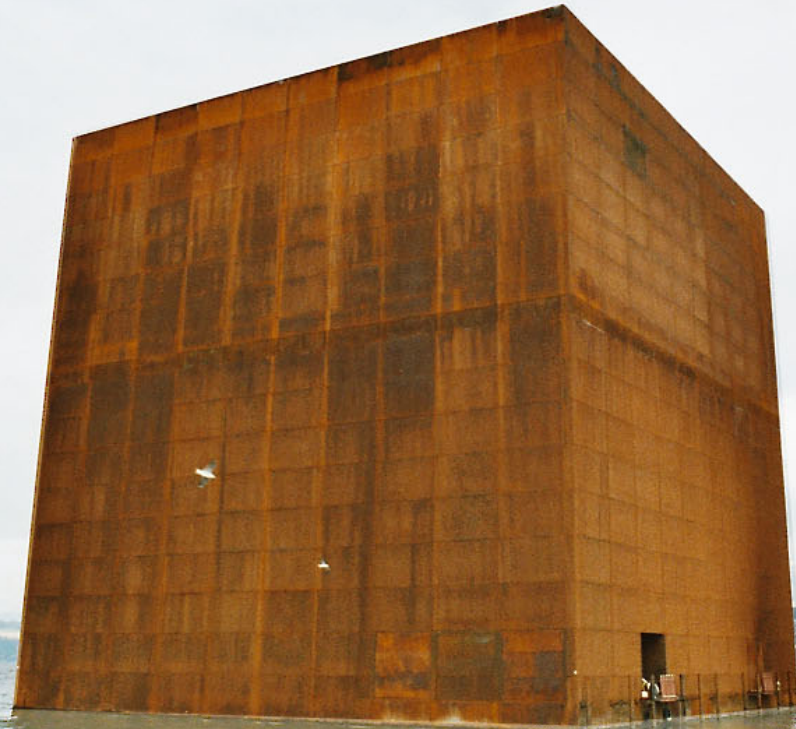
Challenges

- **New design constraints**
 - Maximize parallelism
 - Minimize data movement and energy consumption
 - Minimize synchronizations
- **New programming models**
 - E.g. OpenMP 4.5, Coarray Fortran, CUDA, OpenACC
- **Rapid change**
 - Timescale of HPC system vs. Model



What to do?

300'000 lines of Fortran + MPI code



Libraries / System software



Up or down?



- **Increase level of abstraction**

- Remove details of implementation
- Can be “disruptive”

- **Lower level of abstraction**

- Add implementation details
- Often „incremental“



DOWN – Decrease level of abstraction



- **Approaches**

- Fortran + MPI + Directives (OpenMP, OpenACC)
- Optimize code for a specific hardware
- Custom implementations (#ifdef) or programming languages



Original Version

```
! solve tridiag(a,b,c) * x = d
! pre-computation
...
do j = jstart, jend

! forward elimination
do k = nk, 2, -1
  do i = istart, iend
!CDIR ON ADB(d)
    d(i,j,k) = ( d(i,j,k) - d(i,j,k+1) * c(i,j,k) ) * b(i,j,k)
  end do
end do

! back substitution
do k = 1, nk-1
  do i = istart, iend
!CDIR ON ADB(x)
    x(i,j,k+1) = a(i,j,k+1) * x(i,j,k) + d(i,j,k+1)
  end do
end do

end do
```

- Algorithm: TDMA
- Language: Fortran
- Grid: Structured
Data layout: (i,j,k)
- Parallelization: MPI in (i,j)
- Loop order: (jki)
- Blocking: (j)
- Vectorization: (i)
- Directives: NEC
- ...



Optimized GPU Version

```
! solve tridiag(a,b,c) * x = d
!$ACC DATA COPYIN(a,b,c,d) COPYOUT(x)
!$ACC KERNELS LOOP, GANG(32), WORKER(8)
do i = istart, iend
do j = jstart, jend

! pre-computation
...

! forward elimination
do k = nk, 2, -1
  d(i,j,k) = ( d(i,j,k) - d(i,j,k+1) * c(i,j,
end do

! back substitution
do k = 1, nk-1
  x(i,j,k+1) = a(i,j,k+1) * x(i,j,k) + d(i,j,k+1)
end do

end do
end do
!$OMP END KERNELS LOOPS

!$ACC END DATA
```

- Algorithm: TDMA
- Language: Fortran
- Grid: Structured
- Data layout: (i,j,k)
- Parallelization: Nodes (i,j) and Blocks (i,j)
- Loop order: (ijjk)
- No Blocking
- Vectorization: SIMD Threads (i,j)
- Directives: OpenACC
- ...



DOWN – Discussion



- Easy to learn
- Incremental



- Harder to understand / adapt
 - Increased maintenance effort
 - Performance compromise
-
- **Is it possible to reach a good compromise?**
 - Near optimal performance
 - Multiple hardware architectures
 - Maintainable code



UP – Increase level of abstraction



- **Approaches**

- Compilers
- Libraries / Frameworks
- Code generators and source-to-source translators
- Domain-specific languages (DSL)



Domain-specific language (DSL)

```

function avg {
  offset off
  storage in

  avg = 0.5 * ( in(off) + in() )
}

function coriolis_force {
  storage fc, in

  coriolis_force = fc() * in()
}

operator coriolis {
  storage u_tend, u, v_tend, v, fc

  vertical_region ( k_start , k_end ) {
    u_tend += avg(j-1, coriolis_force(fc, avg(i+1, v)))
    v_tend -= avg(i-1, coriolis_force(fc, avg(j+1, u)))
  }
}

```

Example: gtclang

- Coriolis force

$$\frac{\partial u}{\partial t} = \dots + fv$$

$$\frac{\partial v}{\partial t} = \dots - fu$$

- No loops
- No data structures
- No halo-updates



UP – Discussion



- User code easy to understand / modify
- Performance portability
- High performance
- Safety / correctness can be imposed



- No turn key solutions available
- Disruptive change
- Maintenance of DSL / compiler

- **Can be achieve a community solution?**



Both approaches for COSMO

Fuhrer et al., 2014, doi:[10.14529/jsfi1401](https://doi.org/10.14529/jsfi1401)

Lapillonne and Fuhrer, 2014, doi: [10.1142/S0129626414500030](https://doi.org/10.1142/S0129626414500030)

Dynamical core → Rewrite
(C++)



Rest → Refactor
(Fortran + OpenACC)

User code
(algorithms)

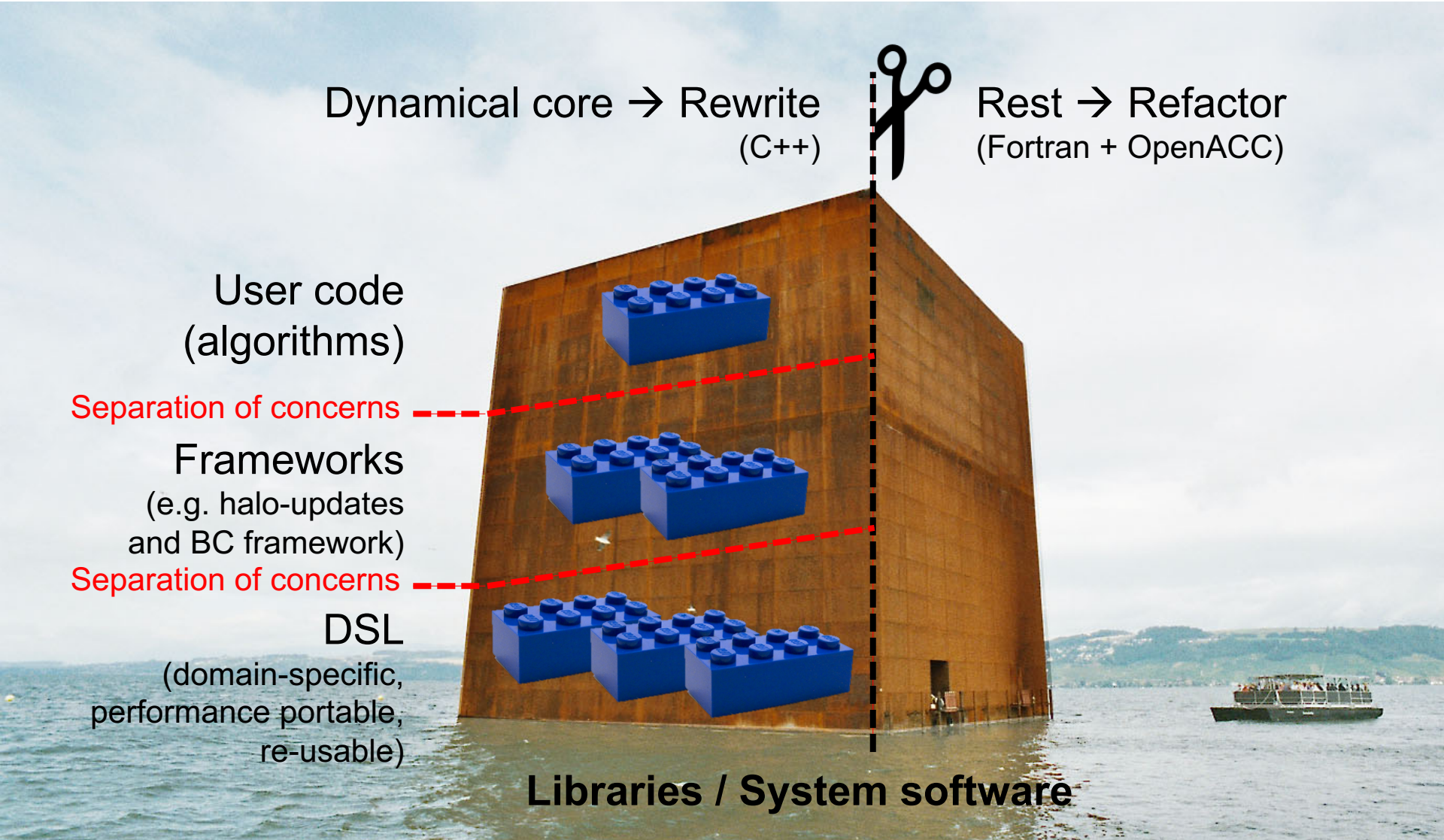
Separation of concerns

Frameworks
(e.g. halo-updates
and BC framework)

Separation of concerns

DSL
(domain-specific,
performance portable,
re-usable)

Libraries / System software





Operational system in 2016



Piz Kesch (Cray CS Storm)

- GPU-accelerated hybrid system
- “Fat” compute nodes with
 - 2 x Intel Haswell E5-2690v3
 - 8 x NVIDIA Tesla K80
- 12 nodes per rack
- Including service nodes, post-processing nodes, file system, ...
- 2 redundant racks

Increase in computational problem size of 40x in 4-5 years with constant budget and running costs.



Learnings (so far)

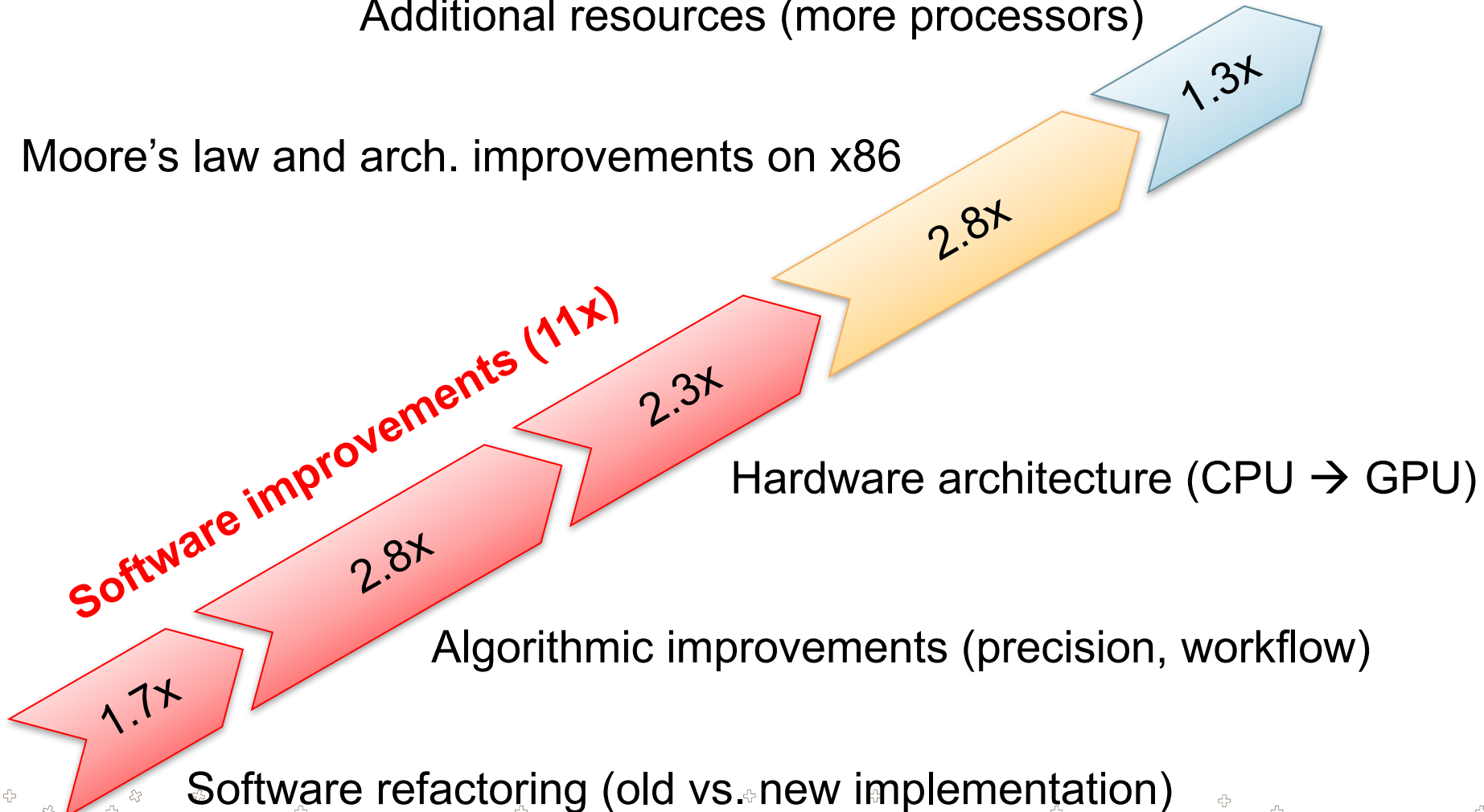
- **Co-design approach:** Team of computer scientists, computational scientists, domain scientists, system architects and vendors
- Trading off options and **taking compromises** is important
 - e.g. cannot re-write everything in one go
 - e.g. data-assimilation is not a good match for GPUs
- Consider **full workflow** (including I/O, pre-/post-processing, ...)
- Aim for **sustainable solutions**
 - Consider development and maintenance effort



How was factor 40x achieved?

Additional resources (more processors)

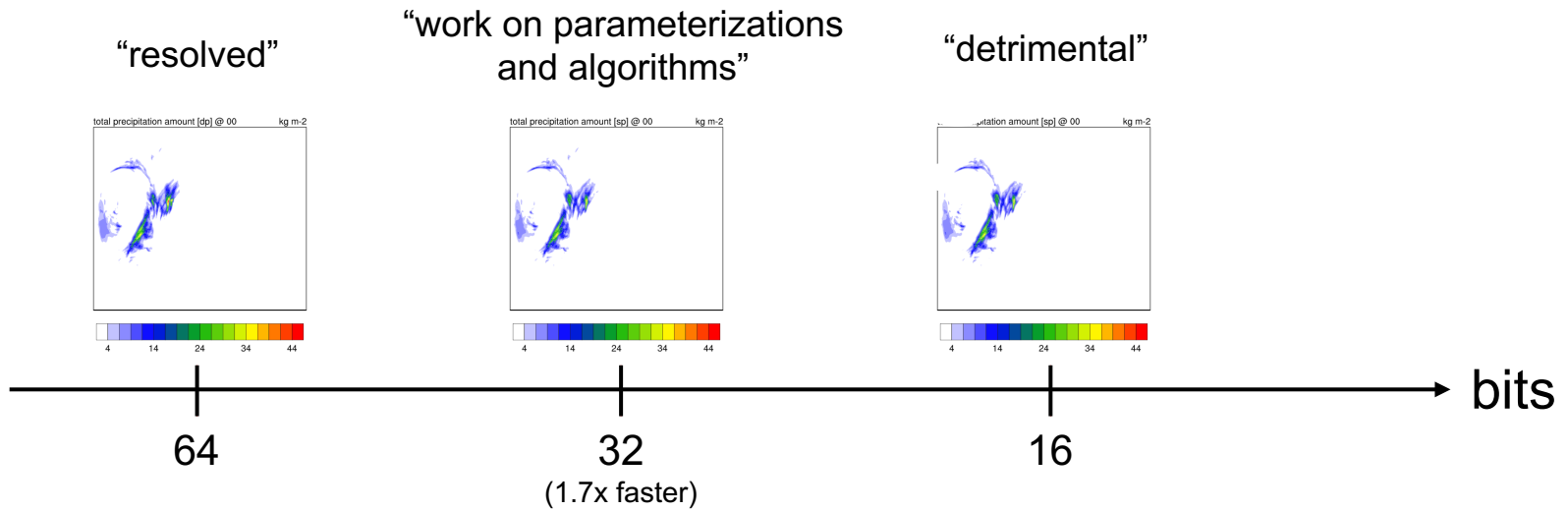
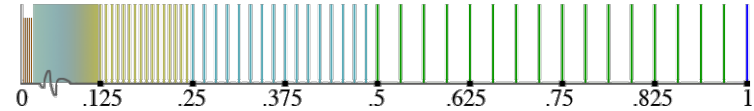
Moore's law and arch. improvements on x86





Greyzone of precision

- Discretization of number space
- Higher precision → more data movement / energy

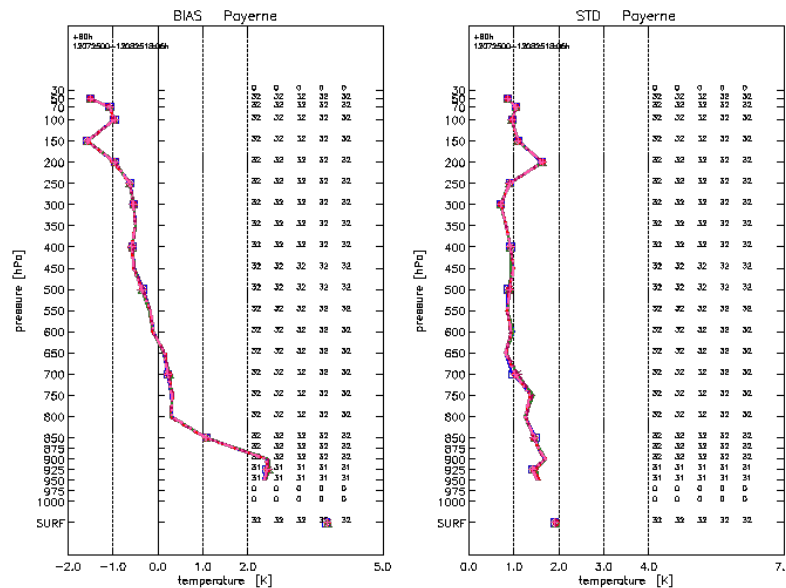


- Tradeoff: algorithm, precision, resolution, ensemble size



COSMO in single precision

- Results not distinguishable between single / double precision (e.g. upper air verification)



- Ensemble runs are in single precision (60% more members)
- ✖ Issues with data assimilation code



Summary

- Key issues for O(1-2 km) modeling over complex terrain
 - ABLs over complex terrain
 - Turbulence and shallow convection in greyzone
- Exponentially increasing compute power is no longer a given
 - Specialization of hardware
 - New programming models
- Urgent need to also address HPC issues in order not to get stuck in greyzone!



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